

OPERATION MANUAL

RESISTOMAT® Type 2304

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Installation

Operation

Parameterization

Configuration

Note:

written approval.

Exclusion of warranty liability for operating manuals

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Calibration

Programming

Techn. Specifications & Appendix

burster **RESISTOMAT®**

Type 2304

	Präzisionsmessger für elektrische, the	äte, Sensoren und Messs rmische und mechanische (ysteme Größen	Installatic
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Name des Herstellers: Manufacturer's Name:	burster präzisionsmesstechnik	gmbh & co kg		peratio
Adresse des Herstellers: Manufacturer's Address:	Talstr. 1-5 76593 Gernsbach, Germany			0
erklärt unter alleiniger Ver declares under sole responsibili	rantwortung, dass das gelieferto	e Produkt ivered		
Produktname: <i>Product Name:</i>	Hochpräziser Meß- und Prüfan High-Precision Automatic Inspec	utomat für die elektrische W tion and Test Unit for Electrica	iderstandsmeßtechnik al Resistance Testing	rizatio
Modellnummer(n) (Typ): <i>Models Number / Type:</i>	2304 / 2305			amete
Produktoptionen: Options	Diese Erklärung beinhaltet obe This declaration covers all option	engenannte Produkte mit alle as of the above product(s)	en Optionen	Par
mit den folgenden europäis complies with the requirements	schen Richtlinien übereinstimm of the following applicable Europea	t und entsprechend das Cl in Directives, and carries the C	E -Zeichen trägt: E marking accordingly:	
2006/95/EC El Low Voltage El	ektrische Betriebsmittel zur Verw ectrical Equipment designed for use	wendung innerhalb bestimmt within certain voltage limits	ter Spannungsgrenzen	uratio
2004/108/EC El EMC El	ektromagnetische Verträglichkei ectromagnetic Compatibility	t		Config
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Sicherheit: IE Safety requirements:	C 61010-1:2001 / EN 61010-1:2001	Messkategorie 1 CAT 1	Schutzklasse 1; (110)/ 230 V~ Kat. II	uo
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Table of contents

Installation and maintenance	Chapter 1
Operation	Chapter 2
Parameterization	Chapter 3
Configuration	Chapter 4
Calibration.	Chapter 5
Programming the SCPI operating interface	Chapter 6
Technical specifications and appendix	Chapter 7

burster RESISTOMAT®

Туре 2304

Installation

Chapter 1

Installation and maintenance of the RESISTOMAT®2	2304 1-1
Input control	1-2
Optional features and accesories	1-3
Installation	1-4
Maintenance	1-5
Mode of operation	1-5

Chapter 2

Introduction	2-1
Activation	2-2
Display	2-3
Controls	2-4
Inductive test-units	2-5

Chapter 3

Parameterization (main menu 1)	3-1
Evaluation (main menu 2)	3-2
Special functions (main menu 3)	3-3

Chapter 4

4-1
4-2
4-3
4-4
4-5
4-5
4-7
4-8

Techn. Specifications & Appendix



Installation

Chapter 5

General information	5-1
Zero point calibration	5-2
Scaling factor calibration	5-3
Reference values	5-4
Pt100 calibration	5-5
Pt100 coefficients	5-5

Chapter 6

External interfaces of the RESISTOMAT ® 2304	. 6-1
The RESISTOMAT [®] 2304 command language	. 6-2
The RESISTOMAT [®] 2304 command list	. 6-3
HP-IB command list	. 6-4
Sample program for controlling the RESISTOMAT ® 2304	
via the RS 232 interface	. 6-5

Chapter 7

Technical specifications	7-1
Pin assignment	7-2
Error messages	7-3
Basic factory settings ("default parameters")	7-4
Printer character se	7-5
Function key overview	7-6

·

Type 2304

Table of contents, chapters 1 - 1 to 1- 6 Installation and maintenance of the RESISTOMAT®2304	peration Installation
General information1-1-2	
Inputcontrol 1-2-2	ation
Options and accessories 1-3-1	steriz
Installation 1-4-1	arame
Grounding	uration
IEEE488 bus	Config
Device address for Remonte control	ation
Maintenance 1-5-1	alibra
General information1-5-1 Customer service1-5-1	
Serial number	gramming
Operation 1-6-1	P 2

Techn. Specifications & Appendix Programming Calibration

Page 1 - 1 - 1

Installation

Operation

Parameterization

Installation and maintenance of the **RESISTOMAT®2304**

General information

Position the RESISTOMAT[®] resistance measuring device so that enough space is left behind the back panel to ensure proper ventilation of the black heat sink. The output of the ventilation channel shown in Fig. 1.2 must not be obstructed. Enough space should also be allowed for the connection of interface cables.

Input control

The device weighs 28 kg and is contained in appropriately shock-resistant packaging. Unpack it carefully and check whether any contents are missing. The standard scope of delivery includes:

- a type 2304 resistance measuring device,
- a mains cable.
- a copy of this handbook.

Check the device carefully for damage. Should there be signs of damage which has occurred during transport, inform the shipping company within 72 hours. The packaging a comparable Page 1 - 1/2 - 2 should be kept so that it can be examined by the manufacturer's representative or the shipping company.

The RESISTOMAT may only be transported in its original packaging or a comparable packaging.

Configuration Calibration

Programming

v

burster RESISTOMAT®

Installation

Operation

Parameterization

Configuration

Calibration

Programming

Techn. Specifications & Appendix

Optional features and accessories

The following optional features and accessories are available for the 2304 RESISTOMAT®:

- Version for 115VAC + 6% 10% power line voltage.
- Type 2304-Z004 calibration resistance package:
 5 type 1240 calibration resistances with values of 100μΩ, 1 mΩ,
 10 mΩ, 100 mΩ and 1 Ω. Every resistance has a DKD (german calibration service) label. In addition, every package contains a type 2394 adapter for direct connection of the calibration resistances to the measurement sockets of the RESISTOMAT[®] (see Chap. 2.4.5).
- Temperature measuring sensor (Pt100) including LEMO 1B type 2304-V001 plug connector:
 For measuring the temperature of the test unit in the case of automatic temperature compensation (see Chap. 3.2.2), cable length: 2.5 m.
- 37-pin type 2304-Z001 mating connector for the digital inputs/outputs (see Chap. 1.4.4.3 and 7.2.3.)
- 25-pin type 2304-Z002 mating connector for the RS232/485 output (see Chapters 1.4.4.2 and 7.2.2.)
- 5-pin type 2304-Z003 mating connector for rear-panel connection of the test unit (see Chap. 7.2.4)
- Kelvin measuring tongs and Kelvin test prods see specification sheet KM 2.3.
- Clamping device, see specification sheets EV 2.3 und PE 2.3.
- 19" type 2304-Z004 assembly kit.

·



Installation

Operation



Fig. 1.1.: Ground conductor connection

Normally, this INTERNAL ground is used. It is advisable to use a seperate, EXTERNAL ground only for networks which are particularly prone to interference. This also applies to measurements on objects with single-end grounding, like motors. In order to avoid ground loops here, the reference potential of the measuring circuit should be connected directly with the neutral point of the test unit. (see Chap. 4.7 for changeover from INTERNAL to EXTERNAL grounding).

Programming Calibration Configuration Parameterization

Techn. Specifications & Appendix

Installation

Operation

Parameterization



Installation

Power supply

The standard RESISTOMAT® is designed to operate at a mains voltage of 230_{VAC} + 6% - 10% and a mains frequency of 45 - 65 Hz. 115_{vac} is available as an option (conversion is only carried out by the manufacturer; it is not sufficient to simply switch the voltage selector shown in Fig. 1.2).

For this reason, it must be checked whether the voltages specified on the type and voltage plates correspond with the local mains voltage, before the mains voltage is connected (Fig. 1.2) and turned on (Chap. 2.2).

The adaption of the device's internal time base (for synchronizing the A/D converter and other functional units) to mains frequencies other than 50 Hz is described in Chap. 4.3).



Page 1 - 4 - 2



Installation

Operation

Parameterization

guration

Installation

Line Power fuse

The two line power fuses each rated at 2 A (both with medium time-lag) are located behind the panel with the voltage information, inside the mains connection module (see Fig. 1.2). The fuses are changed by inserting a screwdriver into the notch underneath the upper edge of the mains socket, lifting the plate with the voltage information slightly, and pulling out the fuse-insert.

ATTENTION:

After a fuse has been changed, the fuse-insert must be pushed into the mains module in the correct manner (mark on housing facing arrow with the desired mains voltage).

Connection of the inputs and outputs

IEEE488	The GPIB cable is connected to the 24-pin socket (IEEE-488 standard) on the rear panel of the device (see Fig. 1.2 and Chap. 7.2.1).	Confi
RS232/485	The RS232/485 interface cable is connected to the 25-pin subminiature D-socket on the rear panel of the device (see Fig. 1.2 and Chap. 7.2.2).	ation
Digital	The following inputs/outputs are accessible via the 37-pin subminiature D-socket on the rear panel of the device (see Fig. 1.2 and Chap. 7.2.2): 9 relays each with a changeover switch for the comparator or classify functions (see Chapters 3.2.4 and 3.2.5)	Calibra
inputs/ outputs	 1 START/STOP1 input for connecting a foot switch (Pin 1 to DGND/Pin 20), 1 START/STOP2 input via optocoupler (Pin 23 to GNDEXT/Pin 5), 1 status output, Measurement error" (optocoupler, "open collector", "active low"), 1 status output, Measurement in progress" (optocoupler) 	Programming
	 a status output "measurement in progress (optocoupler, "open collector", "active low"), 1 printer enable input (optocoupler, "open collector", "active low"). 	specifica- Appendix

fechn.

ions &

Installation

Operation

Parameterization

Configuration

Calibration

Programming

Fechn. Specificaions & Appendix



Device address for computer control The device address can be selected via a keyboard or an external interface. The following chapters contain the relevant information: IEC bus control: Chap. 6.1.2.1), RS232/485: Chap. 6.1.3), Chap. 3.3.4). Interfaces: The address selected last is stored after the mains voltage is turned off; the factory presettings (see Chap. 7.4) are "9" (IEC bus) and "0" (group and device address in the case of RS 232/485). 19"type 2304-Z004 assembly set Removing the upper and lower casings: Loosen the fastening screws (4 each at the top and bottom), take off the casings, remove the 8 clamping nuts which have been released. Removing the front panel: Loosen the shaft screws (one each on the vertical side), lift the front panel out of the notch by bending the horizontal sides. Removing the lateral grips: Loosen the fastening screws (3 on each side), take off the grips and lateral rails, _ remove the clamping nuts which have been released. _ Attaching the cover plates at the top and the bottom: Prepare the cover plates for assembly by sliding on the clamping nuts contained in the accompanying bag (smooth side of the clamping nuts facing outwards). stick on the HF contact strips (1 each at the top and the bottom) insert the tabs of the plates into the corresponding slots in the chassis tie-bar, tilt the cover plate toward the front panel and secure the plate and the panel by means of 3 M4 recessed screws in each case (accompanying bag). Attaching the 19" front angle: secure the front angle with 2 M5 recessed screws (accompanying bag) on the left and right hand sides of the front panel. In this manner, the device is converted to a 19" insert-module. Page 1 - 4 - 4

Installation

Operation

Parameterization

Configuration

Maintenance

General information

In principle, the RESISTOMAT does not require any maintenance by the user. If any repairwork becomes necessary, it must only be carried out by the manufacturer. The device complies with the relevant VDE (Associaton of German Engineers) specifications and postal interference suppression regulations.

Customer service

Enquiries The manufacturer strongly recommends accompanying technical enquires with the relevant serial numbers. Only then is it possible to determine the technical model (including the software version) and thus ensure a prompt solution. The serial number is shown on the the type plate at the bottom, right-hand corner of the rear panel of the device.

Shipping instructions If the RESISTOMAT®has to be sent in for repairwork, the following must be observed as regards packaging and shipping:

- If complaints arise, we recommend describing the fault in keywords and attaching the list to the housing of the device.
 Stating your name, department and complete telephone number (in case further enquiries arise) will also accelerate service.
- For shipping via rail, forwarding agencies or other transport companies, it is advisable to use the carefully stored original packaging or an equivalent. Damage occuring during transport as a result of inadequate packaging is not covered by the guarantee.

Factory guarantee

Burster precision measurement technology guarantees reliable operation and correct calibration data for a period of 12 months after delivery.

Repairwork required within this period will be carried out free of charge.

Damage caused through improper handling of the device or transgression of the specified limiting values are not covered by the guarantee.

In addition, the manufacturer will on no account accept any responsibility for consequential damage.

Our delivery and payment terms are applicable.

burster **RESISTOMAT®**

Type 2304

Installation

Operation

Operation

The measuring unit of the high-precision RESISTOMAT® 2304 automatic measuring and testing device operates on the principle of an advanced 4-wire design shown in Fig. 1.3. The voltage drops when current is applied are measured not only across the test unit, but also across an internal reference resistor. Both voltage drops are used to calculate the quotient, which is multiplied by the characteristic value of the reference resistor in order to determine the ohmic value of the test unit. This procedure eliminates contact and transition resistances and is advantageous in that measurement errors are only dependent on the quality of the internal, highly stable reference resistors. Accordingly, the measuring device allows an extremely accurate determination of the test unit's resistance, irrespective of the parasitic resistances in the electrical circuit.



Fig. 1.3: Block diagram of the 2304

Installation

A measured value results from the computational combination of 2*4 single measurements from a measurement cycle and comparison with the internally stored reference value. In this context, a distinction is always made between BIPOLAR and UNIPOLAR measurements of ohmic or inductive resistances (see Chap. 4.5, V.1). The resulting measurement cycles are illustrated in the following Figures 1.4, 1.6 and 1.7:



Fig. 1.4: **BIPOLAR** measurement of ohmic resistances

The transient period E1 leading to the negative measurement current value and a subsequent waiting period (see Chap 3.1.2, V.5 variable, standard value=1), are followed by two parallel, single measurements of R_x via amplifier channel V_x and of R_{ref} via amplifier channel V_{κ}. After that, the amplifier channels V_x and V_{κ} are switched over and the two measurements are repeated after a renewed waiting period with the amplifiers interchanged. Now the polarity of the measurement current is switched to the positive value, and the above-mentioned half-cycle is repeated accordingly. The allocation of the switching operations to the resistors and amplifier is clarified once again in Fig. 1.5.

Page 1 - 6 -2

Programming

Fechn. Specifica-ions & Appendix





Installation

Operation

Programming

Techn. Specifica-tions & Appendix

I

After the start key is operated, a test pulse about 30 ms long is sent to the test unit. If the test unit actually has a significant inductive content, the maximum transient and waiting periods (see Chap. 3.1.2, V.5) are prolonged and the measurement is started as shown in Fig. 1.4.

In the MEASMODE = SINGLE (see Chap. 3.1.2., V1), this sequence is repeated after renewed operation of the start key (including the test pulse).

In contrast, in the MEASMODE = REPETITION, the test pulse only occurs once.

If MEASSEQ = BIPOLAR is selected, the connection of large inductances can lead to excessively long measurement cycles, due to the counter-voltage arising during switchover and polarity reversal; in certain cases, stable measurement values cannot be obtained at all. Then it is advisable to select MEASSEQ = UNIPOLAR.





Fig. 1.7: UNIPOLAR measurement of ohmic resistances

burster **RESISTOMAT®**

Installation

Operation

After the start key is operated, a reference measurement (half-cycle) is carried out (see Fig. 1.7), the transient period E1 leading to the positive measurement current value is allowed to elapse, and the measurement sequence (from Fig. 1.4) for positive currents is started. In MEASMODE = SINGLE, the sequence is repeated after renewed operation of the start key (including reference measurement).

In contrast, in the MEASMODE = REPETITION, the reference measurement is only carried out once.

B2) BIPOLAR measurement of inductive resistances Z

The measurement sequence corresponds to B.1 and Figure 1.7. In order to save time, an inductive test unit is presupposed, i.e. no inductance test is carried out as in Fig. 1.6. However, the prolonged values in A2 apply for the transient and waiting periods.

Parameterization Configuration Calibration

Programming

Specifica-

Techn. S tions & /

Table of contents, chapters 2 - 1 to 2 - 5

Operating the RESISTOMAT®2304

Introduction2-1-1
Switching on the device2-2-1
Display
General information
Controls2-4-1
Display-oriented keypad2-4-2 Permanently assigned function keys
Measurement range selection 2-4-5
Starting a measurement
Access to configuration and calibration menus 2-4-6
Numerical keyboard
Measurement of inductive testunits2-5-1



Operation of the RESISTOMAT[®]2304

Introduction

The RESISTOMAT[®] 2304 is a precision electronic device for measuring resistances; it has been developed specially for applications involving industrial measurement and testing techniques. It is capable of high resolution up to 1 n Ω , offers measuring currents of between 100 μ A and 10 A, and can be controlled completely with a standardized programming language (SCPI) via a computer.

Due to the complexity of its functions, it is advisable to install the device in steps (Chap. 1), start it up (Chap. 2) and parameterize it (Chap. 3). Chapters 4 (configuration), 5 (calibration) and 6 (programming) should not be dealt with at the beginning, as useful preselections have been provided for these features in Chap. 7.4.

In order to facilitate the treatment of Chapters 3 - 5, it should be mentioned here that all menu descriptions have been arranged in the following, standard format:

- I) A c c e s s, i.e. key designation for access to the menu,
 - <u>Function</u> of the menu,

 $||\rangle$

III) Restrictions, to be observed when using the menu, Operation

Parameterization

Configuration

Type 2304



RESISTOMAT[®] burster



In the case of certain menus, this sequence does not always correspond with the "normal" control sequence. However, this disadvantage has been accepted in the interests of a standard representation.

Page 2 - 1 -2





"Parameterize", "Evaluate" and "Special Function".

Page 2 - 2/3 -1

Techn. tions & õ

Installation

Operation

Parameterization

Header fields

K1 (\leq 6 characters + 1 number):

SINGLE or REP. measurement (see Chap. 3.1.2, V.1) and measurement cycle information (continuous numbers from 1 to 9, every number represents a measurement cycle as described in Chap, 1.6).

K2 (\leq 5 characters):

Error messages, e.g. I selected measurement current cannot be adjusted (the complete list can be found in the appendix $\stackrel{\triangle}{=}$ following Chap. 7.3). An error message remains until a new error occurs or the original error has disappeared.

K3 (\leq 9 characters):

Temperature display if temperature compensation has been activated (see Chap. 3.2.2, V.1). An A before the temperature value represents automatic temperature measurement, and an M before the temperature value represents manual temperature measurement,

e.g.A 20.5°C or M 120.5°C.

K4 (1 character):

Type of test unit (see Chap. 3.1.2, V.6), R means: purely ohmic test unit, Z means: inductive test unit with ohmic component.

K5 (1 character):

Measurement mode (see Chap. 4.5),

B means: BIPOLAR measurement, U means: UNIPOLAR measurement

Only the bipolar measurement mode ensures that parasitic thermoelectric voltages in the measurement circuit are compensated during every measurement.

K6 (\leq 6 characters):

Currently selected measurement range (see Chap. 2.4.2.1), for example, the largest measurable value for the 20 k Ω measurement range is 19.999 K Ω .

K7 (\leq 6 characters):

Currently selected measuring current (see Chap. 3.1.2, IV.3) + V.2), e.g.100 μ A.

Configuration



Function keys

F1 - F4:

Depending on the selected menu, these keys have different meanings which are redefined via the software in accordance with the selected menu.

F5:

This key is reserved for jumps to other menus. At the highest level of the main menu ("Parameterize", "Evaluate" and "Special functions"), for example, it allows a changeover to the next menu at the same level (in the sequence mentioned). At the lowest menu level, a return to the intermediate level is always effected with F5.



Installation Field for the measured value The measured value can be indicated in this field as follows: Operation A) as an ohmic resistance in Ω , as a resistance per unit length in Ω /unit length, B) Parameterization C) as the specific resistance of a conductor in Ω * unit of length, whereby the following applies: $\rho = \mathbf{R} \cdot \mathbf{S}/\mathbf{I} = \mathbf{R} \cdot \mathbf{m}/(\rho_{m} \cdot \mathbf{I}^{2}),$ S is the cross-sectional are of the conductor, I the measured length of the test unit, Configuration m the mass of the measured length of the test unit, ρ_m the specific conductor material density in g/cm³. as a specific conductance in $1/(\Omega * unit length)$, D) whereby the following applies: Calibration $\gamma = 1/r$. as a perentage deviation from an entered specified E) value R. Programming If the comparator or classify function has been activated (see Chap. 3.2.3) the following displays are possible: F) Use of the 3-class comparator: Techn. Specifica-tions & Appendix =: Measured value in specified window, <: Measured value smaller than the lower limit LL, >: Measured value larger than the upper limit value UL. Page 2 - 3 - 4




The temperature compensation (see Chap. 3.2.2) can be combined with all the display modes mentioned.



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Type 2304

Installation

Controls



RESISTOMAT® burste

Installation Operation Parameterization Configuration Calibration Programming Techn. Specifica-tions & Appendix

The controls in Fig. 2.2 are arranged in the following function blocks:

Display-oriented keypad

This block has five function keys

F1 - F5,

whose meanings are defined according to the selected menu, as well as the

Cursor controls \blacktriangleleft , \blacktriangle , t and \triangleright .

Using the

Cursor controls, ▲, t, ◀, ►

parameters (lines) are selected and value lists are scrolled through.

In the case of external computer control (see Chap. 6),

the F5 key

has a special function:

It allows a return to keyboard operation, which causes the F5 definition = LOCAL displayed during computer control to vanish.

The

ENTER key

is meant for acknowledging entries. After this key is operated, the program returns to one of the three main menus (exceptions: scaling factor calibration described in Chap. 5.3 and the menu for individual, range-dependent selection of the measuring current described in Chap. 3.1.2, IV.3).





Installation

RESISTOMAT[®] burster

2nd Alternative: Incrementing or decrementing the measurement range with the cursor keys



i.e. selection of the measurement range indicated in the field for measured values with the help of the cursor keys.

The RGE LED remains lit until the entry is completed with the ENTER key. The entry has then been accepted.

In principle, the following range limits are valid:

F	lange		Meas	sured	value
200	μΩ	<	200	μΩ	
2	mΩ	<	2	mΩ	
20	mΩ	<	20	mΩ	
200	mΩ	<	200	$m\Omega$	
2	Ω	<	2	Ω	
20	Ω	<	20	Ω	
200	Ω	<	200	Ω	
2	Ω	<	2	kΩ	
20	kΩ	<	20	kΩ	





Installation

Operation

Parameterization

Configuration

Access to configuration and calibration menus



Start of the entry of a 4-digit security code ("SELect"), with the help of which various configuration and calibration menus are accessible as described in Chapters 4 and 5 (not possible while a measurement is in progress, i.e. the STOP LED must be lit).

Sequence:



The SEL LED remains lit until the entry of the last *Number N4* is complete.

The selected configuration or calibration menu only appears after the correct code has been entered.

Any attempt to enter a security code (successful or unsuccessful) effects an entry (with date and time) in the access monitor (see Chap. 3.3.2).

A current entry up to N3 can be aborted with the clear key C.

Numerical keyboard:

This section contains the nine numerical keys $0 \dots 9$, the decimal point and the clear key C, with the help of which entries which have been started can be cleared. This clear function also resets the

· SEL und · RGE

functions.

Units key:

The $\mu\Omega$... $k\Omega$ keys are meant for completing range entries which have been started with the \cdot RGE key, and for completing all other entries with the Ω unit (e.g. comparator limiting values, reference variables etc.) without use of the \cdot RGE -key.

Techn. Specifications & Appendix Programming Calibration

burster RESISTOMAT®

Test unit connections:

Test units are connected in 4-wire resp. Kelvin configuration; the two outer terminals on the front panel shown in Fig. 2.2



comprise the current path, while the inner terminals next to the resistance symbol comprise the voltage circuit.



The warning LED marked with 🖄 indicates whether an inductive test unit has been recognized if load type Z has been selected (see Chap. 2.3.1, K4 and Chap. 3.1.2. As long as this LED stays lit, the test unit may not be removed, for reasons of safety (build-up of inductive counter e.m.f's). This also applies when the STOP LED lights up at the same time.

As shown in Fig. 1.2, it is also possible to connect the test unit to a connector on the rear panel of the device. The pin assignment can be found in Chap. 7.2.4.

As long as the \triangle -LED stays on, no entries are possible, except for STOP and F5-LOCAL.

Installation

Programming

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Meas	urement of inductive test-units	stallation
	(e.g. motors, transformers, cable drums)	Ĕ
	Important!	tion
Particular	caution must be exercised with inductive test units!	Opera
lf	 the plugs are pulled out of their sockets, the measurement current is switched over, the cables tear, the terminals on the test unit are loose, the unit is turned off during a measurement, the power fails during a measurement, the measurement current changes due to other 	Parameterization
Then	this could give rise to extremely hazardous induced voltages which might also destroy the unit.	Configuration

Notes

When inductive test units are measured, energy accumulates inside them. In case of any interruption, no matter how brief, this energy is discharged in an uncontrolled manner. This could result in severe injuries to operators and damage to the measuring device. Consequently, only controlled discharges via the internal circuit are permissible. For this, press the STOP key and wait for the red warning lamp above the measurement terminals on the front panel to go off.

Recommended device setting:

-	UNIPOLAR measuring sequence	see page	4-5-1
-	LOW or MEDIUM resolution	11	3-1-12
-	LARGE measurement current	w	3-1-6
-	Average value 1	81	3-1-6
-	Time base 9	n	3-1-6
-	Measurement pause 1	17	3-1-6
-	Load Z	R	3-1-6

Note that the device does not recognize inductive test units itself, but that the "Z" operating mode must be selected by the user.

Calibration

Programming

Techn. Specifica-tions & Appendix

Page 2 - 5 -1

Bipolar as well as single measurements are possible for test units with a small inductive component (known to include transformers and motors rated up to approx. 2 kVA).

The moment the measurement values are no longer reproducible, i.e. exhibit distinct steps, a switchover must be made to unipolar and continuous measurement.

The measurement current must be as large as possible, due to the constant presence of ambient interferences and thermal e.m.f's in the measuring circuit.

To obtain stable measurement values nevertheless, the time base of the A/D converter must be set to 9, and the average-value formation must be increased to the required value (1- approx. 10).

The measurement pause should always remain set to 1.

Increases in the case of small inductive test units and bipolar measurement are only feasible in extreme ranges and the presence of severely fluctuating thermal e.m.f's. The set value combined with the transient time has a multiplicative effect on the total measurement time. For this reason, particular caution must be exerceised here.

In the case of extremely long discharge times, the measurement is interrupted. If this occurs, a careful increase in the measurement pause can still allow the measurement to be continued.

For test units with an inductive response, the "Load" must always be set to "Z".

The measuring circuit must be checked before a measurement is started; in particular, it must be ensured that the contacts are mechanically and electrically secure.

By selecting the appropriate measurement leads and connecting them properly to the test unit, ensure that the current flow cannot be interrupted under any circumstances until the test unit is completely discharged.

To discharge the test unit:

Press the STOP key and wait for the red warning lamp above the measurement terminals on the front panel to go off. It is only afterwards that the measurement circuit can be interrupted without any danger to the operator or the device.

To check the extent to which a measurement can be reproduced, wait sufficiently long after the warning lamp has extinguished before repeating the measurement. This is because the test unit still carries low residual induced voltages which are not yet discharged entirely when the warning lamp goes off, and which would thus affect results if a new measurement were commenced immediately.



Table of contents, chapters 3-1 to 3-3

Operation of the RESISTOMAT®2304

Parameterizing (main menu 1)	
Measurement parameters (SETTING 1)	
Boundary conditions (SETTING 2)	
Measurement units (DISPLAY MODE)	
Reference variables (ENTRY)	
Reference variables for Ω/m and Ω/km	
Reference variables for $\Omega/10$ ft and Ω/k ft	
Reference variables for Δ %	
Reference variables for ρ_1 and γ_1	
Reference variables for ρ_2 and γ_2	

Installation Operation Parameterization Configuration Calibration Programming Techn. Specifica-tions & Appendix ·



Evaluation (main menu 2) 3-2-1	Installation
General information3-2-1	l
Temperature compensation (TC)	Dperation
Comparator parameters (COMP)3-2-8	3
COMPARATOR, COMPARATOR TYPE, BAR DISPLAY	2
LIMITING VALUE UNIT, DISPLAY UNIT (relay outputs)	atic
Comparator statistics (STATCOM3-2-1)	7 ameteriz
Classify statistics (STATCLA)	
Special functions (main menu 3)	Configuration
Access monitoring (CONTROL)3-3-4	4
Cooling curve (COOL)3-3-6 Rc, T1, Δt, R(t), T2	Calibration
Interfaces (INTERFACE)	2
Printer parameters (PRINTER)	2 Programming

Page 3 - 1 -2

a X -

.



Туре 2304

Installation

Operation

Parameterization

Specifica-Appendix

Techn. S tions & /

Operation of the RESISTOMAT[®]2304

Parameterizing (main menu 1)

General information

The main menu shown in Fig. 3.1 allows access to setting menus with the help of which measurement parameters, boundary conditions, measurement units and their reference variables can be specified. Figure 3.2 shows the underlying, three-level menu hierarchy as well as the function keys and paths via which transitions between the individual menus can be made.

Configuration	K7	<u>K6</u>	K5	K4	K3	K2	K1
Calibration		olay	disp	lue	easured va	eld for m	F
amming	CONT	C	ENTRY		Mode	SELECT 2	SELECT 1
Progra	F5		F4		F3	F2	F1

Fig. 3.1: Parameterizing (main menu 1)

Туре 2304

RESISTOMAT® burster

Installation	I)	<u>A c c e s s,</u> Via cold start (mains switch on) or via F5 = CONTINUE into special functions (main menu 3).	
Operation	II)	<u>F u n c t i o n</u> Measured value or comparator display and selection of various parameterizing menus.	
ameterization	III)	<u>R e s t r i c t i o n s</u> , F4 in IV.4 is dispensed with if the measurement unit Ω has been selected.	
Para	IV)	Function keys:	
Configuration	IV.1)	SELECT 1 : Setting the measurement parameter F 1 (SELECT menu 1)	rizing menu
Calibration	IV.2)	SELECT 2 : Setting the boundary conditions F 2 (SELECT menu 2)	
	IV.3)	MODE : Selecting the measurement units	
ogramming		(DISPlay MODE)	
hn. Specifica- Is & Appendix Pro	IV.4)	ENTRY:Selecting the ENTRY of the referent for the measurement unit selected $(\Omega/m, \Omega/km, \Delta\%)$ or the indicated variable r = specific red the indicated variable g = specific c	ice variables via F 3 esistance, onductance.
tion	Page 3 - 1 -4		

burster **RESISTOMAT®**

Type 2304



Installation

Operation

Parameterization

Configuration

Calibration

Programming

Techn. Specifications & Appendix

Measurement parameters (SELECT 1)

LOAD:	R	INDIV.
MEAS. PAUSE:	1	
TIME BASE(50 HZ):	5	
AVERAGE VALUE:	1	
MEASURING CURRENT:	LARGE	
MEASUREMENT MODE:	REPETITION	

Fig. 3.3: Measurement parameters

- I) <u>A c c e s s</u>: Via F1 = SELECT 1 within "parameterize" (main menu 1)
- II) <u>Function:</u> Setting.

III) <u>Restrictions</u>:

The setting of individual measuring currents via F5 = INDIV is only possible if the INDIV option in line 2 in the measuring current value list has also been selected.

IV) Function keys:



(Cursor) keys for selecting the parameter to be set, i.e. the line containing the parameter. The selected parameter is indicated in the display field in inverse form.

Page 3 - 1 - 6

IV.1)

RESISTOMAT® burster

Type 2304



After this function key is operated, the table shown in Fig. 3.4 appears. (Variations in the current are possible depending on the previous setting).

Calibration	mA mA	1	Ω kΩ	200		A	10	μΩ mΩ	200
Programming	RETURN		N3 2			mA mA mA	, 100 10 1	mΩ Ω Ω	200 200 2 20
Techn. Specifica- tions & Appendix	lly Page 3 - 1 - 7	t individual	be set	which can b	currents	nent	ble of measurem	Tat	Fig. 3.4:



Installation

Every line represents one of the measurement ranges between 200 $\mu\Omega$ and 20 k Ω , and is selected by means of the \blacktriangle - \forall keys.

A maximum of four measuring currents are assigned to each measurement range, as shown in Fig. 3.5.

Measurement range

Selectable measuring currents

200	μΩ	10 A					
2	mΩ	10 A,	1 A				
20	mΩ	10 A,	1 A,	100 mA			
200	mΩ		1 A,	100 mA,	10 mA		
2	Ω		1 A,	100 mA,	10 mA,	1 mA	
20	Ω			100 mA,	10 mA,	1 mA,	100 μA
200	Ω				10 mA,	1 mA,	100 μA
2	kΩ					1 mA,	100 μA
20	kΩ						100 μA

Fig. 3.5: Value list of the measuring currents which can be selected for each measurement range

The value lists are scrolled through with the ◀ - ▶ - keys. The acknowledgement of the displayed value and, thus, the return to the "parameterize" menu is effected via the F5 RETURN key.

- V) Parameters
- V.1) MEASUREMENT MODE:

The following value lists are provided:

- SINGLE: When the START key is pressed, only one measured value is computed and displayed (= 1 measurement cycle); after that, the device automatically returns to the · STOP state.
- REP.: When the START key is pressed, measured values are computed and displayed until the measurement is aborted by pressing the STOP key, or a measurement or contact error occurs during operation with a preselected load type Z (resistance with inductive component).
- REF0.: You can only choice it, if you have adjust measurement "CONSTANT" (see page 4-5-2). On mesure start the device make first a zero-reference measurement.

Page 3 - 1 -8

Calibration Configuration Parameterization Operation

Programming

burster RESISTOMAT®

Type 2304

Installation

V.1) MEASURING CURRENT:

The following value lists are provided; they can be scrolled through with the \blacktriangleleft - keys:

SMALL,

MEDIUM,

LARGE,

INDIV.

Depending on the range selected, the first three settings correspond to the current values shown in Fig. 3.6:

Range	SMALL	MEDIUM	LARGE
200 μΩ	10 A	10 A	10 A
2 mΩ	1 A	10 A	10 A
20 mΩ	100 mA	1 A	10 A
200 mΩ	10 mA	100 A	1 A
2 Ω	1 mA	100 A	1 A
20 Ω	100 μA	10 mA	100 mA
200 Ω	100 μA	1 mA	10 mA
2 kΩ	100 μA	1 mA	1 mA
20 kΩ	100 μΑ	100 μA	100 μA

Fig. 3.6: Measurement currents for the SMALL, MEDIUM and LARGE categories.

Only the last option, INDIV, allows the individual, range-dependent selection of the measurement current (see Chap. 3.1.2, IV.3).

V.3) AVERAGE VALUE:

Entries for this menu line are made with the numerical keyboard (see Chap. 2.4.3). For this, the value range

 $1 \leq input value \leq 255$

is available, whereby the input value specifies the number of selected measurement cycles by means of which an average value is formed and indicated.

Operation Parameterization Configuration Calibration Programming

RESISTOMAT® burster

Installation V.4) TIME BASE: Inputs for this menu line are made with the numerical keyboard (see Chap. 2.4.3). For this, the value range: $1 \leq \text{input value} \leq 9$ is available, whereby the input value specifies the multiple of the mains Operation frequency period (50 Hz: 20 ms, 60 Hz: 16.7 ms) over which the single measured values are integrated within a cycle. The adaption to the line frequency can be altered within the scope of the configuration menu 4.3. Parameterization V.5) **MEASUREMENT PAUSE:** Entries for this menu line, which is significant for inductive test units, are made with the numerical keyboard (see Chap. 2.4.3). For this, the value range $1 \leq \text{input value} \leq 255$ Configuration is available, whereby the input value specifies the waiting periods between two different measuring currents or amplifier channels within a measurement cycle. This waiting period constitutes a multiple of the mains frequency period (50 Hz: 20 ms, 60 Hz: 16.7 ms) and is sometimes needed for inductive test units in order to adapt transient periods and charging periods for the test unit. Details concerning this can be found in Chap. 1.6. Calibration V.6) LOAD: The following list values R and Z are available; they can be scrolled through with the \triangleleft - \blacktriangleright keys. Programming R implies a purely ohmic test load, while Z represents an inductive or ohmic load. When Z is selected, an inductance test is carried out before each measurement. For this reason, the measurement time is always longer than on the R selection, where this test is omitted. Techn. Specifica-tions & Appendix Before measurements on transformers and motors are carried out, all windings must be fully discharged and open. Otherwise the error message ERR 0 could occur. (see Chap. 7.3).

Installation

VI) Special comments:

Assuming that sufficiently stable measured results are to be obtained within the shortest possible measuring time, the table in Fig. 3.7 contains guidelines on how to select the correct measuring parameters (MEASUREMENT PAUSE as described in Chap. 3.1.2, V.5 is normally = 1):

Criterion	MEASUREMENT SEQUENCE Chap. 4.5 V.1)	MEASURING CURRENT Chap. 3.1.2 V,2)	TIME BASE Chap. 3.1.2 V.4)	AVERAGE VALUE Chap. 3.1.2 V.3)	MEASURING RANGE Chap. 2.4.2,1)	ODei
Stable measurement of ohmic resistances (R)	BIPOLAR	MEDIUM or LARGE	Basic settings	as in Chap. 7.4	Arbitrary	tion
Preventing ohmic test units (R) from heating up	BIPOLAR or UNIPOLAR	MEDIUM or SMALL; if LARGE is requined, observe measurement- range instructions!	Arbit	rary	Examine load capacity of test unit.	Parameterize
Interference in measurement set-up expected (R or Z)	BIPOLAR or UNIPOLAR	As LARGE as possible	1st. Prior.: as large as possible, ≤ 9	2nd. Prior.: as large as necessary, ≤ 255	In case of unstable display and/or amp. overload, select next highest range.	hauration
Large or strongly	Preferably BIPOLAR	As LARGE as possible	1st. Prior.: as small as possible ≥ 1	2nd. Prior.: as large as necessary ≤ 255	Arbitrary	Cont
varying thermal e.m.f´s (R or Z)	If BIPOLAR not possible, UNIPOLAR	As LARGE as possible	1st. Prior.: as large as necassary for stable display	2nd. Prior.: in case TIME BASE = max. increase AVERAGE VALUE	Arbitrary	Calibration
Stable measurement Small of resistances with BIPOI	Large Z: UNIPOLAR; Small Z: BIPOLAR;	As Large as possible	TIME BASE = 5 - 9 MEAS. PAUSE = 1	As large as necessary	Beginning at 20 k Ω , "approach" from above!	mina
arge inductive component (Z)	Medium Z: Possibly BIPOLAR with MEAS. PAUSE > 1	In case of oscillati adapt release limit	ions or undesived transient phases, ts as described in Chap. 4.6 !		- RESOLUTION (Chap. 3.1.3 V.5) = LOW	Program
Fig. 3.	7: Correct	selection of pa	rameters			schn. Specifica-

Installation

Operation

Parameterization

Configuration

Calibration

Programming

Techn. Specifications & Appendix I)

VII) <u>E x i t:</u> Via the function key ENTER into "parameterize" (main menu1)).

Boundary conditions (selectmenu 2)

DATE:		dd. mm. yy
TIME:		hh. mm. ss
CONTRAST:		54
BUZZER:		OFF
RESOLUTION:		MEDIUM
Fig. 3.8:	Boundary conditions	
Ac	cess:	

 $\overline{\text{Via F2} = \text{SELECT 2 within "parameterize" (main menu 1).}}$

II) <u>F u n c t i o n :</u> Display and setting of various boundary conditions relating mainly to the operating interface.

- III) <u>Restrictions:</u> None.
- IV) Function keys:



Cursor keys for selecting the parameter to be set, i.e. the line containing the parameter. The selected parameter is indicated in inverse form.

Page 3 - 1 - 12

IV.1)



is available, whereby the input value 1 constitutes the smallest, and the value 100 the largest contrast setting for the liquid crystal display. The value 54 is ideal at room temperature (20°C).

Туре 2304

Installation	V.4)	BUZZER: The list values
		ON and OFF
ation		are avaliable; they can be scrolled through with the \triangleleft -> - keys.
Opera		ON means that the BUZZER is active. This indicates the discharge of an inductive test unit (together with the warning LED described in Chap. 2.4.5)
erization		OFF means that the BUZZER is inactive.
Paramete	V.5)	RESOLUTION:
ь		with the \blacktriangleleft - \blacktriangleright -keys:
Configurati		HIGH = display of 5 1/2 digit positions, MEDIUM = display of 4 1/2 digit positions, LOW = display of 3 1/2 digit positions,
Calibration		The larger the selected resolution, the longer the measurement period. On the LARGE setting, which is normally only meant for basic investigations, the AVERAGE VALUE (V.3 from Chap. 3.1.2) and MEASUREMENT TIME (V.4 from Chap. 3.1.2) parameters are automatically set to \geq 5. Lower settings are not possible then.
b	VI)	Special comments:
Programmi		With this device, even a resolution of 1 $n\Omega$ can be achieved if the following settings are chosen:
Techn. Specifica- tions & Appendix	Page 3 - 1 -14	$\begin{array}{llllllllllllllllllllllllllllllllllll$

Exit:

Installation

VII)

Via the function key ENTER into the "parameterize" menu (main menu 1)

Measurement units (display mode)

		Measurer	nent	U	n i t s (display moc	le)	ation
	Ω		ρ		R·S/I		Oper
	Ω /	m	ρ_2	-	R · m / ($\rho_{\rm m}$ · I ²)		Ę
	Ω/	km	γ_1		1/ (R·S)		izatic
	Ω/	10 ft	γ_2		$ ho_{m}\cdot$ I² / (R · m)		neter
	Ω/	kft	Δ %	6			Parar
Fig. 3.9:		Measurement units (in accordance with D	"S" implies IN 1304)	s cros	s-sectional area		uration
1)		<u>Access:</u> via F3 = MODE withi	n "parame	terize	e" (main menu 1).		Config
11)		F u n c t i o n: Setting of the measu measurement.	rement un	it to t	be indicated for the resistance		libration
)		Restrictions: The measurement of with the Ω unit!	cooling cu	urves	(see Chap. 3.3.3) is only possi	ble -	g G
IV)		Function keys	:: Cursor ke	ave fr	r selecting the parameter to be	sat	rogrammin
17.1)			i.e. the lin paramete form.	e cor er is in	itaining the parameter. The sele dicated on the display field in inv	cted - erse	echn. Specifica- F
					Page 3	- 1 - 15	Fä

RESISTOMAT®



Page 3 - 1 - 16

V.6) $\rho_1 = R \cdot S / 1$:

If this line is selected with the cursor keys, the device indicates the specific resistance r in $\Omega *$ unit of length, based on the conductorcross-section S and the conductor length I. All evaluating and special functions described in Chap. 3.2 and 3.3 also relate to this measurement unit.

V.7) $\rho_2 = \mathbf{R} \cdot \mathbf{m} / (\rho_m \cdot l^2)$:

If this line is selected with the cursor keys, the device indicates the specific resistance ρ in $\Omega*$ unit of length, based on the mass m, density ρ_m and conductor length I. All evaluating and special functions described in Chap. 3.2 and 3.3. also relate to this measurement unit.

V.8) $\gamma_1 = 1 / (R \cdot S)$:

If this line is selected with the cursor keys, the device indicates the specific conductance g in $l/(\Omega * unit of length)$, based on the conductor cross-section S and the conductor length I. All evaluating and special functions described in Chap. 3.2 and 3.3. also relate to this measurement unit.

V.9) $\gamma_2 = \rho_m \cdot l^2 / (R \cdot m)$:

If this line is selected with the cursor keys, the device indicates the specific conductance g in I / ($\Omega *$ unit of length), based on the mass m, density ρ_m and conductor length I. All evaluating and special functions described in Chap. 3.2 and 3.3 also relate to this measurement unit.

V.10) Δ %:

If this line is selected by means of the cursor keys, the device shows Δ R as a precentage deviation from the entered specified value R. Evaluating and special functions relate to Ω .

VI) Special comments:

The reference variables required for the measurement units V.2) to V.10) are entered in the reference variable menu shown in Chap. 3.1.5. This menu is only inaccessible when the measurement unit Ω has been selected. The mass m in the case of ρ_2 and γ_2 must be based on the measured length!

VII) Exit:

Via the function key ENTER into "parameterize" (main menu 1).



Parameterization Operation

Installation

Calibration

Programming





		Installation
IV.2)	m : Unit key for completing a numerical entry of length in m as the reference variable. F 1	Operation
IV.3)	km:Unit key for completing a numerical entry of length in km as the reference variable.F 2	Parameterization
V)	<u>Parameters:</u>	uo
V.1)	LENGTH:	gurati
	Entries for this menu line are made with the numerical keyboard (see Chap. 2.4.3) including the decimal point key. For this, the value range	Confiç
	0.001 m \leq input value \leq 999.999 km	Ľ
	is available.	Calibratic
VI)	Special comments:	bu
VII)	None.	Programm
v 11 <i>)</i>	Via the function keys F1 or F2 into "parameterize" (main menu 1).	echn. Specifica- ions & Appendix

Page 3 - 1 - 19



RESISTOMAT® burster

Type 2304

IV.2) ft : Unit key for completing a numerical entry of length in m as the reference variable.	Contained
IV.3) kft : Unit key for completing a numerical entry of length in km as the reference variable.	
V) Parameters: V.1) LENGTH: Entries for this menu line are made with the numerical keyboard	
(see Chap. 2.4.3) including the decimal point key. For this, the value range $0.001 \text{ ft} \le \text{input} \text{ value} \le 999.999 \text{ kft}$ is available.	
VI) <u>Special comments</u> : None.	L'UGIAIIIII
VII) <u>E x i t</u> : Via the function keys F1 or F2 into "parameterize" (main menu 1).	tions & Appendix

RESISTOMAT[®] burster




Туре 2304

RESISTOMAT® burster











Installation

Operation

Parameterization

Operation of the RESISTOMAT®2304

Evaluation (main menu 2)

General information

Main menu 2 shown in Fig. 3.14 allows access to parameterizing and evaluating menus related to temperature compensation and the comparator functions. Fig. 3.15 shows the underlying, three-level menu hierarchy and the function keys resp. paths via which transitions between the individual menus can be made.





Page 3 - 2 -1

Techn. Specifications & Appendix









RESISTOMAT® Type 2304 Every line represents one of the 10 temperature coefficient presettings, is Installation selected with the ▲ - ▼ - keys. This line is then indicated in inverse form. Renewed entry of a selected temperature coefficient can be made via the numerical keyboard (see Chap. 2.4.3). For this, the value range $0 \leq \text{input value} \leq + 9999$ is available. The acknowledgement of the display value and the consequent return to Operation the "temperature compensation" menu is effected via the F5 RETURN key. IV.4) Sign entry for the temperature of the test unit in the +/case of manual temperature compensation. Configuration Parameterization (line 3, parameter V.3). F 2 V) Parameters: V.1) TEMP.COMP (= On/off switch for temperature compensation) The list values OFF and ON are available. They can be scrolled through with the \triangleleft - \triangleright - keys. OFF means that the **TEMP**erature **COMP**ensation is inactive: ON means that it is active. Calibration When the **TEMP**erature **COMP**ensation is active, the test unit's resistance R20 at 20 °C is displayed. This value is calculated from the test unit's resistance RT at measurement temperature V 3, taking into account the linear temperature coefficient V 4. V.2) MEASUREMENT (= manual or automatic temperature measurement) The list values Programming MAN and AUT are available; they can be scrolled through with the - keys. MAN means manual temperature measurement, in which case the test unit's temperature is entered in line 3, parameter V 3. Techn. Specifica-tions & Appendix AUT means automatic temperature measurement, in which case the test unit's temperature is measured via an externally connected Pt100 unit.

Page 3 - 2 - 6

Type 2304

Installation

Operation

V.3) TEMPERATURE (= temperature display or input)

Entries for this menu line are only possible in case of MANual temperature MEASUREMENT; they are made with the numerical keyboard (see Chap. 2.4.3) The sign is entered with the function key

+/- = F2 in accordance with IV.4.

The line is used as a display when AUTomatic MEASUREMENT has been selected.

The test unit's temperature also appears in header field K3 of the main menu (see Chap. 2.3.2). An A preceding the temperature value signifies automatic temperature measurement, while an M signifies manual temperature measurement.

V.4) TEMP.COEFF. (= display of the selected temperature coefficient)

This menu line only involves one display ("Read Only"-mode), which shows the temperature coefficient selected in the COEF = F1 submenu (see IV.3)

VI) Special comments:

Before the temperature compensation TEMPCOMP: ON is activated (line 1, IV.1) the following procedure is recommended:

Manual selection of a fixed reference temperature:

MEASUREMENT = MAN and entry of the desired temperature value in line 3, IV.3 +

COEFF = F1 and selection of a suitable temperature coefficient from the table shown in Fig. 3.16 (or preceded by entry of a new coefficient in the table)+ RETURN = F5.

Automatic measurement of the reference temperature for temperature compensation:

MEASUREMENT = AUT and COEFF = F1 and selection of a suitable temperature coefficient from the table shown in Fig. 3.16 (or preceded by the entry of a new coefficient in the table) + RETURN = F5.

VII) Exit:

Via the function key ENTER into "evaluation" (main menu 2).

Configuration

Parameterization

Techn. Specifications & Appendix

llation	(Со	mpara	ator p	a	r a m e t	ers	
Insta		СОМ	PARATOR:		OFF			
		сом	PARATOR TYP	E:	CON	MPARATOR		
Ē		BAR	DISPLAY:		OFF	a. 		
sratic		LIM.	VALUE UNIT:	:	Ω			
Ope		DISP	LAY UNIT:		Ω			
5	LV. AE	S	LV. PER					
eterizati		8: C	Comparator para	meters	· · · · ·			
Param	1)	$\frac{A c c}{via F}$	e s s: 2 = COMP withi	n "evaluation" (n	nain	menu 2).		
onfiguration	11)	II) <u>F u n c t i o n</u> : Setting of various parameters which specify the type of comparator resp. classification function.						
Calibration	111)	 III) <u>Restrictions</u>: The display and comparator resp. classification units must correspond; only under this condition can the menu be exited again. During comparator or classification operation, the upper limiting value must lie in the MANually adjusted measurement range. If this is not possible, the AUTomatic measurement range selection mode should be selected. 						
Programming	IV) IV.1)	Fur	nction keys	Cursor keys for	sele	ecting the para	meter to be set, i.e.	
Techn. Specifica- tions & Appendix	Page 3 - 2 -	8		the line contain parameter is sh	ing t iown	the parameter. 1 in the display f	The selected field in inverse form	

burster	RESISTOM	AT® Type	2304
IV.3)	LV.ABS. F 1	: Selection of the menu for setting the specified value and the comparator Limiting Values as ABS olute values in the selected measurement unit.	tallation
		After this function key is operated, two different setting menus can appear, depending on the COMPARATOR TYPE selected in line 2:	Ē
		A as shown in Fig. 3.19 or B as shown in Fig. 3.20.	ation
		Comparator Limiting Values entered as ABS olute values are automatically converted into PER centages and transfered into the menus IV.4, A or IV.4, B. That is, limiting values can be entered as ABS olute values or as PER centages of the specified value, according to requirement.	zation Oper

IV.3.A) COMPARATOR TYPE = COMPARATOR, i.e. dual comparator operation with specified value and lower and upper limiting values:

figuratic		100.00 Ω	SPE. VAL.:
Con		90.00 Ω	LOWER LIMIT:
Ę		110.00 Ω	UPPER LIMIT:
alibratic	RETURN		

Fig.3.19: Entry of comparator, specified and limiting values as absolute values.

Line 1 states the SPECIFIED VALUE, line 2 the LOWER LIMIT and line 3 the UPPER LIMIT of the comparator. One of these lines is selected with the ▲ --▼ keys; it is then displayed in inverse form. A numeric value entered in this manner can be re-entered via the numerical keyboard (see Chap. 2.4.3). For this, the value range

 0Ω < input value $\leq 20 \text{ K}\Omega$

is available, whereby the upper limit must be larger than the lower limit.

Parameter

ç

Programming

Techn. Specifications & Appendix

Туре	2304				RE	SISTO		
Installation		The UP If ti	e following restric PER LIMIT/100 he Ω unit has be	ction also appli < input value : en selected (se	es to the ≤ 20 kΩ ee Chap.	SPECIFIED and \leq UPPE 3.1.4), entr) VALUE: ER LIMIT. ies are completed	
Operation		sin Un F1. to t key	hply by means of its different to Ω, ϵ . In this case, entri- the menu "compa /.	one of the mea e.g. Ω/m etc. an es of numbers a trator parame	asuremer e shown i are comp ters" is (nt range key n the field abo leted by ope effected via	rs (see Chap. 2.4). ove the function key erating F1. A return the F5-RETURN	
ation	IV.3.B)	CC cla	MPARATOR TY ssification function	PE = CLASSIF on:	FY, i.e. op	peration with	n 9-class	
teriza	LV	1:	96 Ω	LV 5	5:	101 Ω		
ame	LV	2 :	97 Ω	LV 6	6 :	102 Ω		
Par	LV	3 :	98 Ω	LV 7	7 :	103 Ω		
uo	LV	4 :	99 Ω	LV 8	3:	104 Ω		
urati				SPE		100 Ω		
Config							RETURN	
Calibration	 FIG. 3.20: Classify function, entry of the specified value and limiting value as absoltue values. Lines 1 to 8 contain the limiting values available for classification, and line 9 states the corresponding specified value. One of these lines is selected wit the ▲- ▼ keys and then indicated in inverse form. A numerical value 							
Jramming		Ch Fo	ap.2.4.3). r this, the value r available, wherek	ange 0 Ω <i by</i 	input valu	ue ≤ 20 KΩ		
Proç		ар	LV1 < plies as a bound	LV2 < LV3 < L ary condition.	_V4 < LV	5 < LV6 < L'	V7 < LV8	
ifica-		Th	e following restrie	ction also appli	es to the	SPECIFIED) value:	
echn. Spec ons & Appe			LV8/1	00 < input val	ue ≤ 20	$k\Omega$ and $\leq L$	V8.	

Installation

Operation

Parameterization

Configuration

If the unit Ω has been selected (see Chap. 3.1.4), entries are completed simply via one of the measurement range keys (see 2.4). Units different to Ω , e.g. Ω/m etc. are shown in the field above the function key E1. In this case, entries of numbers are completed by operating E1.

key F1. In this case, entries of numbers are completed by operating F1. A return to the menu "comparator parameters" is effected via the F5 RETURN key.

IV.4)



: Selection of the menu for setting the specified value and the comparator Limiting Values as **PER**centages of the specified value.

After this function key is operated, either of two setting menus A (see Fig. 3.21) or B (see Fig. 3.22) can be selected, depending on the COMPARATOR TYPE selected in line 2:

Comparator Limiting Values which have been entered as PERcentages, are converted automatically into ABSolute values and transferred to the menus IV.3, A or IV.3, B. Consequently, limiting values can be entered as PERcentages or ABSolute values, according to

IV.4.A) COMPARATOR TYPE = COMPARATOR, i.e. simple comparator operation with specified value and lower and upper limiting values:

requirement.

- in				tion
	SPECIFIED VALUE:	100.00 Ω		libra
	LOWER LIMIT:	- 10.000 %		Ca
	UPPER LIMIT:	+ 10.000 %		
				ning
			RETURN	ogramı

Fig.3.21: Comparator, entry of specified value as absolute value, entry of limiting values as percentages



Туре	2304				RESISTO	MAT [®] burste
Installation		Line 1 s 3 the ⊥ ▲ - ♥ k in this r 2.4.3).	states the SPI upper limit of th eys and then i manner can be The value ran	ECIFIED VALUE, ne comparator. On ndicated in inverse e reentered via th nge	line 2 the LOWEF le of these lines is s e form. A numerica e numerical keybo	R LIMIT and line selected with the al value selected pard (see Chap.
_			($\Omega < input value$	e ≤ 20 KΩ	
peratior		is avail a perce	able for the sp entage of the s	pecified value. For specified value,	r the limiting value	es expressed as
0			-	$99.9\% \le input val$	ue < 10000%,	
Parameterization		applies Negativ the sign If the un are cor Units di F1. In t	, whereby the limiting value limiting value of the numbrit Ω has been npleted simply ifferent to Ω , e his case, numbrit for the second se	e upper limit must ues can be entered er just selected. In selected for the s via one of the mu .g. Ω/m , are shown herical entries are	at be larger then ad with the F3 key specified value (se easurement range n in the field above completed by pre	the lower limit. which reverses e 3.1.4), entries keys (see 2.4). the function key ssing F1.
Configuration		In contr with the A retur TURN.	rast, the entrie e F2 key. n to the men	es of limiting value u "comparator pa	es as percentages rameters" is effec	s are completed sted via F5-RE-
Calibration	IV.4.B)	COMP/ classific	ARATOR TYF cation functio	PE = CLASSIFY, i n:	.e. operation with	9-class
	LV 1	: -4	%	LV 5 :	1%	
ning		2: -3	%	LV 6 :	2%	
ramı		3: -2	%	LV 7 :	3%	
Prog		+2	70	LV 8 : SDE ·	4 % 100 O	
dix			%	+/-		RETURN
ecifi						
chn. Sp ns & Aj	riy.3.22:	limiting	value (perce	ntage)	cmed value (absc	nute), entry of the

12 T

Page 3 - 2 - 12

Installation

Operation

Parameterization

Configuration

Calibration

Programming

n. Specifica-& Appendix

Techn. Stions &

Lines 1 to 8 contain the limiting values available for classification, and line 9 states the corresponding specified value. One of these lines is selected with the \blacktriangle - \triangledown - keys and then indicated in inverse form. A numerical value selected in this manner can be re-entered via the

$$0 \Omega < \text{input value} \le 20 \text{ K}\Omega$$

numerical keyboard (see Chap. 2.4.3). The value range

for the specified value. For the limiting values expressed as percentages of the specified value,

$$-99.9\% \le \text{input value} < 10000\%$$

applies, whereby

LV1 < LV2 < LV3 < LV4 < LV5 < LV6 < LV7 < LV8

must be considered as a boundary condition. Negative limiting values can be entered with the F3 key which reverses the sign of the number just selected.

In case the Ω unit has been selected for the specified value (see 3.1.4), entries can be completed simply via one of the measurement range keys (see 2.4). Units different to Ω , e.g. Ω/m , are shown in the field above the function key F1. In this case, numerical entries are completed by pressing F1.

In contrast, the entries of limiting values as percentages are completed with the F2 key.

A return to the menu "comparator parameters" is effected via F5-RETURN.

V) <u>Parameters</u>:

V.1)

COMPARATOR = on/off switch for the comparator (as dual comparator or classification comparator):

The list values

OFF and ON

are available. They can be scrolled through with the ◀ - ► keys. OFF means that the COMPARATOR function is inactive, ON means that it is active.

Тур	e 2304		RESIS	TOMAT [®] burster
Installation		In this case, menus show value: - Dual com	the fields for indicating the measured vantue following comparator symbols insterparator mode: < : measured value <	alues in all three main ad of the measured lower limiting value,
			= : lower limiting value ≤ upper limiting va > : measured value> ∟	e ≤ measured value lue, µpper limiting value.
Operatio		- Classify o	peration	Bange
				nanye
zation		< 1 2	$\begin{array}{rllllllllllllllllllllllllllllllllllll$	RGE0 RGE1 RGE2
meteri		3 4 5	$LV3 \leq$ Measured value $< LV4$ $LV4 \leq$ Measured value $\leq LV5$ $LV5 \leq$ Measured value $\leq LV6$	RGE3 RGE4 RGE5
Para		6 7	$LV6 < Measured value \le LV8$ $LV6 < Measured value \le LV7$ $LV7 < Measured value \le LV8$	RGE5 RGE7
Configuration	V.2)	> COMPARAT two limits (du	LV8 < Measured value TOR TYPE = Select whether the compa- ual comparator) or eight limits (classifica	RGE8 arator is to operate with ation comparator):
		The list value	es	
_			COMPARATOR and CLASSIEV	
ation		are available	e. They can be scrolled through with the	∢ - ▶ - keys.
Calibra		COMPARAT >, = , <. CLAS is active.	FOR means dual comparator mode with SSIFY means that the classification comp	three ranges, arator with nine classes
nming	V.3)	BAR DISPL/ The list value	AY = on/off switch for the bar display: es	
lrar			OFF and ON	
Prog		are available	e. They can be scrolled through with the	┥ - 🕨 - keys.
echn. Specifica- ons & Appendix		OFF means t of the measu three main m activated bef	that the bar display is inactive. ON means ired value - on the fields for displaying the nenus. However, this only applies if the CC forehand. Fig. 3.23 shows the appearance	that it appears - instead measured values in all OMPARATOR was also of a typical bar display.
	Page 3 - 2 - 1	14		

Type 2304



This only involves one display ("read only" mode), which states the previous unit active for the specified value and comparator limiting values in the setting menus.

Attention:

A change of the measurement unit in the unit menu (see Chap. 3.1.4) does not have any effect on the unit of the selected limiting values. For this reason, they must be changed in accordance with the specification in the field of the F1 function key after a change of measurement unit in the setting menus 3.19, 3.20, 3.21 or 3.22.

Page 3 - 2 - 15

Programming

Specifica-

Techn. tions &

Installation V.5) DISPLAY UNIT = Indication of the selected measurement unit: This only involves one display ("read only" mode) which states the selected measurement unit (see Chap.3.1.4). Operation VI) Special comments: The comparator can only be activated in accordance with V.1) if the DISPLAY UNIT (V.5) and LIMITING VALUE UNIT (V.4) Parameterization are identical. The comparator ranges are assigned to relay outputs whose pin assignment is shown in Chap. 6.2.3. The relays are inactive in the idle state. In this case, O is connected to W. The relay function becomes **active** (S is connected to W) **only** when the SINGLE measurement mode and comparator function Configuration are selected. In addition, a valid measurement must be available. The relay remains active until another one is switched, or an invalid measurement (with error message) occurs, or the REPETITION measurement mode is selected, or the device is switched off. Duringcomparator operation, the following applies: Calibration Relay 0 \triangleq <. Relay 4 \triangleq = and Relay 8 \triangleq >. For the classification function, relay number \triangleq range number Programming applies. (see page 3-2-14). VII) Exit: Via the function key ENTER into "evaluation" (main menu 2). Fechn. Specifica-ions & Appendix Page 3 - 2 - 16

Type 2304

tallation

Parameter

Configuration

Comparator statistics

		S
Range 1 (<) :	0	
Range 2 (=) :	0	u
Range 3 (>) :	0	eratic
Total:	0	ď
RESET		zation

Fig. 3.24: Comparator statistics (value range 9999999)

I)

Access: Via F2 = STATCOM within "evaluation" (main menu 2).

 $||\rangle$ Function: Display of the subtotals allotted to the three evaluation ranges of the comparator after a certain number of single measurements, as well as the total.

|||)**Restrictions**: The comparator statistics function only when the comparator is active (see Chap. 2.3.2, V 1) and when the SINGLE mesaurement mode is selected (see Chap. 3.1.2, V.1).

IV) Function keys:

E

N

Ţ Ε R



Acknowledgement of the current measurement parameter setting and return to the next higher menu level.



Page 3 - 2-17





tallation

Parameteriza

Configuration

Calibration

Programming

Techn. Specifications & Appendix

Classification statistics

0				 		
Ë	0	•	RGE 5	0	(<):	RGE 0
	0	:	RGE 6	0	:	RGE 1
lion	0	:	RGE 7	0	*	RGE 2
perat	0	(>) :	RGE 8	0	:	RGE 3
ō	0	:	TOTAL	0	:	RGE 4
ition						RESET

Fig. 3.25: Comparator statistics (value range 9999999)

I) $\frac{A c c e s s}{Via F4 = STATCOM within "evaluation" (main menu 2).}$

:

II) Function:

Display of the subtotals allotted to the nine evaluation classes after a certain number of single measurements, as well as the total.

III) <u>Restrictions</u>:

The classification statistics can be used only when the classification function is active (see Chap.2.3.2, V.1) and the SINGLE measurement mode is selected (see Chap. 3.1.2, V.1).

IV) Function keys:

IV.1)



Acknowledgement of the current measurement parameter setting and return to the next higher menu level.

IV.2)	RESET	RESET of the subtotals and the total.
,	F 1	

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ation	V)	Parameters:						
Install	V.1)	RANGE 0 (<): Number of measured values allotted to the range 0 after a certain number of single measurements:						
по		measured values < lowest limiting value LLV1						
Operati	V.2) - V.8)	RANGES 1 - 7: Number of measured values allotted to one of the classification windows 1 to 7 (see Chap. 3.2.3, V.1) after a certain number of single measurements.						
erization	V.9)	RANGE 8 (>): Number of measured values allotted to range 8 after a certain number of single measurements:						
amete		highest limiting value HLV8 < measured values.						
Par	V.10)	TOTAL:						
uration		Sum of V.1 + V.2 + V.3 + V.4 + V.5 + V.6 + V.7 + V.8 + V.9.						
onfig	VI)	Special comments:						
0		The following procedure is recommended for using the classification						
Calibration		 MEASUREMENT MODE = SINGLE (Chap. 3.1.2, V.1) COMPARATOR TYPE = CLASSIFY (Chap. 3.2.3, V.2), select the LIMITING VALUE UNIT equal to the DISPLAY UNIT! 						
5704		(Check for equality; if necessary, match the measured value units -see Chap. 3.1.4 - and the limiting value units - see Chap.3.2.3 IV.3),						
ramminç		 COMPARATOR = ON (Chap. 3.2.3, V.1), Performing the desired number of measurements (see Chap. 2.4.2.2). 						
Prog		The totals remain stored even after the mains voltage has been turned off.						
ca- dix	VII)	<u>Exit:</u>						
hn. Specifi is & Appen		Via the function key ENTER into "evaluation" (main menu 2).						
Tec	Page 3 - 2 -	20						







Type 2304

IV) IV.1)	Functionkeys: CONTROL : Selection of the table for access monitoring, i.e. CONTROL : CONTROL of any access to the configuration	Installation
IV.2)	F 1 menus which has been carried out via the SEL key. COOL : Selection of the parameterization menu for recording	Operation
IV.3)	F 2 a COOLing curve. INTERF. : Selection of the menu for INTERFace INTERF. : Selection of the menu for INTERFace	leterization
	PRINTER	uration Paran
IV.4+)	F 4 Selection of the menu for PRINTER	on Config
V)	<u>Parameters:</u> Header fields (see Chap. 2.3.2)	Calibratio
VI)	<u>Special comments:</u> None.	nming
VII)	<u>E x i t:</u> Via F 5 / = CONTINUE into parameterize (main menu 1) or	Progran
	via / SEL / N1 / N2 / N3 / N4 / into the configuring menus. Page 3 - 3 -3	Techn. Specifica- tions & Appendix

Page 3 - 3 -3

Туре 2304

Installation		Acce	ss monito (CONTROL	ring)
g	21.	.02.91	11:01:23	SEL
ratic	22.	.02.91	12:02:10	SEL
Ope	22.	02.91	13:03:11	SEL
	23.	.02.91	14:04:12	SEL
ation	24.	.02.91	16:06:34	SEL
Parameteriza	L Fig.3.28:	Access monitoring		
ation	")	<u>Access:</u> Via F1 = CONTRO	DL within "special functions	s" (main menu 3)
Configur	11)	<u>F u n c t i o n :</u> Time-based regist configuration and	ration of all attempts by the calibration menus (see Ch	e user to access the ap. 4).
Calibration	III)	R e s t r i c t i o n s A maximum of 256 exceeded, the old	<u>s:</u> 6 positions (lines) can be re est line is deleted every tin	gistered. Should this number be ne a new line is to be registered
nming	IV)	Function ke	<u>y s:</u>	
Progran	IV.1)		Cursor keys for selecting currently displayed.	ng further lines which are not
nn. Specifica- is & Appendix			while the six succeedin displayed with the ▼-	g lines (provided they exist) are key.

Page 3 - 3 - 4





Installation

Operation

Parameterization

Configuration

Calibration

Programming

Techn. Specifications & Appendix

As R cannot be measured until the load current has been turned off, i.e. after a certain delay time, R2 can only be determined by extrapolating the cooling curve.

- II.2)Parameter settings and recording of the dynamic characteristic of any electrical
resistance $\leq 20 \text{ k}\Omega$ (data logging).
- III) Restrictions:

For resistance measurement R(t), the values set in the parameterization and evaluation menus are always taken over, and can no longer be changed in the cooling-curve menu. Consequently, the parameters should be optimized (see Chap. 3.1.2, VI) before the cooling curve is recorded. However, the following exceptions apply:

A) Measurement of the cold resistance Rc of the test unit:

LOAD (see Chap. 3.1.2, V.6)	= Z,
Measurement unit (see Chap. 3.1.4. V.1)	= Ω,
TEMP.COMP: (see Chap. 3.2.2, V.1)	= OFF
COMPARATOR (see Chap. 3.2.3, V.1)	= OFF

B) Measurement of the test unit's resistance R(t) as a function of the cooling time:

as in A), and additionally,

MEAS. MODE (see Chap. 3.1.2, V.1) = REPETITION.

After the cooling curve menu is selected, these parameters are set automatically, and are reset to their initial state after this menu has been exited.

IV) Function keys:



Cursor keys for selecting the parameter to be set or measured, i.e. the line containing the parameter. The selected parameter appears in inverse form on the display field.

Ту	pe 2304		
Installation	IV.2)	E : N T E R	Acknowledgement of the current measurement parameter setting and return to the next higher menu level main menu 3).
Operation	IV.3)	μΩ : : kΩ	Completion of the entry of a resistance value for ${\sf R}_{\sf c}$
Parameterization	IV.4)	+ / - F 2	Entry of the sign for the ambient temperature t_1 at the beginning of the load phase and t_2 at the end of the load phase.
Configuration	IV.5)	L-Rem [:] F 3	Entry of the load REM oval (= start of the internal stopclock for the cooling curve); after this key is operated, the cooling curve menu may not be exited until the recording of the cooling curve is complete. Every access to the menu causes the stopclock to be reset.
Calibration	IV.6)	Meas-t F 4	Changeover of the lines 2 (T1) or 5 (T2) to MEAS mode; in each case, only one temperature measurement is performed (the measurement phase is indicated by the inverse display of the MEAS-t field).
Programming	IV.7)	EVAL [:] F 5	Selection of the cooling curve protocol (EVAL uation). After this function key is operated, the table in Fig. 3.31 appears, provided that a cooling curve was recorded previously.
echn. Specifica-		R-RESET : F 1	The key is only indicated if measured values are present in the memory. If it is operated, the memory for measured values is cleared, and the (R-RESET) key is no longer indicated.
 :=	≥_ rage 3 - 3	9 - Q	

l o					
allati		100.20 Ω	1.46 s	1	1
Insta		100.19 Ω	2.46 s	2	2
		100.17 Ω	3.46 s	3	3
c		100.15 Ω	4.46 s	4	4
ratio		100.12 Ω	5.46 s	5	5
Ope					
	RETURN	PRINTER			POS 0

Fig 3.31: Cooling curve protocol

Each of the lines 1 - 5 states a pair of cooling-curve values (measured-value index/time reference in sec. with respect to the load removal/test unit's resistance in Ω); needless to say, this method of registration can also be used as a normal data-logging function.

The cursor key can be used for selecting further lines which are not currently displayed. The five preceding lines are displayed with the \blacktriangle key, while the five succeeding lines (provided that they exist) are displayed with the \checkmark key. With the help of the F1 = POS. key, every pair of measured values whose current index is known can be positioned in line 1. The desired index is simply entered via the numerical keyboard (control display in the F1 field) and the entry completed with F1. The maximum memory depth is 256 pairs of values.

The F4 = PRINTER key allows the stored values to be printed via the RS232 type serial interface, which must be set previously in the interface menu (see Chap. 3.3.4). In addition, IEEE488 must be chosen as part of the interface selection. The return to the "cooling curve" menu is effected via F5 - RETURN.

- V) <u>Parameters:</u>
- V.1) Cold resistance R_c:
- V.1.1) Enter cold resistance R_c manually:

Entries for this menu line are made with the numerical keyboard (see Chap. 2.4.3), including the decimal-point key. For this, the value range 0 $\mu\Omega \leq$ input value $\leq XXXXXX k\Omega$

Configuration

Parameterization

Installation is available. (X = any number or a decimal point. The entry is complete via the unit key (see IV.3). R_c can only be entered manually when the measurement is in the STOP mode. V.1.2) Measurement of the cold resistance R_c: For the cold resistance $\rm R_{c}$ to be measured, the START key must be Operation operated. The resulting measured values are then written over the value entered in accordance with V.1.1). The SINGLE or REPETITION MEASUREMENT MODE can be selected for this purpose. The restrictions stated in Chap. 3.3.3, III should be observed. Ambient temperature (T1 before the load phase, T2 at the end of the load V.2) Parameterization phase): V.2.1) Entries for the menu lines 2 (T1) or 5 (T2) are made with the help of the numerical keyboard (see Chap. 2.4.3) including the decimal-point key. For this, the value range $-99.9 \circ C \leq \text{input value} \leq +999.9 \circ C$ is available. (Sign change via F2 in accordance with IV.4). Configuration V.2.2) Measurement of the ambient temperature: Select menu line 2 (T1) or 5 (T2), operate the MEAS-t key as described in IV.6). Enter the time reference for the cooling curve Δ t: V.3) Calibration Entries for this menu line are made with the numerical keyboard (see Chap. 2.4.3.). For this, the value range $0 s \leq input value \leq 3600 s$ is available. Dt specifies the time interval during which no values are stored. The next pair of values determined after Δ t has elapsed are stored. V.4) Measurement of the resistance R (t) with respect to time: Programming After the restrictions stated in III have been observed, the procedure below is to be followed: Selection of line 4 (inverse display), Operation of the START key, _ Display of the measured values together with the current _ Techn. Specifica-tions & Appendix measured value index. Operation of the STOP key or attainment of the maximum number of measured-value pairs (256). Page 3 - 3 - 10

VI)

Type 2304

Special comments:

The cold resistance R_c (V.1) and ambient temperatures T_1 and T_2 (V.2) are only entered for the purpose of documentation. Further computationa evaluations with R_c , T_1 and T_2 are not carried out.

To increase the measurement rate in the case of small inductances, it might be advisable to switch the measurement cycle from BIPOLAR to UNIPOLAR mode (see Chap. 4.5). In this operating mode, the compensation measurement at I = 0 A is only carried out once after operation of the START key, which saves the time otherwise required for charge reversal.

However, this could result in a considerable deterioration of the measuring accuracy (particularly with small and medium measuring currents) because, as is generally known, the thermal e.m.f's in the measuring circuit change over long cooling periods, thus increasing the measurement errors. As only the BIPOLAR mode compensates the thermal e.m.f's during every measuring cycle, this setting is preferable for small inductances (if possible, in combination with a LARGE measuring current and TIME BASE > 1). In the case of large inductances, correct measured values are only obtained in the UNI-POLAR mode.

VII) Exit:

Via the function key ENTER into "special functions" (main menu 3).

Techn. Specifications & Appendix



Type 2304



and PASSIVE are available.

Туре 2304

Installation

Operation

Parameterization

Configuration

Calibration

Programming

Techn. Specifications & Appendix The list values can be scrolled through with the \triangleleft \triangleright keys. A return to the "interface" menu is effected via the F5 RETURN key.

B)

Interface type = RS485 or RS232 (Line 1 or 2):

RS485 (232):	FULL DUPLEX (only with RS485)
BAUD RATE:	9600
DATA BITS:	8
STOP BITS:	1
PARITY:	NONE
	RETURN

Fig 3.34: Operating modes and data format for the RS232/485

Line 1 states the operating mode and line 2 states the corresponding transfer rate. The desired data format (number of data bits, number of stop bits and parity check) is shown in lines 3 to 5. The individual lines are selected with the \blacktriangle - \forall keys, and subesquently indicated in inverse form. A parameter selected in this manner can be changed as follows:

- Line 1: Serial interface type; for this the list values FULL DUPLEX and HALF DUPLEX are available, provided that type RS485 has been selected. Otherwise line 1 is disabled.
- Line 2: BAUD RATE = rate of data transfer; for this, the list values 19,200, 9,600, 4,800, 2,400, 1,200, 600 bauds are available.
- Line 3: DATA BITS = number of data bits; for this, the list values 7 and 8 are available.

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IV.4)

Li	ìne 4:	STOP BITS = numbe are available.	er of stop bi 1 and 2	its; for this, t	the list values	Installation
Li	ine 5:	PARITY= parity chec For this, the list value are available.	ck desired? es EVEN, C	DD and NC	DNE	ation
T	he list values	can be scrolled throu	ugh with the	e ┥ 🕨 key	/S.	Opera
А	return to the	"interface" menu is e	ffected via	the F5 RET	URN key.	
.4) SW-6	CONF : = 2	Selection of the settir parameters of the set After this function key in Fig. 3.3.5 appears.	ng menu for rial interface / is operate	^r the softwai es (S oft W ar d, the settin	re e CONF iguration). g menu shown	Parameterization
		SW CONFIGURA	TION			guration
G	ROUP ADD	RESS:		0		Confi
U	JSER ADDRE	ESS:		0		
С	HARACTER	DELAY:		OFF		n
B	BLOCK CHEC	Ж:		OFF		librat
					RETURN	Ca
Fig 3.35:	Software pa	arameters for the RS2	232/485			ming
	Line 1 is th addresses character d	1e header, and lines respectively. Lines 4 elay and the block che	2 and 3 s 4 and 5 se eck characte	state the gr erve as sw er. The indiv	oup and user itches for the ridual lines are	Program

addresses respectively. Lines 4 and 5 serve as switches for the character delay and the block check character. The individual lines are selected with the \blacktriangle - \triangledown keys, and subsequently indicated in inverse form. A parameter selected in this manner can be changed as follows:

Page 3 - 3 - 15

Techn. Specifica-tions & Appendix

1

RESISTOMAT® burster

ч						
Illati		Line 2:	GROUP ADDRESS and			
Insta		Line 3:	USER ADDRESS			
			For both lines, the value range			
on			$0 \le input value \le 15$ is available.			
Operat		Line 4:	CHARACTER DELAY= fixed time delay between the transfer of individual characters (approx. 2 ms) and			
eterization		Line 5:	BLOCK CHECK = check sum of the transferred data block. For both lines, the list values OFF and ON are available.			
Param		The list values "interface" me	s can be scrolled through with the $\triangleleft \triangleright$ keys. A return to the nu is effected via the F5 RETURN key.			
ion						
Jurat	V)	Paramete	ers:			
Confi	V.1)	RS485: Selection of tl (≤ 32 connect	he bus-compatible serial interfaces type RS 485 ted measuring devices).			
ы	V 2)	BS232:				
alibratio	• • • • •	Selection of the state of the selection	he bus-incompatible serial interface type RS 232 tion with only one connected measuring device).			
Ö	V.3)	IEEE488:				
ğ		Selection of the (1 control state)	tion with \leq 30 connected measuring devices).			
mmi	VI)	Special c	omments:			
Progra		Selection of t the RS232 in Fig. 3.34 The	he parameter V.3) IEEE 488 also allows printer operation via terface jack. The underlying parameters for this are shown in a format of the printed data is shown in Fig. 3.37			
ica- idix		ng. 0.04. me	e format of the printed data is shown in Fig. 3.37.			
vpperit	VII) i	Exit:				
Via the function key ENTER into "special functions" (main menu 3)						
ouo	Page 3 - 3 - 16					



nstallation

Paramete

Configuration

Calibration

Printer parameters (PRINTER)

				House and
PRINT:	OFF	TC:	OFF	
TYPE:	Т 0	TEST NO .:	OFF	Ę
NUMERATOR:	ON	TEST NO.:		ratio
DATE:	ON	MV/HEAD.:	1000	Opel
TIME:	ON			
TIME REF.:	hh : mm : ss			lion
 			RESNUM	izai

Fig. 3.36: Printer parameters

I) Access:

Via F4 = PRINTER within "special functions" (main menu 3).

II) Function:

Setting of the printer parameters and stipulation of the desired printer listing (see Fig. 3.37).

III) Restrictions:

The format settings only apply for the IBM character set 2 (see Appendix 7.5). They were tested, for example, on an "NEC Pinwriter P6 plus" printer. TYPE 0 requires 8 data bits. The TYPE 1 and TYPE 2 settings replace the " Ω " symbol with "O", the " μ " symbol with "u" and the "°" symbol with a space.

IV) Function keys:

IV.1)
 Cursor keys for selecting the printer parameter to be set,
 i.e. the line containing the desired parameter. The selected
 line is indicated in the display field in inverse form.

Techn. Specifications & Appendix

RESISTOMAT® burster



Page 3 - 3 - 18

burster RESISTOMAT®

		_
V.2)	TYPE = printer type: The following list values are available: T 0 : DIN A4 printer (80 characters/line), T 1 : 40 character protocol printer,	Installation
V.3)	T 2 : 20 character protocol printer. NUMERATOR = current counter index for the measured-value lines to be printed out: The following list values are available: OFF = the numerator is not printed, ON = the numerator is not printed,	tion Operation
V.4)	DATE = on/off switch for the date: The following list values are available:	Parameterizat
V.6)	 OFF = the time is not printed, ON = the time is also printed in every measured-value line. TIME REF. = time reference for the printout of the measured-value 	Configuration
	lines: After the entry field (hr., min., sec.) is selected with the ◀ ► keys, the value of the time reference (= minimum waiting time between two measured-value lines) is entered via the numerical keyboard (see Chap. 2.4.3). For this, the value ranges 0-24 hrs., 0-59 min. and 0-59 sec. are available.	Calibration
V.7)	TC = on/off switch for the temperature of the test unit in the case of temperature compensation:	Programming
	Paαe 3 - 3 - 19	Techn. Specifica- tions & Appendix

RESISTOMAT®

Installation The following list values are available: , OFF = the temperature of the test unit is not printed out, ON = the temperature of the test unit is printed out, provided that the temperature compensation has been activated (see Chap. 3.2.2, V.1). Operation V.8) TEST NO. (2nd column, 2nd line) = on/off switch for a test number or experimental number sepcified by the customer: The following list values are available: Parameterization OFF = the test number (see V.8) is not printed out, = the test number is printed out in the 1st line of the ON protocol header (see V.9) V.9) TEST NO. (2nd column, 3rd line) = input line for the test number: Configuration The test number is input via the numerical keyboard (see Chap. 2.4.3). For this, the value range $0 \leq \text{input value} \leq 999999$ is available. MV/HEAD. = measured-value line reference up until a new protocol V.10) Calibration header is printed: It is possible to print a protocol header before a certain number of measured-value lines; it contains the following information (also see Fig. 3.37): Line 1: Test number (see V.7, 8) Programming Line 2: Temperature coefficient, provided that the temperature compensation (see Chap. 3.2.2, V.1) and the TC switch (see V.6) have been activated. Specified value on which the comparator limiting Line 3: values are based as percentages (see Chap. 3.2.3, Techn. Specifica-tions & Appendix IV.4), provided that the comparator function (see Chap. 3.2.3, V.1) has been activated.



- Lines 4-11: Comparator or classification limiting values (lower and upper limiting value for COMPARATOR TYPE = simple comparator or limiting values 1-7 for COMPARATOR TYPE = classification comparator with nine classes), provided that the comparator function (see Chap. 3.2.3, V.1) has been activated.
- Last line: Headers for the protocol columns 1 to 6. Columns which are not selected are omitted and indented.

The entry of the number of measured-value lines until the next protocol header is carried out via the numerical keyboard (see Chap. 2.4.3). For this, the value range

 $1 \leq \text{input value} \leq 9999$

is available.

VI) Special comments:

The menu for the printer parameters is only accessible from main menu 3, if the interface type IEEE488 was previoulsy selected. It is only in this operating mode that the RS232 interface connector is not assigned to a control station for communication tasks and thus available for printer control.

VII)

Exit:

Via the function key ENTER into "special functions" (main menu 3).

Techn. S tions & /

RESISTOMAT® burster

Installation **TEST NUMBER :** 1245 0.003980 TEMP. COEFFICIENT: $\Omega * mm2/m$ 100 SPEC VAL .: 101.000 Ω*mm2/m LIM VALUE 0 : **PROTOCOL HEADER** LIM VALUE 1: 102.000 Ω*mm2/m 103.000 Ω*mm2/m LIM VALUE 2 : 104.000 Ω*mm2/m Operation LIM VALUE 3 : 105.000 Ω*mm2/m LIM VALUE 4 : 106.000 Ω*mm2/m LIM VALUE 5 : LIM VALUE 6 : 106.999 Ω*mm2/m 108.000 Ω*mm2/m LIM VALUE 7 : VALUE EVAL. MEASURED-POS MEAURED TIME TEMPERATURE DATE °C 17.12.90 101.39 Ωmm2/m 2 10:42:03 21.6 1 VALUE Parameterization 101.40 Ωmm2/m 2 10:42:04 17.12.90 °C 2 21.6 3 101.41 Ωmm2/m 2 10:42:05 17.12.90 21.5 °C LINES °C 101.33 Ωmm2/m 2 10:42:06 17.12.90 21.5 4 5 101.35 Ωmm2/m 2 10:42:07 17.12.90 21.5 °C °C 6 101.32 Ωmm2/m 2 10:42:08 17.12.90 21.6 7 101.40 Ωmm2/m 2 10:42:09 17.12.90 21.6 °C 10:42:10 17.12.90 °C 8 101.32 **Ωmm2/m** 2 21.6 ۸ Comparator or classivication evalutation (<=> or <1 ... 7>), Numerator is only pronted out when COMPARATOR = ON Configuration (Chap. 3.2.3, V.1). TEST NUMBER : 1245 TEMP. COEFFICIENT: 0.003980 SPEC VAL .: 100 $\Omega * mm2/m$ Calibration LIM VALUE 0 : 101.000 Ω*mm2/m LIM VALUE 1 : 102.000 Ω*mm2/m LIM VALUE 2 : 103.000 Ω*mm2/m LIM VALUE 3 : 104.000 Ω*mm2/m LIM VALUE 4 : 105.000 Ω*mm2/m LIM VALUE 5 : 106.000 Ω*mm2/m LIM VALUE 6 : 106.999 Ω*mm2/m LIM VALUE 7 : 108.000 Ω*mm2/m Programming MEAURED VALUE POS EVAL. TIME DATE TEMPERATURE ်င 9 101.94 Ωmm2/m 2 10:42:11 17.12.90 21.5 101.33 Ωmm2/m 10 2 10:42:12 17.12.90 21.5 °C 101.35 Ωmm2/m 11 2 10:42:13 17.12.90 21.5 °C 12 101.34 Ωmm2/m 2 10:42:14 °C 17.12.90 21.7 13 °C 101.28 Ωmm2/m 2 10:42:15 17.12.90 21.7 14 101.27 Ωmm2/m 2 10:42:16 17.12.90 21.7 °C 15 $101.26 \Omega mm^2/m^2$ 10:42:17 17.12.90 21.8 °C Techn. Specifica-tions & Appendix Fig. 3.37: Format of the measurement protocol for TYPE 0, 1 and 2

Page 3 - 3 - 22



Installation Table of contents, Chapters 4-1 to 4-8 Operation Configuring the **RESISTOMAT®2304** Parameterization Configuration Keyboard access 4-2-1 Mains frequency 4-3-1 Measurement sequence...... 4-5-1 Calibration Potential fixing 4-7-1 Basic settings 4-8-1

Page 4 - 1 -1

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Operation of the RESISTOMAT [®] 2304	Installation
Configuration	Operation
General information	leterization
Configuration and calibration functions influence the fundamental characteristics of the device; for this reason, they are only accessible through special security codes (see Fig. 4.1).	Paran
The access procedure from any of the three main menus is as follows:	Iration
RGE N1 N2 N3 N4	Configu
, The SEL light-emitting diode remains on until the entry of the last number N4 has been completed. The return from the configuration menu into the calling main menu is effected with the	Calibration
ENTER key.	ling
	Programm
Page $A = 1 - 2$	Techn. Specifica- tions & Appendix

RESISTOMAT® burster





Installation	Keyboard access
ameterization Operation	KEYBOARD ACCESS MEASUREMENT MEASUREMENT + RANGE SELECT. FULL ACCESS
Configuration Par	Fig. 4.1: Keyboard access IMPORTANTE NOTE:
g Calibration	Fig. 4.2 shows all the security for selecting the configuration and calibration menus. An unqualified operaator familiar with these codes would posses the capability of altering the fundamental functions of the measuring device, thus rendering the displayed values useless. Consequently, this sheet should be separated before the device is put
Programmin	into operation, an kept in the custody of a responsible person. The guarantee does cover malfunctions resulting from improper configuration or calibration.
Techn. Specifica- tions & Appendix	Page 4 - 2 -2

RESISTOMAT® nurste











RESISTOMAT®



ç		
Ilatio	V)	Parameters:
Insta	V.1)	50 Hz:
ation		Matching of the internal integrating time with the interference frequency of 50 Hz. All statements of the measurement time (TIME BASE) are based on multiples of 20 ms (1/50 Hz).
Opei	V.2)	60 Hz:
eterization		Matching of the internal integrating time with the interference frequency of 60 Hz. All statements of the measurement time (TIME BASE) are based on multiples of 16.67 ms (1/60 Hz).
Param	V.3)	16 2/3 Hz:
Configuration		Matching of the internal integrating time with the interference frequency of 16 2/3 Hz. All statements of the measurement time (TIME BASE) are based on multiples of 60 ms (1/16 2/3 Hz).
tion	VI)	Special comments:
Calibra		There are no value lists for the individual lines V.1) - V.3); the parameters are selected simply by positioning the inversely inticated cursor on the desired line and acknowledging with ENTER.
Programming	VII)	<u>E x i t</u> : Via the function key ENITER into the main menu which was exited
Techn. Specifica- tions & Appendix	Page 4 - 3 - 2	previously.

burster RESISTOMAT®

[Clo	ck	stallation
DAT TIM	E: E:	25.02.91 08:29:10	eration
VEF	RSION:	V0193	zation Ope
Fig. 4.6:	Setting menu for the version used.	e date and time, and display of the software	Parameteri
I)	<u>A c c e s s:</u> Via SEL < security o main menus.	code as in Fig. 4.1 > within one of the three	Configuration
11)	<u>Function</u> : Input of the date an used. Bestrictions:	d time, and display of the software version	Calibration
IV)	None. Function keys	<u>S:</u>	ogramming
IV.1)		Cursor keys for selecting the parameter to be set, i.e. the line containing the parameter. The selected parameter is shown on the display field in inverse form.	chn. Specifica- ns & Appendix

RESISTOMAT®



Installation	IV.1)	 Cursor keys for positioning the cursor field on the entry fields Day Month Year and Hr.:Min.:Sec.
Operation	IV.2)	E N:Acknowledgement of the current parameter settings and return to the next higher menu level.E R
configuration Parameterization	V) V.1)	P a r a m e t e r s: DATE: After the entry field (day,month,year) has been selected with the ◀ - ▶ - keys, the desired value is entered via the numerical keyboard (see Chap. 2.4.3). For this, the value ranges 00-31.00-12.00-99 are available.
Calibration	V.2)	 TIME: After the entry field (hr., min., sec.) has been selected with the ◀ - ▶ - keys, the desired value is entered with the numerical keyboard (see Chap. 2.4.3). For this, the value ranges 00-23 : 00-59 : 00-59 are available.
Programming	VI)	<u>Special comments:</u> The clock and date "remain stationary" during the time of the display, i.e. the counter stops running.
Techn. Specifica- tions & Appendix	VII)	$\underline{E \times i t}$: Via the function key ENTER into the main menu which was previously exited.
	1 ayo 4 - 4 - 2	



Installation Measurement sequence Operation MEAS. SEQUENCE: **BIPOLAR** Parameterization Fig.4.7: Measurement sequence $|\rangle$ Access: Configuration Via SEL < security code as in Fig.4.1 > within one of the three main menus. II) Function: Determination of whether the measurement should be unipolar or bipolar. Calibration $|||\rangle$ **Restrictions:** None. IV) Function keys: Programming (V,1): Cursor keys for scrolling through the value list available for the selected parameter. When the key is pressed, the next list value appears; when the *key* is pressed, the previous list value appears. Techn. Specifica-tions & Appendix IV.2) Е Acknowledgement of the current parameter : Ν setting and return to the next higher menu Т level. Ε R

V)	<u>Parameters:</u>
V.1)	MEASUREMENT SEQUENCE: For this, the list values UNIPOLAR, BIPOLAR and CONSTANT are available. In the UNIPOLAR mode, the measuring current through the test unit is switched once between I = 0A and I = +I _{Meas} , i.e. no change in polarity occurs.
	In the BIPOLAR mode, however, the sign of the measuring current changes cyclically, i.e. it is switched between $I = -I_{Meas}$ and $I = +I_{Meas}$.
	In the CONSTANT mode it'll measure immediately with switched on measure current. This measure mode is only possible at manual range selection. Before it is necessary to make a reference zero-measurement.
VI)	 Special comments: In the UNIPOLAR mode, the compensation measurement is carried out at I = 0A (see chap. 1.6) only once after the operation of the START key. This has the following advantages: the measurement time is shortened and the time required for charge reversal on inductive test units is saved. However, this is accompanied by the following disadvantages: a decrease in the measuring accuracy, (particularly with low and medium measuring currents), as thermal e.m.f's are not compensated.
	Only the BIPOLAR mode compensates thermal e.m.f's during every measurement cycle; for this reason, it is advisable to use this mode in case of doubt (if possible, in combination with a LARGE measuring current and TIME BASE $>$ 1).
	The measure mode CONSTANT is for big inductivities with stability effects -to stabilise the measure values- > 5 minutes. In this case the discharge time is approx. the same. Sometimes a discharged test object has nevertheless a little residual charge, which in a new measurement in the UNIPOLAR mode results in a wrong value because the residual charge is stored as the zero point. For all measurements in this mode the test object must be total discharged and the REFØ-value must be measured new (see page 3 - 1 - 8). The difference to the mode UNIPOLAR is, that the measurement happens immediately after having switched on the measure current without zero point measurement
	Please choose the biggest measure current in the used range (only manual range selection possible).
VII)	$\underline{Exit:}$ Via the function key ENTER into the main menu exited previously.

Operation Installation

Parameterization

Programming

Techn. Specifications & Appendix

Seite 4 - 5 - 2



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Rele	ase	thres hold for inductive test units	Installation
	REL.	THRESHOLD: 20.00 %	Operation
			Parameterization
Fig. 4.8:	Release I	threshold for inductive test units	E
	1)	<u>A c c e s s:</u> Via SEL < security code as in Fig. 4.1 > within one of the three main menus.	Configuratio
	11)	<u>F u n c t i o n</u> : Setting of the ripple limiting value, which must not be exceeded during the transient phase of inductive test units, so that valid measured values can be obtained.	Calibration
	III)	<u>Restrictions:</u> None.	
	IV) IV.1)	Function keys: E : Acknowledgement of the current	Programming
		N T E R Page 4 - 6 1	Techn. Specifica- tions & Appendix

Installation

Operation

Parameterization

Configuration

Calibration

Programming

Techn. Specifications & Appendix

VII)

RESISTOMAT[®]

burster



V.1) RELEASE THRESHOLD:

As shown in Fig. 4.9, this parameter specifies the maximum acceptable change in transient amplitudes between two consecutive measured values after the transition from I= 0A to I= $+I_{Meas}$ in UNIPOLAR operating mode involving inductive test units.



The entry of the release threshold as a percentage of the measur

The entry of the release threshold as a percentage of the measuring current I+ is made via the numerical keyboard (see Chap. 2.4.3). For this, the value range

 $0.05\% \le$ input value $\le 20.00\%$ is available.

VI) Special comments:

It is only when the amplitude difference between two consecutive measurements is determined to be smaller or equal to the release threshold after the START of a UNIPOLAR measurement that the subsequent measured values are released for display. The measurement itself is not influenced (or made quicker) by this!

Exit:

Via the function key ENTER into the main menu which was previously exited.

Page 4 - 6 - 2



Potential fixing

POTENTIAL FIXING

MEAS. UNIT:

INTERN. GROUNDED

Fig. 4.7: Potential fixing

GROUNDED	eterization
Potential fixing	arame
I) $\frac{A c c e s s}{Via SEL < security code as in Fig. 4.1 > within one of the three main menus.$	iguration
 II) <u>F u n c t i o n</u>: Determination of whether the test unit is externally grounded or should be grounded internally. 	Sent
III) <u>Restrictions:</u> None.	Calibration
IV.1) : Cursor keys for scrolling through the value list available for the selected parameter. When the ▶ key is pressed, the next list value appears; when the ◀ key is pressed previous list value appears.	Programming
IV.2) E : Acknowledgement of the current parameter N T setting and return to the next higher menu level. Page 4 - 7 -1	Techn. Specifica- tions & Appendix

Type 2304

Installation

Operation







1).

Type 2304

Installation

Operation

Parameterization

Configuration

Basic settings

RESISTOMAT[®]

burster präzisionsmeßtechnik

Fig. 4.11: Activate basic settings

- <u>Access:</u> Via SEL < security code as in Fig. 4.1 > within one of the three main menus.
- II) <u>F u n c t i o n</u>: Selection of the basic parameter settings (see Chap. 7.4).
- III)Restrictions:
This function can only be used after operation of the STOP key (the
STOP LED is lit).
- IV) Function keys: None.
- V) <u>Parameters</u>: After the entry of the 4th numbr N4 of the security code for activating the basic settings, the required procedure is commenced automatically, and the message shown in Fig. 4.11 appears on the display, with the 3rd line flashing. The procedure itself lasts only a few seconds. After it is completed, the calling main menu is displayed again.
- VI) <u>Special comments:</u> The calibration values (see Chap. 5) and the access monitoring (see Chap. 3.3.2) are not overwritten!
- VII) $\underbrace{E \times i t:}_{Automatically into main menu 1 after completion of the procedure.}$

Calibration

Programming

Techn. Specifications & Appendix

Table of contents, Chapter 5-1 to 5.5

Calibration of the

RESISTOMAT® 2304

General information	5-1-2
Offset calibration	5-2-1
Calibration	5-3-1
Reference values	5-4-1
Pt100 calibratio	5-5-1
Pt100 coefficients	5-5-3





Operation of the RESISTOMAT®2304

Calibration

Generalinformation

Calibration functions (see Fig. 5.1) influence the basic characteristics of the device; for this reason, they are only accesible via special security (see Fig. 4.2). The access procedure from any one of the three main menus is as follows:



The SEL light-emitting diode remains lit until the entry of the last number 4 has been completed.

The return from the calibration menu into the calling main menu is effected via the ENTER key. Only the submenu (execution) for calibration (selection) can be exited solely via the F5 RETURN key.

Page 5 - 1 - 2

RESISTOMAT[®] burster







Techn. Specifications & Appendix Installation

Operation

Parameterization

Configuration

Calibration

Programming

II) <u>Function:</u>

Start and execution of the offset adjustment of the measuring amplifier.

III) <u>Restrictions:</u>

The adjustment is only possible after operation of the STOP key (the STOP LED is lit).

IV) <u>Function keys:</u>

None.

- V) <u>Parameters:</u>
- V.1) OFFSET ADJUSTMENT ACTIVE:

Before entering the security code, any resistor with less than 1 Ω has to be connected.

After the 4th number of the security code for offset adjustment has been entered, the adjustment is started automatically through a relay-switching procedure, and the message shown in Fig. 5.2 appears on the display.

The adjustment procedure itself can last between 5 s and 60 s depending on its starting values. It is completed through a second relay-switching procedure, after which the calling main menu appears again on the display.

VI) Special comments:

The zero point adjustment must be performed after every repair; during normal operation, however, a maximum of one adjustment per month is recommended.

If high gain, i.e. low measuring currents and/or small measurement ranges are used preferentially during operation, more frequent adjustment could be required. Finally, the occurence of the error message ACOV (see chap. 7.3) could indicate that a zero point adjustment is necessary.

VII) <u>Exit:</u>

Automatically into the previously exited main menu after completion of the adjustment.
burster RESISTOMAT®

Type 2304

			Са	libr	ation	•	1			Installation
			C A	A L I E	3 R.					
n e e e e e e e e e e e e e e e e e e e	200 2 20	μΩ mΩ mΩ	25.02.91 25.02.91 25.02.91		20 200 2	Ω Ω kΩ	25 25 25	.02.91 .02.91 .02.91		Operation
			25.02.91			KS2	25	CAL		ameterization
Fig	g. 4.5:	Keyboard	access							Para
97.		I) II)	<u>A c c e s s:</u> Via SEL <s main menus <u>F u n c t i o</u> Selection of</s 	security s. <u>n :</u> the resi	code as in Fig stance measur	. 4.1 >v ement r	vithin	one of the thre	e	Configuration
		III) IV)	<u>Restrict</u> None. <u>Functio</u>	tions: n key:	<u>s:</u>			,		Calibration
		IV.1)]:	Cursor keys t be set, i.e. the The selected field in invers	for selec line con parame e form.	cting f ntainii eter is	the parameter t ng the paramete s shown on the	o er.	Programming
		IV.2)	E N T E R	:	Acknowledge setting and re level.	ement o eturn to	f the c the r	current paramet next higher mer	er 1u	echn. Specifica- ons & Appendix

RESISTOMAT® burster



Fig. 5.4 : Calibration procedure

Line 1 states the selected measuring range, line 2 states the date of the last calibration for this measuring range. Line 3 contains the value of the calibration resistance R_{ext} which is to be externally connected; before every calibration procedure, this value must be entered via the numerical keyboard (see Chap. 2.4.3) and the entry completed with one of the measurement range keys (see Chap. 2.4). The calibration procedure for the previously selected measurement range is as follows:

- a) Connection of the external calibration resistance R_{ext} (see VI).
- b) Entry of the resistance value of R_{ext} . The entry must be completed with the unit key corresponding to the selected range. If the stated value of R_{ext} lies outside the permissible range, the error message R_{ext} ? appears. A new entry must then be made.
- c) CAL-F1: Start of the calibration procedure.
- d) Check message: "CALIBR:: ACTIVE".

Page 5 - 3 - 2

Calibration

Programming

Techn. Specifications & Appendix burster RESISTOMAT®

Installation

Operation

Parameterization

- e) Return to the next highest measurement range as shown in Fig. 5.4 (exception: $20k\Omega$). If R_{ext} is not suitable for calibration of the selected range, i.e. if it lies far beyond the order of magnitude of the reference resistances (see Fig. 5.5), the error message R_{int} ? occurs. The calibration is then aborted.
- V) Parameters:
- V.1) -V.9)
- < measuring range> : < Day.Month.Year>

Every line contains one of the nine measuring ranges and the date of its last calibration. The measuring-range lines can also be used for selecting the corresponding calibration procedure (see Fig. 5.4). If all the measurement ranges need to be recalibrated, it is advisable to start in line 1 (200 $\mu\Omega$ range).

VI)

Special comments:

The device only adheres to its specified fault-tolerance limits if the externally connected calibration resistances remain within the following limits (taking into account the influences of self-heating and the ambient temperature):

Measuring range	R _{Cal} Rated value of R _{Cal}	Uncertainty of the actual value	at measuring current	
20 kΩ	10 kΩ	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	100 μA	
2 kΩ	1 kΩ		1 mA	
200 Ω	100 Ω		10 mA	
20 Ω	10 Ω		100 mA	
2 Ω	1 Ω		100 mA	
200 mΩ	100 mΩ		1 A	
20 mΩ	10 mΩ		1 A	
20 mΩ	10 mΩ		1 A	
20 mΩ	10 mΩ		10 A	
200 μΩ	10 mΩ		10 A	

After a calibration has been carried out, it is advisable to measure the external calibration resistance once again in the normal measuring mode, and check whether the display of its (previously entered) resistance value is correct. If a discrepancy is established, the calibration should be repeated.

- VII)
- <u>Exit:</u>

Via the function key ENTER into the previously exited main menu.



Reference values

200 μΩ:100.00000	μΩ	20 Ω:10.00000	Ω
2 mΩ: 1.00000	mΩ	200 Ω:100.00000	Ω
20 mΩ:10.00000	mΩ	2 kΩ:1.00000	kΩ
200 mΩ:100.00000	mΩ	20 kΩ:10.00000	kΩ
2 Ω: 1.00000	Ω	Pt100:180.00000	Ω

Fig. 5.5: Reference values

I) Access:

Via SEL < security code as in Fig. 4.1 >within one of the three main menus.

II) Function:

Display of the internally determined reference resistance values.

III) Restrictions:

None.

IV) Function keys:

None.

Installation Operation Parameterization Configuration Calibration Programming Techn. Specifica-tions & Appendix

Installation

Operation

Parameterization

Configuration

Calibration

Programming

Techn. Specifications & Appendix Parameters:

< measuring range> : < internal reference resistance>

V.1) -V.10)

V)

Lines 1 to 9 contain the 9 measuring ranges, and line 10 displays the temperature-measurement channel for temperature compensation of the test unit. Every measurement range has a reference resistance assigned to it whose value lies approximately in the middle of its scale (\pm 10%). This resistance value is re-determined after every scaling factor calibration (see Chap. 5.3) and entered in the table shown in Fig. 5.5.

VI) Special comments:

The display of the reference resistance values serves as a plausibility check for the calibration (see Chap. 5.3). For example, if a sequence of several consecutive calibrations of a measurement range is analysed, only small deviations between the reference values should emerge, whereby the absolute values are of minor significance. Otherwise the following errors could exist:

- incorrect entry of the value of the calibration resistance R_{ext} to be connected externally,
- R_{ext} is unstable,
- the internal calibration resistance R_{ref} is unstable.

Upon return to the factory presettings (see Chap 4.8), the calibration values are not overwritten!

VII) Exit:

Via the function key ENTER into the previously exited main menu.

Page 5 - 4 - 2

Type 2304



Туре	2304	RESISTOMAT [®] burster
Installation	IV.2)	CAL : Start of the calibration procedure (CAL (CAL ibration).
ation		F 1
Oper	V)	Parameters:
Ŭ	V.1)	CALIBRATION Pt100:
rization		Only display of the Pt 100 channel to be calibrated.
mete	V.2)	Day . Month . Year:
Paral		Date of the last calibration of the temperature measurement channel.
<u> </u>	V.3)	$R_{ext} = 100\Omega$:
Configuratio		Entry of the value of the calibration resistance to be connected externally; this value must be entered via the numerical keyboard (see Chap. 2.4) before every calibration, and the entry completed with the measurement-range keys (see Chap. 2.4).
Calibration	VI)	Special comments: uncertainty $\leq 5 \cdot 10^{-5}$ at 1 mA.
		R _{ext}
Programming	VII)	E x i t: ——— Via the function ENTER into the previously exites main menu.
chn. Specifica- ns & Appendix		

Page 5 - 5 - 2

Installation

Operation

Pt100 - coefficients

R_{o}		100
А	=	3.9083 e ³
В		-5.775 e ⁻⁷
С	5	-4.183 e ⁻¹²
t ₁₀₀		100

Fig. 5.7: Pt100-coeffizients

I) Access:

Via SEL < security code as in Fig. 4.1 > (page 4-1-3) within one of the three main menus.

II) <u>Function:</u>

Display of the actual Pt100-coefficients. The default values ex work are the above mentioned cofficients. The calculation of the temperature ensue the following formula:

 $\begin{array}{cccc} - \ 200 \ ^{\circ}C \ to \quad 0 \ ^{\circ}C \quad R_{t} = R_{0} \cdot [1 + A \cdot t + B \cdot t^{2} + C \cdot (t - t_{100}) \cdot t^{3}] \\ 0 \ ^{\circ}C \ to \ 850 \ ^{\circ}C \quad R_{t} = R_{0} \cdot (1 + A \cdot t + B \cdot t^{2}) \end{array}$

III) Restrictions:

Variations of the coefficients are only possible via interface. s. page 6-3-31 Commande: SCALe:Pt100

IV) Exit:

Via the function ENTER into the previously exites main menu.





Table of contents, chapter 6	Installation
External interfaces of the RESISTOMAT [®] 2304	Operation
RESISTOMAT [®] 2304 command language	ation
RESISTOMAT®2304 command lis	neteriz
HP-IB command list	Paran
Sample program for controlling the RESISTOMAT [®] 2304 via the RS232 interface	Configuration
	Calibration

Techn. Specifications & Appendix Programming Calibration



Installation

Table of contents, chapter 6 - 1

External interfaces of the RESISTOMAT®2304

Introduction	6-1-2
Remote/Local changeover	6-1-2
Control via IEEE488	6-1-2
Setting device addresses Input/output commands Sending a command Receiving the data of the Res2304 Remote/Local	6-1-2 6-1-3 6-1-3 6-1-3 6-1-4
Control via serial interface	6-1-5
Introduction Settings in the serial interface menu Description of the communications protocol for connection set-up RESISTOMAT as master RESISTOMAT als slave Connection termination Description of the data transfer protocol according to ANSI X3.28 Subcat A3/A4 Timer functions according to ANSI X3.28 Flow diagram of connection set-up according to ANSI X3.28 Sub2.5,A3/A4	6-1-5 6-1-5 6-1-6 6-1-7 6-1-7 6-1-9 6-1-9 6-1-10 6-1-11



External interfaces of the RESISTOMAT®2304

Introduction

The **RESISTOMAT** [®]**2304** (called Res2304 in the following) has two external interfaces via which it can be controlled; one IEC bus interface and one serial interface, which can be configured as an RS232 or RS485 interface. All functions selectable via the front panel keyboard can also be configured via these interfaces. The only exception here is the function for selecting the interface via which the device is to be controlled. The command language for controlling the device is version 1990.0 of **SCPI** (Standard Commands for Programmable Instrumentation) agreed upon by leading manufacturers of measuring devices.

Remote/local change

The Res2304 must be in the remote state if it is to be controlled via an external interface. The remote state is indicated on the display by the fact that the function key F5 is shown as a local key. Except for the F5 key (change to front panel operation), all other keys on the front panel are inhibited until the device is switched back to the local state (F5 is pressed).

Control via GPIB

If the device is to be controlled via the GPIB bus interface, the IEEE488 setting must be selected in the interface menu.

Selecting the device address

The device address of the Res2304 for control via the GPIB is selected in the IEEE488 interface menu. The address can be selected from a range between 0 and 30. Address 9 is preset and used in all the examples. Every device connected to the IEEE488 must have its own address. After an address has been changed on the front panel or via the interface, the new address immediately beomes active, and from then on, the device must be activated under this new address.

Туре 2304

RESISTOMAT® burster

Installation	Input/output commands	If the Res2304 is to be controlled by an GPIB controller, its input/output commands must be known. The syntax of the commands is stated in the operating manuals of the individual IEEE488 interface controllers. For example, the input/output commands of the HP series 200/300 in Basic language are:
Operation		OUTPUT and ENTER. If a National PC GPIB board is used, these commands are: IBWRT und IBRD.
Parameterization	Sending a command	The examples in this manual are written in HP Basic. If a command is to be sent to the Res2304, the output command of the GPIB interface must be combined with the SCPI of the Res2304. To set the display contrast, for example, the following is sent
Configuration		1. in HP Basic: OUTPUT 709;":DISPLAY:CONTRAST 0.5" Output command HP-IB Select Code + device
Calibration		address 2. with National: IBWRT ":DISPLAY:CONTRAST 0.5\n"
Techn. Specifica- tions & Appendix	Receiving the data of the Res2304	Output commandSCPI commandLine Feed as com- mand terminatorThe Res2304 returns data requested by an SCPI query. For example, in response to the questionOUTPUT 709;":DISP:CONT?"OUTPUT 709;":DISP:CONT?"the Res2304 writes the current setting of the display contrast into its output buffer. This response can then be fetched using the input command of the GPIB interface.

Page 6 - 1 - 3

Installation

Operation

For example, the following program in HP Basic fetches the response from the device and writes it on the screen:

10 ENTER 709;cont\$ 20 PRINT cont\$ 30 END

With national, the input command is:

IBRD < number of bytes > .

Remote/local

On receiving a command addressed to it, the Res2304 switches over into the remote state. The remote state is indicated by the LOCAL designation for function key F5. In this state, all keys except for the local key (F5) are inhibited.

The change to local operation is made by pressing the Local key or sending the IEEE488.1 Go-to-local command.

If the IEEE488.1 Local Lockout command is sent, the Res2304 can only be switched back to local operation by the Go-to-local command, as the local key is also inhibited then.

Calibration Configuration Parameterization



Тур	e 2304	RESISTOMAT [®] burster
nstallation		Control via serial interface
Operation	Introduction	Control via the serial interface can be performed using the RS232 or the RS485. The type of interface can be set in the interface menu. The ANSI standard serves as the communication protocol between the system controller and the Res2304: ANSI X3.28-1976 Subcategory 2.5, A3/A4
Parameterization	Settings in the serial inter- face menu	Hardware settings The hardware settings of the Res2304 and the system controller must correspond in order to allow proper communication. Baud rate
Configuration		The baud rate is adjustable in steps from 60019200 bits/sec Data bits 7 oder 8 Stop bits
Calibration		1 or 2 Parity even, odd or none
Programming		Type of connection (only for RS485) full duplex or half duplex
Techn. Specifica- tions & Appendix	Page 6 - 1 - 5	

Page 6 - 1 - 5

Software settings

Group address

The group address at which the Res2304 can be addressed: 0..15(0...f)

User address

The user address at which the Res2304 can be addressed: 0..15(0..f)

Character delay

Turn on delay time (approx. 1-1.5ms) between two transmitted bytes.

Block check

With the block check = ON, transfer is effected in accordance with the ANSI standard X3.28 Subcat.2.5,A4. The BCC is sent after <ETX>. It is formed from all bytes which follow <STX>, including <ETX>. The BCC is an "Exclusive-Or" combination of these bytes.

Description of the communications protocol for connection set-up

General description

The ANSI standard X3.28 Subc. 2.5 is used for systems in which several subordinate stations are present in a non-connected multi-point connection, and all commands are sent from a control station. On the bus, only a transmitter (master) and receiver (slave) are active at any time.

One of the stations is a control station. It receives master status and sends commands to a selected slave station or transfers its master status to a subordinate station, assuming the slave status itself in order to receive data. A link between two subordinate stations is not permissible. The control station monitors the connection constantly.

Connection set-up

Before a connection is set-up, the control station posseses master status, and none of the subordinate stations possesses slave status. The control station can either

(1) poll, in order to deliver the master status to a subordinate station

or

(2) specify a slave station in order to establish a connection





RESISTOMAT® burster

u	Resistomat	Polling
Installati	as master	The control station sends a "Polling Supervisory Sequence". This sequence is meant to fetch requested data from the Res2304. The prefix selects a single station. <enq> defines the end of the "Polling Supervisory Sequence". The polling supervisory sequence of the Res2304 has the following format:</enq>
Operation		<groupadr><groupadr><useradr><useradr>po<enq> group address (in hex) user address (in hex) set in selected in the interface the interface menu menu "p"und"o"</enq></useradr></useradr></groupadr></groupadr>
Parameterization		Prefix Example: selected group address 10 selected user address 11 Polling Supervisory Sequence: aabbpo <enq></enq>
Configuration		 A subordinate station which recognizes its polling supervisory sequence responds in one of two ways: (1) When the station has to send data, it starts transmission. The control station assumes the slave status.
Calibration		 (2) When the station does not have to send anything, it transmits <eot>, which ends its master status. The master status returns to the control station.</eot> If the control station receives no reponse, or an invalid one, it terminates the connection by sending <eot>.</eot>
hn. Specifica- Programming	Resistomat as slave	Selection with Response The control station sends a "Selection Supervisory Sequence". This sequence initializes the Res2304 as a slave so that the control station can subsequently transmit SCPI commands to it. The prefix selects a singlestation. <enq> defines the end of the selection supervisory sequence.</enq>
Tec	Page 6 - 1 - 7	



	Connection termination	Termination The master station sends <eot> in order to indicate that it does not have any further data to transfer. <eot> gives the master status back to the control station.</eot></eot>
Operation	Description of the data trans- fer protocol	After the connection is set-up in accordance with the specifications of the ANSI X3.28 Subcat. 2.5 Protocol, the data is transferred in accordance with the specifications of Subcat. A3 or Subcat A4 (corresponds to A3 with an additional Block Check character.
Parameterization	according to ANSI X3.28 SubcatA3/A4	Subcat. A3/A4 are used when a master station sends data to a single slave station. The master station sends every message to the slave station and waits for a response. When the response indicates that the data has been accepted (ACK), the master station can send another message or terminate the connection. A negative response (NAK) from the slave station tells the master station that the data was not understood.
Conriguration		Data transfer The data transfer is begun by the master station after the connection is set up (see Subcat 2.5). The master station commences transfer with <stx>. After that, the required data is sent. The data block is terminated with <etx>. During transfer in accordance with Subcat. A4, the block-check - character (BCC) must follow <etx>.</etx></etx></stx>
endix Programming Calibration		 Response After recognizing <etx> resp. <bcc>, the slave station sends one of two possible responses:</bcc></etx> (1) If the data has been accepted and the station is ready to receive new data, it sends <ack>. After that, the master station can either send the next batch of data, or terminate transfer.</ack> (2) If the data has not been accepted and the slave station is ready to receive new data, it sends <nak>. After that, the master station can either send send other data or terminate the connection.</nak> If the master station receives an invalid response, or no response at all, it can send a "Reply-Request Supervisory Sequence" consisting of <enq>, or terminate the connection.</enq>
s & App		

Installation Oneration otori-otion 000 Configuration libration ζ 3 Techn. Specifica-tions & Appendix

Page 6 - 1 - 9

RESISTOMAT® burster

Timer func- tions in accor- dance with	The timers control cha Timer A (defined by the ANSI standard are used to indicate that a certain racter was not received within a specified time period. Response Timer)	Installation	
ANSI X3.28	Timer A is response or	used by the transmitting station for protection against an invalid no response.		
	Start: Time whicl	r A is started following the transmission of an end character after h a response is awaited (e.g. after ENQ or ETX).	Operation	
	Stop: Time	r A is stopped if a valid response has been received.	Ŭ	
	Time Out:	When a Time Out occurs, the Res2304 sends EOT, thus terminating the connection.	zation	
	In the Res	2304, timer A is set to 5 seconds.	arameter	
	Timer B (Receive Timer)			
	Timer B i recognition	s used by the receiving station for protection against non- of an end-of-text character (e.g. ETX).	uration	
	Start:	Timer B is started when a start-of-text character (STX) is received.	Config	
	Restart:	Timer B is restarted as long as data are received, to allow data blocks of variable length to be received.	ion	
	Stop:	Timer B is stopped when a valid end character is received.	ibrat	
	Time Out:	When a Time Out occurs, the received data are discarded, and the Res2304 waits for another transmission.	Cal	
	In the Res	2304, timer B is set to 5 seconds.	hn. Specifica- s & Appendix	
		Page 6 - 1 - 10	Tecl	

Installation	Flow diagram for connection set-up in ac-	The with 0.	following diagram shows the connection set-up the Res2304. The Res2304 has the group address	diagram shows the connection set-up of a system controller)4. The Res2304 has the group address 0 and the user address		
	cordance with	1.	Controller sends "Selection Supervisory Sequence"	Master	Slave	
ration	Sub2.5,A3/		0000sr <enq></enq>	Controller	Х	
Oper	2 1 7	2.	Res2304 assumes slave status and sends			
ion.			<ack></ack>	Controller	Res2304	
Parameterizat		3.	The controller then sends a command beginning with <stx> and ending with <etx> resp. <bcc></bcc></etx></stx>			
uration		<st< th=""><th>X>:DISP:CONT?0.5<lf><etx> (<bcc>)</bcc></etx></lf></th><th></th><th></th></st<>	X>:DISP:CONT?0.5 <lf><etx> (<bcc>)</bcc></etx></lf>			
Config		4.	On recognizing the command, the Res2304 sends			
c			<ack></ack>			
libratio			and writes the instantaneous setting of the display contrast into the output buffer.			
ပီ		5.	The controller terminates the connection with	Controllor	v	
Ð			<eot></eot>	Controller	Λ	
Programmi		6.	To fetch the response of the Res2304, the controller sends the "Polling Supervisory Sequence", thus making the Res2304 the master.			
specifica-			0000po <enq></enq>	Res2304	Controller	
Techn. S tions & /	Ρ ασε 6 - 1 - 11					

		Master	Slave	allation
7.	The Res2304 transfers the data to its output buffer			Inst
<st< td=""><td>X>0.5<cr><lf><etx>(<bcc>)</bcc></etx></lf></cr></td><td></td><td></td><td>ution</td></st<>	X>0.5 <cr><lf><etx>(<bcc>)</bcc></etx></lf></cr>			ution
8.	The controller responds with			Opera
	<ack></ack>			
9.	The Res2304 sends			ation
	<eot></eot>	Controller	v	steriz
	and thus terminates the connection	Controller		Parame
A Po prog of a	C with an RS232 interface can serve as a syster gram in GW basic for controlling the Res2304 PC is shown later in the Appendix.	n controller. via the serial	A sample interface	Configuration
				ration

Page 6 - 1 - 12

Table of contents, chapter 6-2

The RESISTOMAT®2304 Command Language

Introduction	6-2-2		
Command heading	6-2-2		
Command tree	6-2-3		
Query form	6-2-4		
Moving through the command tree	6-2-4		
Parameters	6-2-5		
Command terminator	6-2-6		
Special features of the Resistomat6-2-7			
Effects of the "MEASure?"-, "BEAD?"-, "FETCh?"-commands			
Effects of the "MEASure?"-, "READ?"-, "FETCh?"-commands during continuous measurement	6-2-7		
Effects of the "MEASure?"-, "READ?"-, "FETCh?"-commands during continuous measurement Difference between GPI B and serial interface	6-2-7 6-2-7		
Effects of the "MEASure?"-, "READ?"-, "FETCh?"-commands during continuous measurement Difference between GPI B and serial interface Status messages	6-2-7 6-2-7 6-2-8		
Effects of the "MEASure?"-, "READ?"-, "FETCh?"-commands during continuous measurement Difference between GPI B and serial interface Status messages	6-2-7 6-2-7 6-2-8 6-2-8		
Effects of the "MEASure?"-, "READ?"-, "FETCh?"-commands during continuous measurement Difference between GPI B and serial interface Status messages Introduction	6-2-7 6-2-7 6-2-8 6-2-8 6-2-9		
Effects of the "MEASure?"-, "READ?"-, "FETCh?"-commands during continuous measurement Difference between GPI B and serial interface Status messages Introduction	6-2-7 6-2-7 6-2-8 6-2-9 6-2-9		
Effects of the "MEASure?"-, "READ?"-, "FETCh?"-commands during continuous measurement	6-2-7 6-2-7 6-2-8 6-2-9 6-2-9 6-2-9 6-2-10		
Effects of the "MEASure?"-, "READ?"-, "FETCh?"-commands during continuous measurement	6-2-7 6-2-8 6-2-8 6-2-9 6-2-9 6-2-9 6-2-10 6-2-11		

Page 6 - 2 - 1

burster RESISTOMAT®

Type 2304

Installation

The RESISTOMAT[®]2304 Command Language

Introduction

The command language of the Res2304 is called **SCPI** (Standard Commands for **P**rogrammable Instrumentation). SCPI is a common language with standard commands, agreed upon by leading manufacturers of measuring devices. SCPI not only provides a standardized set of commands but also allows manufacturers of devices to define their own commands in accordance with specific rules.

SCPI knows four HLL commands sufficient for controlling a device: MEASURE?, READ?, FETCH? and CONFIGURE. The commands should be understood by every SCPI device.

In addition to these commands, the following **IEEE488.2 Common Commands** should be implemented in all SCPI devices:

- *CLS Clear Status Command
- *ESE Standard Event Status Enable Command
- *ESE? Standard Event Status Enable Query
- *ESR? Standard Event Status Register Query
- *IDN? Identification Query
- *OPC Operation Complete Command
- *OPC? Operation Complete Query
- *RST Reset Command
- *SRE Service Request Enable Command
- *SRE? Service Request Enable Query?
- *STB? Read Status Byte Query
- *TST? Self-Test Query (not implemented in the Res2304)
- *WAI Wait to Continue Command

Command heading

e.g.: DISPlay

Every SCPI command heading has a long and a short form. Every SCPI device should only accept the correct long and short forms. The IEEE488.2 limits the length of a command heading to 12 characters.

ion Parameterization Operation

Calibration Configuration

Programming

Techn. Specifications & Appendix The long form comprises either a single word or several abbreviated words. The short form is an abbreviation of the long form.

If the command consists of a single word, the word is the long form of the command (e.g. DISPLAY). If the command consists of several words, it is formed from the first letter of each word and the entire last word. For example, the words "Line Frequency" result in the command "LFREQUENCY".

The short form of the command heading normally consists of the first four letters of the long form (e.g. DISP). An exception is when the long form comprises more than four letters, the fourth one being a vowel. In this case, the vowel is omitted. Then the short form only consists of the first three letters of the long form. For example, the short form of the calibration command is CAL.

In the command list, the command is displayed in the long form, with the corresponding short form in capital letters and the rest of the command in small letters.

The commands can be sent in upper or lower case.

Command tree

The SCPI command tree has a hierarchial structure. Consequently, the same command heading can be used repeatedly for different tasks at different levels of the command tree.

e.g.:	TIME	:STATE	
	PRINTER	:TIME	:STATE
	Level 1	Level 2	Level 3

The various command levels are separated by a ":" Some commands have optional headings. In the case of the DISPlay:CONTrast command, for example, the "CONTrast" heading from level 2 is optional. None of the optional command headings need be transfered with the command.

In the command list, the optional parts of a command are enclosed in square parentheses (e.g. DISPlay[:CONTrast]). The parentheses are not part of the command, and must not be transmitted with it.



Query form

If not labelled otherwise, all commands have an appropriate query form. As defined in the IEEE488.2, the query form of a command is created by suffixing a question mark to the command heading (e.g. DISPlay:CONTrast?), A query form can, but need not be transmitted with a parameter. When the Res2304 receives the query form of a command, the current setting corresponding to the command is written into the output buffer. The response to a query command does not contain the command heading. If the response to a query command consists of one word, the short form is always used.

When measured values are requested, they are always in the same form as that shown on the display of the 2304.

For example: Display: 100.34kOhm -> Response 100.34KOHM

Moving through the command tree

Within a command message, several commands can be sent to the Res2304. The first one always refers to the root directory. Subsequent commands always refer to the same tree level as the preceding command of the command message. The individual commands within a command message are separated by a semicolon. If a command is transmitted with a prefixed colon, it again refers to the root directory. The command message is terminated with "Line Feed" (<nl>).

Example: If a device has the following command tree

INITiate :CONTinuous [:IMMediate]

<parameter>

SYSTem :BEEPer [:STATe]

<parameter>

ABORt

Calibration

Programming

Techn. Specifications & Appendix

Fechn. Specificaions & Appendix the following command messages act as described:

INIT:CONT ON;IMM<nl>

switches the device to continuous measurement and begins the measurement.

INIT:CONT ON;:INIT:IMM<nl> switches the device to continuous measurement and begins the measurement.

INIT:IMM;ABOR<nl>

starts the measurement and generates an error, because ABOR is not a command from the current interpreter level.

INIT:CONT ON;:INIT:IMM;:ABOR<nl> switches to continuous measurement, starts the measurement, and stops it again.

SYST:BEEP:STAT ON;:INIT;:ABOR;:SYST:BEEP:STAT OFF<nl> switches on the beeper, begins measurement, stops it, and switches the beeper off.

Parameters

The parameters valid for a command are listed in the following command list under the syntax description. The parameters are separated from the command heading by space character.

Format of a resistance parameter:

A parameter which stets a resistance value or resistance measurement range can be entered in several formats and with several units.

The resistance value can be entered in the form of integers, floating-point numbers or exponential numbers.

Valid units for a resistance parameter are:

UOHM	->	Microohm
MOHM	->	Milliohm
OHM	->	Ohm
KOHM	->	Kiloohm
MAOHM	->	Megaohm

Page 6 - 2 - 5

Туре 2304

Installation

If the unit is omitted, the parameter is assumed to be in Ohms. Examples of valid resistance parameters for a resistance of 123.45 Ohms:

123.45,123.45OHM,0.12345KOHM,123450MOHM,123.45E-6MAOHM.

Format of the ON/OFF parameters:

The ON/OFF parameters can be replaced by numerical parameters. When responding to query forms, the Res2304 always uses numerical values.

OFF -> 0 ON -> 1

The parameters for the quera forms of the individual commands can be omitted if only the current setting is being requested.

Command terminator

Line Feed (nl), Semicolon (;) or EOI (IEEE488.1 End or Identify), together with the last transmitted character (EOI only for GPIB control) indicate the end of the command.

For example, if the HP200/300 basic command 'OUTPUT 709;"INIT"" is sent, the controller automatically appends a <cr><nl> to the command. In the case of the other IEEE488 interfaces, e.g. a National PC insert-card, the <nl> character may need to be stated explicitly. (e.g..:ibwrt ":init\n")

Operation Parameterization Configuration Calibration Programming Techn. Specifica-tions & Appendix

Special features of the Resistomat

If a measurement has been started, no setting can be changed or requested. This means that the Res2304 ignores all commands until the measurement is stopped. Exceptions here are the "ABORt" command for stopping the measurement, the commands for status register control ("STATus") and the IEEE488.2 commands.

If the device has been switched to the cooling curve measurement mode, all "non-cooling" curve commands are disabled until the cooling curve measurement mode is turned off.

Effects of the "MEASure?", READ?", FETCh?"commands during continuous measurement

When one of these commands is sent, the next (!) available measured value is written to the output buffer. This measured value can then be fetched. For this, the Resistomat 2304 is made a talker (GPIB) or a master (ANSI X3.28). After the measured value is fetched, a new one is not written into the output buffer until a new "FETCh?" command is sent.

Difference between GPIB and serial interface

When several "MEASure?", "READ?" or "FETCh?" commands are sent in a row without the measured values being fetched, there is a difference between serial control and control via the GPI B.

In the case of the GPIB, each requested measured value is written into the output buffer (256 bytes) until it is full. After that, no new measured values are written into the buffer until it has been emptied. This can occur through the reading out of one or more requested measured values (first in, first out) or through the transmission of a "device clear" command.

During control via the serial interface, only the newest requested value is written into the output buffer.

Page 6 - 2 - 7



Туре 2304

Installation

Operation

Parameterization

Configuration

Calibration

Programming

Techn. Specifications & Appendix

Status Messages

Indroduction

Every SCPI device requires the status mechanism described in Chater 11 of the IEEE488.2, including full implementation of the Event Status Register Structure.



IEEE488.2 Data register structure

Installation	O p e r a t i o n status register	The operation status register contains states which are part of the normal functions of the Res 2304. If a bit in the operation status register is set, and the corresponding bit in the operation status enable register is released, the operation status summary bit (bit 7) in the status register is set. When bit 7 in the status register enable		
Operation		(bit 7) in the status register register is released, a servic control of the Res2304 via The bits used in the Res230 0 - Calibrating	 is set. When bit 7 in the service request enable e request is sent to the system controller during the IEC bus. 4 are: The Res2304 is performing a calibration. 	
Parameterization		 2 - Ranging 4 - Measuring 5 - Waiting for Trigger 8 - Z_x in charge 	 The Res2304 is changing its measurement range. The Res2304 is performing a measurement. The Res2304 is waiting for a trigger signal. The unit under test on the Res2304 has been recognized as mainly inductive 	
Configuration		9 - EOC	 and has been loaded. The bit corresponds to the warning LED on the front panel. End of Conversion: The bit indicates that a valid measured value is available to the Res2304. It is reset when the measured value is read out. 	
Calibration		The commands for controll STATus:OPERation:EVE STATus:OPERation:ENA	ing the operation status structure are: ENt? ABle	
chn. Specifica- ns & Appendix	Questionable status register	The questionable status register indicates that the data which has just been registered is invalid for some reason. If a bit in the questionable status register is set and the corresponding bit in the questionable status enable register is released, the questionable status summary bit (bit 3) in the status register is set. If bit 3 in the service request enable register is released, a service request is sent to the system controller during control of the Res2304 via the IEC bus.		
e e ≅ H	Page 6 - 2 - 9			
RESISTOMAT® burster

	Bit 14 is the command wa ignored during the execution The commands for controlli	rning bit and indicates that a parameter was n of a MEASure command. ng the questionable status structure are:	Installation
	STATus:QUEStionable:E STATus:QUEStionable:E	VENt? NABle	
S t a n d a r d event register	The standard event register i in the standard event register event enable register is relea 5 is released in the service re	ndicates different states of the Res2304. If a bit is set and the corresponding bit in the standard used, bit 5 in the status register is set. If this bit equest enable register, a service request is sent	Operation
	to the system controller duri	ng control of the device via the GPIB.	zation
	The bits used in the Res230	4 have the following meanings:	teriz
	Bit 0 Operation Complete	This bit is set in response to the *OPC command. It indicates that the device has executed the selected functions.	Parame
	Bit 2 Query Error	A query error has been detected. The bit indicates that either :	uration
		(1) non-existent data was requested or	Config
		(2) data in the output buffer was lost.	uo
	Bit 3 Device Dep.Error	The device dependent error bit indicates that an error has occurred during a measurement.	alibrati
	Bit 4 Execution Error	The execution error bit is set when a false parameter was sent.	
	Bit 5 Command Error	The command error bit is set when a command from the SCPI interpreter was not recognized.	ogramming
	The IEEE488.2 commands are:	for controlling the standard event data structure	Ъ Б
	*ESR? *ESE *ESE?		chn. Specific ns & Append
		Page 6 - 2 - 10	E O

Installation

Operation

Configuration Parameterization

Calibration

Programming

Techn. Specifications & Appendix



Standard data register

The status byte is used to combine serval event registers in one status register. The status byte of every event register has a corresponding event register summary bit which indicates whether an event in the related event register has occurred. The corresponding summary bit is only set when the related bit in the event enable register is set. If the summary bit is set and the bit in the service request enable register is released, a service request is sent to the system controller during control of the Res2304 via the GPIB.

The bits in the status byte are:

Bit 0 - 2	not used			
Bit 3	Questionable status summary bit. The bit is set when a bit released in the questionable event enable register has been set in the questionable event register.			
Bit 4	MAV-Message available The MAV bit is set when data are present in the output buffer of the Res2304.			
Bit 5	ESB-Event status summary bit. The bit indicates whether an event released in the event status register of the Res2304 has occurred.			
Bit 7	Operation status summary bit. The bit is set when an event released in the operation status register has occured.			
The IEEE488.2 commands for setting the status data structure are:				

*STB? *SRE *SRE?

Comment on the "MEASure" command

The "MEASure?" command stops a current measurement, selects a desired measurement range, starts a new measurement, and writes a measured value into the output buffer the moment it is available.

The command should only be used for simple test programs, as the Resistomat 2304 writes a measured value into its output buffer as soon as it is available. When the status registers are sampled after the "MEASure?" command has been sent, it is not possible to distinctly associate the data in the output buffer with the requested data. A measured value could be obtained instead of the requested contents of the status register.

When the status registers are to be used ("STATus" commands), it is better to work with the "INITiate" and "FETCh?" commands. "INITiate" starts a measurement, but no measured value is written into the output buffer. In this manner, one can request the state of the Resistomat 2304 by means of the "STATus" commands, without obtaining a measured value on a "STATus" command - this would be possible when using the "MEASure?" command. The measured value can then be requested with the "FETCh?" command. Parameterization Operation Installation

Configuration

Techn. Specifications & Appendix



Installation

Operation

Table of contents, chapter 6 - 3

The RESISTOMAT[®]2304 command list

Introduction	
ABORt	ation
CALCulate	Ň
CALibration	te
CONFigure	Ше Ц
DISPlay	a a
FETCh	Å
INITiate	
INPut	L C
MEASure	ati
OUTPut	, n
PRINter	Ĩ.
READ	ő
SCALE	0
SENSe	
SORT	<i>_</i>
SOURce	ō
SYSTem	Ţ
TRACe	<u>2</u>
TRIGger	ပ္မ
	-
Cooling curve measurement commands 6.3.86	Ø
CCURve	<u>,</u>
0-0-07	E
Status - Message commands 63 102	2
STATus	D0
	a 🛛
IEEE488.2 commands	
1222 (002 Commundation 100-3-109	di Si
	en
	b o o
	AR

Page 6 - 3 - 1

Techn. Stions &









ABORt

nstallation	ABORt				
	Description:	Aborts a single or repetition measurement which has been started.			
Operatio	Syntax:	:ABORt			
tion	Comments	The command is equivalent to pressing the "STOP" button.			
Parameteriza	Example:	10 OUTPUT 709;":INITIATE" !start measurement 20 OUTPUT 709;":FETCH?" !request measured values 30 ENTER 709;A\$!fetch measured value			
Configuration		40 PRINT A\$ 50 OUTPUT 709;":ABORT" !stop measurement 60 END			
Calibration					
ichn. Specifica- Ins & Appendix					
tio	Page 6 - 3 - 3				



Installation CALCulate:MATH[:EXPRession] Description: This command selects the desired display mode of the device. Operation Syntax: :CALCulate:MATH[:EXPRession] < parameter > The *parameter* corresponds to the mathematical expression used for the parameter : display. Parameterization Display mode parameter R/LENGTH0[M] Ohm / Meter R/LENGTH0[KM] Ohm / Kilometer R/LENGTH0[10FT] Ohm / 10 feet R/LENGTH0[KFT] Ohm / 1000 feet DELTA% Delta% RHO1 Rhol Configuration RHO2 Rho2 **GAMMA1** Gamma 1 GAMMA2 Gamma2 **ATTENTION:** The corresponding display mode is only set when the "CALCULATE:STATE ON" command is sent. Calibration Otherwise the display remains on "OHM". Comments: $O \ u \ e \ r \ y$ The query form of the command gives the mode selected with "CALC:MATH:EXPR" (see parameter table), when form: "CALC:STAT ON" was sent. Programming Otherwise the response "R" is obtained. CALC:STAT Response ON selected mode OFF R Techn. Specifica-tions & Appendix The individual parameters of the various display modes are entered with the help of the "TRACe:DATA" command. (see "TRACe:DATA" command)

RESISTOMAT® Type 2304 burste Installation CALCulate:MATH[:EXPRession] Example: Setting the display to "Ohm / Meter" Operation - 05 OUTPUT 709;":CALCULATE:STATE OFF"! turn on Ohm display - 10 OUTPUT 709;":CALCULATE:MATH:EXPRESSION? R/LENGTH0[M]" - 20 ENTER 709;A\$!fetch current display mode - 30 OUTPUT 709;":CALCULATE:STATE ON" !switch to "Ohm/ Meter" Parameterization - 40 OUTPUT 709;":CALCULATE:MATH:EXPRESSION?" - 50 ENTER 709;B\$!fetch new display mode - 60 PRINT A\$, B\$!response on screen - 70 END Response of the device: R R/LENGTH0[M] Configuration Calibration Programming Techn. Specifica-tions & Appendix Page 6 - 3 - 5



CALCulate:STATe				Installation	
Description:	The command a "CALC:MATH:E	The command activates or deactivates the display mode set with CALC:MATH:EXPR".			
Syntax:	:CALCulate:STA	Te <	parameter>	Oper	
X [*]	paramete	er	Setting	Ę	
	ON OFF		mode selected with the "EXPR" command Ohm display mode	Parameterizati	
Comments:	Query form: T re w w	The q espoi when when	uery form of the command results in the following use from the device: STATE = ON -> 1 STATE = OFF -> 0	Configuration	
Example:	Reset value:		OFF	Calibration	
Dumpro.	see "CALCulate:	see "CALCulate:MATH:EXPRession" command.			

RESISTOMAT[®] burster

stallation		CALibration:	DATA			
	Description:	This command is meant for calibratir ranges.	ng the individual resistance measurement			
ation	Syntax:	:CALibration:DATA < parameter	>			
Opera	parameter:	The <i>parameter</i> consists of two parts: the resistance measurement range to be calibrated, and the corresponding calibration value. The two parts are separated by a comma.				
rization		parameter	Description			
Paramete		PT100,901100HM 200U0HM,89111U0HM 2M0HM,0.891.11M0HM 20M0HM 8.9.111M0HM	PT100 - measurement range 200UOHM - measurement range 2MOHM - measurement range 20MOHM - measurement range			
Configuration		200MOHM,8.9111MOHM 200HM,0.891110HM 200HM,8.91110HM 2000HM,891110HM 2000HM,891110HM 2KOHM,0.89111KOHM 20KOHM,8.911.1KOHM	200MOHM - measurement range 200HM - measurement range 200HM - measurement range 2000HM - measurement range 2KOHM - measurement range 20KOHM - measurement range			
ion		Example: CAL:DATA 2000HM,100.350HM				
Calibrat	Comments:	The calibration value may consist of no more than 7 digits. Example: "CAL:DATA 20HM,1.0345670HM"				
Techn. Specifica- tions & Appendix	Page 6 - 3 - 7	Example: "CAL:DATA 2OHM,1.034567OHM" Query form: The query form "CAL:DATA?" gives the calibration data all measurement ranges, separated by commas The response has the following format: <pt100>,<200UOHM>,,<20KOHM> Example:: 104.2345OHM,98.12345UOHM,,10.23456KOHM PT100 200UOHM 20KOHM</pt100>				

Page 6 - 3 - 7



Installation

CALibration:DATA

Example: Calibration of all measurement ranges Operation Pt100 OUTPUT 709;"CALIBRATION:DATA PT100,100.4567 OHM" 200uOhm measurement range OUTPUT 709; "CALIBRATION: DATA 200UOHM, 100.4567UOHM" 2mOhm measurement range OUTPUT 709; "CALIBRATION: DATA 2MOHM, 1.004567MOHM" Parameterization 20mOhm measurement range OUTPUT 709;"CALIBRATION:DATA 20MOHM,10.04567MOHM" 200mOhm measurement range OUTPUT 709; "CALIBRATION: DATA 200MOHM, 100.4567MOHM" 20hm measurement range OUTPUT 709; "CALIBRATION: DATA 20HM, 1.0045670HM" 200hm measurement range OUTPUT 709; "CALIBRATION: DATA 200HM, 10.045670HM" Configuration 2000hm measurement range OUTPUT 709; "CALIBRATION: DATA 2000HM, 100.45670HM" 2kOhm measurement range OUTPUT 709;"CALIBRATION:DATA 2KOHM,1.004567KOHM" 20kOhm measurement range OUTPUT 709;"CALIBRATION:DATA 20KOHM,10.04567KOHM" Calibration Request calibration data: 10 OUTPUT 709;"CALIBRATION:DATA?" 20 ENTER 709;A\$!fetch calibration data 30 PRINT A\$!display calibration data 40 END Programming Response of the device (e.g.): 180.03590HM.101.4213U0HM,1.001234M0HM,...,99.99914K0HM Appendix

Techn. Stions & /



stallation		CALibration:ZERO		
2	Description:	This command triggers an offset adjustment of the device.		
Operation	Syntax:	:CALibration:ZERO		
	Comments:	no parameters		
Parameterization	Example:	no query form 10 OUTPUT 709;"CALIBRATION:ZERO" !offset adjustment		
Configuration		20 END		
Calibration				
Programming				
Techn. Specifica- tions & Appendix	Page 6 - 3 - 9			

RESISTOMAT® burster

(CONFigur	•e[F	RESistance:DC]	nstallation	
Description:	Configures the set.	device, i.e	e. a desired resistance measurement range can be		
Syntax:	:CONFigure[:F	:CONFigure[:FRESistance:DC] < parameter>			
parameter	With the help of range.	the parame	eter, the device is switched to a desired measurement	o O	
	The paramters	are:		tion	
	parameter	×	Description	eteriza	
	020KOH	Μ	The device switches to manual range selection and selectes the measurement range containing the parameter.	Parame	
	DEFault		The device remains in the measurement range currently selected.	guration	
	If the parameter range selection independently.	r is omitted a and sear	I d, the device switches to automatic measurement rches for the appropriate measurement range	Config	
Comments:	Query form:	The que the follo FRES: <	ry form of the "CONFigure" command provides owing response from the device: <selected range=""></selected>	Calibration	
		Exampl	e: FRES: 20KOHM	ing	
Example:	10 OUTPUT 7 20 ENTER 709 30 PRINT A\$ 40 END	09;":CON);A\$	FIGURE? 1000HM" !2000HMM-range	Programm	
	Response of th	e device::	FRES: 2000HM	Specifica-	
			Page 6 - 3 - 10	Techn. tions &	



stallation	DISPlay[:CONTrast]			
Ë	Description:	This command is meant for adjusting the display contrast.		
Operation	Syntax: parameter	:DISPlay[:CONTrast] < <i>parameter</i> > 01		
Parameterization	Comments:	The display contrast is adjustable between: 0 -> no contrast 1 -> full contrast		
Configuration		Q u e r y On the entry of the query form of the "DISPLay:CO command, the device sends the current contrast between 0 and 1. Reset value: 0.54	'NTrast" t setting	
Calibration	Example:	10 OUTPUT 709;":DISPLAY:CONTRAST? 0.5" !normal contrast 20 ENTER 709;A\$!fetch requested contrast setting 30 PRINT A\$ 40 END		
echn. Specifica- ons & Appendix		Response of the device: 0.5		
F:2	Page 6 - 3 - 11			

Page 6 - 3 - 11



DISPlay:ENABle				
Description:	Activate or deactivate LCD display (during remote operation)			
Syntax: parameter	:DISPlay:ENABle < <i>parameter</i> > The display is turned on or off with the help of the parameter.	Operation		
Commenta	The parameters are: ON or 1 -> LCD Display is on OFF or 0 -> LCD Display is off The LCD divelops on early he termed on or off via one of the external	Parameterization		
Comments: The LCD display can only be turned on or off via one of the externa interfaces. The function is only active during remote operation				
	Query form: DISPlay:ENABle? Response of the device: 0 -> when LCD off. Display:ENABle? Display:ENABle?	Configurat		
	<i>Reset value:</i> OFF or 0	Calibration		
Example:	10 OUTPUT 709;":DISP:ENAB? ON"! DISPLAYON20 ENTER 709;A\$! RESPONSEFETCH30 PRINT A\$! RESPONSEDISPLAY40 ENDResponse of the device: 1	specifica- Appendix Programming		
	Page 6 - 3 - 12	Techn. S tions & /		

tallation		DISPla	y:MENU[:ST	ATe]		
s L	Description: This command activates or deactivates the bar display.					
Operation	Syntax: parameter	:DISPlay:MENU[:STATe] < <i>parameter</i> > The bar display is activated or deactivated with the help of the parameter.				
tion		parameter	setting	corresponding num. value		
teriza		ON	bar display on	1		
Parame		OFF	bar display off	0		
Configuration	Comments	When the para numerical valu	meter is polled, the devi e.	ce always sends the corresponding		
	Comments.	active.				
Calibration		Query form: On the entry of the query form ":DISP:MENU:STAT?", the device responds with the corresponding numerical value. 0 -> when bar display off 1 -> when bar display on				
Programming	Example:	<i>Reset value:</i> 10 OUTPUT 7 20 ENTER 70	OFF 09;":DISPLAY:MENU: 9:A\$!fetch response	STATE? ON" !bar display on		
rechn. Specifica- ions & Appendix		30 PRINT A\$ 40 END Response of th	e device: 1			



Installation FETCh[:FRESistance:DC]? Description: Revieves measured values while a measurement is in progress and places them into the device's output buffer. Operation Syntax: :FETCh[:FRESistance:DC]? Comments: The command is used to fetch a measured value via the interface while a measurement is in progress. Parameterization During single measurements, the measured value is sent via the interface on every "FETCh" inquiry. During repetition measurements, the most recent measured value is always sent via the interface. The measurement must be stopped with "ABORt". Configuration Example: 10 OUTPUT 709;":INITIATE" !start measurement 20 OUTPUT 709;":FETCH?" !request measured value 30 ENTER 709;A\$!fetch measured value 40 PRINT A\$!display measured value **50 END**



Techn. Specifications & Appendix

RESISTOMAT® burster

INITiate:CONTinuous

stallation	INITiate:CONTinuous					
<u> </u>	Description:	The command is meant for changing over between single and repet measurements.				
Operatio	Syntax:	:INITiate:CON	INITiate:CONTinuous < parameter>			
<u>io</u>	parameter	Repetition mea parameter.	asurement is activated o	or deactivated with the help of the		
terizat		parameter	setting	corresponding num. value		
Paramet		ON OFF	repetition meas. single meas.	1 0		
Configuration	When the parameter is polled, the device always sends the corresponding numerical value.					
		value has been registered.				
oratio		Repetition mea via the keyboa	asurements must be stopp rd.	ped with the "ABORt" command or		
Calik		Query form:	On the entry of the ":INITiate:CONT	e query form inuous?", one obtains:		
ramming		Reset value	0 -> during single meas 1 -> during repetition m : ON	urement leasurement		
Specifica- Appendix Prog	Example:	10 OUTPUTmeasurement20 ENTER 70930 PRINT A\$40 END	709;":INITIATE:CC 9;A\$!fetch requested me !display value	ONTINUOUS? ON" !repetition easurement type		
lechn. ions &		Response of th	e device: 1			
	rage 6 - 3 - 15					



	INITiate[:IMMediate]	Installation
Description:	The "INITiate:IMMediate" command starts a resistance measurement when the trigger is set to passive. When the trigger is set to active, a "group-execute-trigger" is awaited, and the measurement is not started until its occurrence.	Deration
Syntax:	:INITiate[:IMMediate]	ð
Comments: Example:	<i>Query form:</i> none 10 OUTPUT 709;":INITIATE:IMMEDIATE" !start measurement	Parameterization
-	20 OUTPUT 709;":FETCH?" !request measured value 30 ENTER 709;A\$!fetch measured value 40 OUTPUT 709;":ABORT" ! stop measurement 50 END	
	INITiate:REF Ø	uo
Description:	The measurement REFØ will adjust. Zero - reference measurement in measure kind "CONSTANT".	Calibrati
Syntax:	:INITiate:REFØ	mming
Comments:	This instruction is only possible if measure mode "CONSTANT" is adjust.	Progra
	Query form: none Parameter: none.	echn. Specifica- ions & Appendix
	Page 6 - 3 - 16	

RESISTOMAT® burster

nstallation			INPut:LOW	
	Description:	Thepotential f	fixing of the measurement part is selected with this command.	
Operation	Syntax: parameter	:INPut:LOW < <i>parameter</i> > The potential fixing is selected with the help of this <i>parameter</i> .		
uo		parameter	Description	
izati		FLOat	the measurement part floats	
Parameter		GROund	the measurement part is grounded internally	
Configuration	Comments:	Query form:	On the entry of the query form of the command, the device sends the present grounding configuration of the measurement part.	
0				
u			Measurement part floats -> FLO Measurement part grounded -> GRO	
Calibratio		Reset value:	GRO	
rogramming	Example:	10 OUTPUT 7 20 ENTER 7 30 PRINT AS 40 END Response of t	709;":INPUT:LOW?GROUND" !ground internally and inquire 09;A\$!fetch requested response 5 !display grounding configuration the device: GRO	
Techn. Specifica- tions & Appendix P	Page 6 - 3 - 17			



	MEASure[:FR	ESistance:DC]?	Installation	
Description:	configures, starts and stops (in the case of single measurements) the measurement and supplies measured values.			
Syntax: parameter:	MEASure[:FRESistanc With the help of the presistance range.	e:DC]? < <i>parameter</i> > parameter, the device is switched to the desired	Operatio	
	The parameters are:	Description	terization	
	020KOHM	The device switches to manual range selection and selects the measurement range in which the parameter lies.	Parame	
	DEFault	The device remains in the current measurement range.	iguration	
	If the parameter is omittrange selection and sear	ted, the device switches to automatic measurement rches for the appropriate range independently.	Conf	
Comments:	Single measurements ar been registered.	e stopped automatically after a measured value has	ration	
	Continuous measurements must be stopped with the "ABORt" command.			
	The measured value supplied by the device has the following format:			
	 Normal resistance measurement: measured value with unit Comparator function: measured value with unit, valuation symbol Classify function: measured value with unit, valuation class 			
Example:	10 OUTPUT 709;":ME. 20 ENTER 709; A\$ 30 PRINT A\$ 40 END	AS?" !measurement with automatic range selection	Specifica- Appendix Pro	
	possible response: 100.	00OHM	chn. ns &	
		Page 6 - 3 - 18	Te	



allation	OUTPut:TTLTrgO:LEVel			
Inst	Description:	With this command, the bit at pin 21 of the I/O jack can be set or reset.		
Operation	Syntax:	OUTPUT:TTLTrg0:LEVel < parameter >		
rization	Comments:			
Parameter	parameter	1 or ON -> The bit is set 0 or OFF -> The bit is reset		
ration		Query form: OUTPut:TTLTrg0:LEVel?		
Configu		If the bit is set, a 1 is returned. If the bit is not set, a 0 is returned.		
Calibration		Reset value: 1		
r x	Example:	OUTPUT 709; "OUTP:TTLT0:LEV 0"		
Techn. Specifica tions & Appendix	Page 6 - 3 - 19			



r

	OUTPut:TTLTrg1:LEVel	allation
Description:	With this command, the bit at pin 3 of the I/O jack can be set or reset.	Inst
Syntax:	OUTPUT:TTLTrg1:LEVel < parameter >	Operation
Comments: parameter	1 or ON -> The bit is set 0 or OFF -> The bit is reset	Parameterization
	Query form:OUTPut:TTLTrg1:LEVel?If the bit is set, a 1 is returned.If the bit is not set, a 0 is returned.	Configuration
	Reset value: 1	Calibration
Example:	OUTPUT 709; "OUTP:TTLTRG1:LEVEL 1"	Techn. Specifica- tions & Appendix Programming

RESISTOMAT® burster

tallation		PRI	Nter:CNUMber		
n B	Description:	This command	d is meant for entering a test number on the printer listing.		
s	Syntax:	:PRINter:CNU	JMber < <i>parameter</i> >		
Dperati	parameter	The parameter consists of 6 arbitrary ASCII characters.			
E E	Comments:	Query form:	On the entry of the query form of the ":PRINter:CNUMber?" command, the currently selected test number is obtained.		
ameterizatio		Any ASCII cha device. Only r via the keyboa	aracter can be entered as a test number via the interface of the numeric characters can be entered as test numbers manually and of the device.		
ъ Б		Reset value:	<6 spaces>		
iguration		PRINter:CNUMber:STATe			
C C u	Description:	This comman printed on the	d is used to specifiy whether the test number is also to be measurement protocol.		
alibratio	Syntax:	:PRINter:CNU	JMber:STATe < <i>parameter</i> >		
U	parameter	parameter	Setting		
ramming	-	ON OFF	Test number is printed Test number is not printed		
x Prog	Comments:	Query form:	On the query form of the command, the following responses are obtained from the device:		
Specific: Appendi		Pasat values	when STATE = ON $\rightarrow 1$ when STATE = OFF $\rightarrow 0$		
Techn. tions &	Page 6 - 3 - 21	Resei value;	Uff		



tallation

PRINter:DATE[:STATe]

Description:	This command is used to specify whether the date is also to be printed on th				lns
Syntax: parameter	printer listing. :PRINter:DATE	[:STATe] < parameter	* >		Operation
	parameter	Setting			
	ON OFF	Date is printed Date is not printed			meterization
Comments:	Query form:	On the query form of the are obtained from the d	e comn levice:	nand, the following responses	Para
		when STATE = ON when STATE = OFF	-> ->	1 0	nfiguration
	Reset value:	ON			ပိ
					alibration

RESISTOMAT[®] burster

Installation	Boom Anno Statute and an All Contract of Statute Statute	PRINter:DELay
MARROVIN	Description:	This command selects the delay time between two printouts.
peration	Syntax:	:PRINter:DELay < <i>parameter</i> >
0	parameter	Hours, minutes, seconds
zation		With the help of the parameter, the delay time between two printouts is entered in hours, minutes and seconds.
eteri		Example: one measured value to the printer every three hours:
Param		OUTPUT 709;"PRINTER:DELAY 03,00,00"
Configuration	Comments:	<i>Query form:</i> On the entry of the query form ":PRINTER:DELAY?" one obtains the currently selected delay time between two measured values in the following form:
		nours, minutes, seconds
tion		To print out every measured value, the delay time can be set to 0,0,0.
Calibrat		Reset value: 0,0,0
Techn. Specifica- tions & Appendix Programming	Page 6 - 3 - 23	



PRINter:HEADer

	PF	RINter:HEADer	Installation
Description:	This comman printed out be	d speficies the number of measured values which are to be fore the measurement protocol heading is repeated.	ttion
Syntax:	:PRINter:HE	ADer < parameter >	Opera
parameter	The paramete measurement valid values	er states the number of measured values to be printed per protocol heading. -> 19999	eterization
Comments:	Query form:	On the entry of the query form ":PRINter:HEADer?", the device sends the current number of measured values per measurement protocol heading.	ion Param
	The maximum protocol head	n number of measured values between two measurement ings is 9999.	Configurat
	Reset value:	1000	Calibration

Programming

Techn. Specifica-tions & Appendix



Installation		PRINter:	NUMerator[:STATe]
uo	Description:	This command also be printed	specifies whether a numerator of the measured values should on the measurement protocol.
Operati	Syntax:	:PRINter:NUM	erator[:STATe] < <i>parameter</i> >
	parameter	parameter	Setting
meterization		ON OFF	Numerator is printed out Numerator is not printed out
Para	Comments:	The numerator	is printed out before the measured value.
ration		Query form:	On the entry of the query form of the command, one obtains the following responses from the device:
Configu			when STATE = ON $\rightarrow 1$ when STATE = OFF $\rightarrow 0$
Ę		Reset value:	ON
Calibratic		PRINter	:NUMerator:RESet
buj	Description:	With this comm	nand, the measured value numerator is reset to one.
gramm	Syntax:	:PRINter:NUM	lerator:RESet
ix ^{a-} Pro	Comments:	no parameters	
hn. Specific s & Append		no query form	
Tec! tion:	Page 6 - 3 - 25		

burster **RESISTOMAT®**

na an a	PF	RINter[:STATe]	Installation	
Description:	This command interface and a	This command activates or deactivates the connection between the serial nterface and a printer.		
Syntax:	:PRINter[:STA	ATe] < parameter >	Ŏ	
parameter	<i>parame</i> ON OFF	ter Setting Printer function on Printer function off	Parameterization	
Comments:	Qиегу form:	On the entry of the query form "PRINter:STATe?", the device sends the current status of the printer function. Printer function off $-> 0$ Printer function on $-> 1$	Configuration	
	Attention:	The printer function can only be selected if IEEE488 has been selected in the interface menu! During operation via the serial interface, the printer function is not available.	Calibration	
	The printer fun in order for the manually to IE to the serial in	actions can also be configured via the serial interface. However, e printer to operate afterwards, the device must be switched EEE488 interface operation, and the printer must be connected interface.	Iramming	
	When the print bus are also pi	ter function is selected, measured values requested via the IEC rinted out.	Proç	
	Reset value:	OFF	. Specifica- & Appendix	
		Page 6 - 3 - 26	Techn tions &	

nstallation	P	RINter:T	COefficient[:STATe]	
	Description:	This command to be printed ou	specifies whether the selected temperature coefficient is also at in the measurement protocol heading.	
Operatic	Syntax:	tax: :PRINter:TCOefficient[:STATe] < parameter >		
•	parameter	parameter	Setting	
meterization		ON OFF	selected TC is printed selected TC is not printed	
Para	Comments:	Query form:	On the entry of the query form of the command, one obtains the following responses from the device:	
nfiguration			when STATE = ON $\rightarrow 1$ when STATE = OFF $\rightarrow 0$	
S		Reset value:	OFF	
Calibration		The temperatu compensation i	are coefficient is only printed out if the temperature is activated.	
hn. Specifica- s & Appendix Programming				
Tec	Page 6 - 3 - 27			



PRINter:TIME[:STATe]			stallation
Description: Syntax: parameter	This command specifies whether the measurement time is also to be printed in the measurement protocol. PRINter:TIME[:STATe] < parameter > parameter Setting		Operation
Comments:	ON OFF Query form: Reset value:	Time is printed Time is not printedOn the entry of the query form of the command, one obtains the following responses from the device:when STATE = ON $\rightarrow 1$ when STATE = OFF $\rightarrow 0$ ON	Configuration Parameterization
			ramming Calibration
			Prog

Techn. Specifications & Appendix

Installation

Operation

Parameterization

Configuration

Calibration

Programming

Techn. Specifications & Appendix RESISTOMAT[®] burster

PRINter:TYPE

Description: This command selects the type of the connected serial printer.

Syntax:

:PRINter:TYPE < parameter >

parameter With the parameter, any one of three printer types can be selected.

parameter	Printer type
0	80 character - printer
1	40 character - printer
2	20 character - printer

Comments:

Query form: On the entry of the query form "PRINter: TYPE?", one obtains the current setting of the printer type from the device..

Response: 20 character - printer -> 2 40 character - printer -> 1 80 character - printer -> 0

Reset value:

0



Installation

PRINter:TYPE

Example:	Example for setting the printer listing menu.			
	 10 OUTPUT 709;":PRINTER:TYPE 0" !80-character printer 20 ! printout every 30 minutes 30 OUTPUT 709;":PRINTER:DELAY 0,30,0" 40 ! print date and time 50 OUTPUT 709;":PRINTER:DATE:STATE ON" (0 OUTPUT 709;":PRINTER:DATE:STATE ON" 	Operation		
	 60 OUTPUT 709; "PRINTER: HME:STATE ON" 70 ! set measurement protocol number to Test 1 and print 80 OUTPUT 709; "PRINTER: CNUMBER TEST1" 90 OUTPUT 709; "PRINTER: CNUMBER: STATE ON" 100 ! print temperature coefficient 110 OUTPUT 709; "PRINTER: TCOEFFICIENT: STATE ON" 120 ! reset numerator and print 			
	130 OUTPUT 709;":PRINTER:NUMERATOR:RESET" 140 OUTPUT 709;":PRINTER:NUMERATOR:STATE ON" 150 ! measurement protocol heading every 50 printed values. 160 OUTPUT 709;":PRINTER:HEADER 50" 170 ! activate printer function 180 OUTPUT 709;":PRINTER:STATE ON"	Configuration		

Calibration Config



	Туре 2304	RESISTOMAT [®] burster
Installation	READ	[:FRESistance:DC]?
	Description:	starts, stops (in case of single measurements), and supplies measurement result.
Operation	Syntax:	READ[:FRESistance:DC]?
	Comments:	The command is used instead of the "MEASure" command if the desired measurement range has already been selected.
erization		Single measurements are stopped automatically after a measured value has been registered. Repetition measurements must be stopped by means of the "ABORt" command.
Paramete		The measured value supplied by the device has the following format: 1. Normal resistance measurement: measured value with unit 2. Comparator function: measured value with unit, valuation sign
Configuration	Example:	 3. Classify function: measured value with unit, valuation class 10 OUTPUT 709; ":READ?" !measure without range selection 20 ENTER 709;A\$ 30 PRINT A\$ 40 END
Calibration		SKALe:PT100
	Description:	With this command the Pt100 coefficients are transmitted. The individual values are transmitted without unit.
Programmierung	Syntax:	:SCALe:Pt100 < parameter >
		Parameters in the sequence R_0 , A, B, C, t_{100} (without unit) DIN EN 60751 values (default values) $R_0 = 100$, A = 3.9083 e ⁻³ , B = -5.775 e ⁻⁷ , C = -4.183 e ⁻¹² , $t_{100} = 100$
thn. Specifica- Is & Appendix	Comments:	Only the entry of the query form SCALe:Pt100? obtains the following coefficients (R_0 , A, B, C, t_{100}). The entry of the query form SCALe:Pt100:DIN? obtains the DIN EN values.
Tec	Seite 6 - 3 - 31	


Γ

	SENSe:C	ORRection[:STATe]	tallation	
Description:	This command	This command specifies whether a temperature compensation is to be carried out during the resistance measurement.		
	carried out durin			
Syntax:	:SENSe:CORR	ection[:STATe] < <i>parameter</i> >	Oper	
parameter	parameter	Setting	c	
Comments:	ON OFF	Temperature compensation is performed Temperature compensation is not performed	Parameterizatio	
	Query form: Reset value:	On the entry of the query form of the command, one obtains the following responses from the device : when STATE = ON -> 1 when STATE = OFF -> 0 OFF	Configuration	
	If the temperatur is the resistance temperature and	e compensation is activated, the measurement result obtained e value at 20 degrees C, based on the measured value, l linear temperature coefficient.	Calibration	
			Programming	
		Page 6 - 3 -32	Techn. Specifica- tions & Appendix	

stallation	SENSe	e:CORRec	tion:TCOMpensate:AUTO
no	Description:	This command temperature cor manually.	specifies whether a temperature value in the case of npensation should be registered automatically or entered
Operati	Syntax:	:SENSe:CORR	ection:TCOMpensate:AUTO < parameter >
c	parameter	parameter	Setting
rameterizatio		ON OFF	Temperature is registered automatically Temperature can be entered manually
D D D	Comments:	Query form:	On the entry of the query form of the command, one obtains
Configuration		On thew setting	when STATE = ON -> 1 when STATE = OFF -> 0 "AUTO=ON", an external Pt100 sensor must be connected.
lion		On the setting ' command "SEN	'AUTO=OFF", the temperature can be entred with the Se:CORRection:TCOMpensate:TCOM:MAN" command.
Calibrat		During changed the most recent	over frommautomatic to manual temperature measurement, temperature value entred manually is selected again.
jing		The current ten "SENSe:CORF	nperatue can be polled with the Rection:TCOMpensate:MANual?: command.
Programn		Reset value:	OFF
Specifica- Appendix			
Techn. tions &	Page 6 - 3 - 33		



SENSe:	CORRection:TCOMpensate[:MANual]	Installation
Description:	This command is used for manually entering the temperature in the case of temperature compensation.	lion
Syntax:	:SENSe:CORRection:TCOMpensate[:MANual] < parameter >	Operat
parameter	-70999.99 The largest possible temperature range lies between -70 und 999.99 degrees Celsius.	Parameterization
Comments:	 Q u e r y On the query form ":SENS:CORR:TCOM:MAN?" one form: obtains the currently selected temperature from the device. The query form of the command also supplies the current temperature during automatic temperature measurement. 	Configuration
	The response to the query form of the command is sent with the unit "CEL". (Example: "23.4CEL"). The temperature must be selected without stating the unit. (Example: ":SENS:CORR:TCOM:MAN 23.4") When the temperature is selected via the "MANual" - command, the automatic temperature measurement is deactivated. (AUTO = OFF).	amming Calibration
	Page 6 - 3 - 34	Techn. Specifica- tions & Appendix

stallation	SENSe:CO	RRection:TCOMpensate:TCO1TCO10
2	Description:	This command selects one of ten possible temperature coefficients.
Operation	Syntax:	:SENSe:CORRection:TCOMpensate:TCOx < parameter > TC - number:
tion	parameter	09999, depending on the desired temperature coefficient.
sterizat	-	The parameter has the unit "ppm/K". The unit may not be transferred as well.
Parame	Comments:	Quary form. On the entry of the query form, one obtains the value of the
ation	Commonds.	currently selected temperature coefficient, if the TC number is not transferred as well.
Configura		If the TC number is also transferred, the value of the corresponding TC is obtained as a response.
ation		For selecting a specific TC, the corresponding TC number and the desired TC value must be transferred.
Calibra	Example:	Setting the temperature compensation menu:
dix Programming		 10 ! manual entry of the ambient temperature 20 OUTPUT 709;":SENS:CORR:TCOM:MAN 23.4" 30 ! setting the desired TC (number 1) to 3980 ppm/K 40 OUTPUT 709;":SENS:CORR:TCOM:TCO1 3980" 50 ! activate temperature compensation 50 OUTPUT 709;":SENS:CORR:STAT ON"
Techn. Specifi tions & Appen	Page 6 - 3 - 35	·

SENSe:LFRequency

WATS CONTRACTOR OF THE STATE OF T	SEN	Se:LI	FRequency		stallation
Description:	This command the nominal li	ls synchror ne frequen	nizes the integration time of the A/D co cy at which the device is operated.	onverter with	
Syntax:	:SENSe:LFRe	SENSe:LFRequency < parameter >			Operation
parameter	parame	eter	Remark		Б
	16.7 50 60	,	Device operated at 16 ² / ₃ HZ Device operated at 50 HZ Device operated at 60 HZ		Parameterizati
Comments:	The parameter <i>Query form:</i>	r is sent wi On the er	thout a unit. htry of the query form "SENSe:LFRec	quency", one	Configuration
	2	obtains th device. The respo <value>H (Exampl</value>	ne current setting of the mains frequent conse of the device has the form: HZ He: 50HZ)	ncy from the	Calibration
	Reset value:	5	0		mming
Example:	10 OUTPUT 709;":SENSE:LFREQUENCY? 50" ! 50HZ mains frequency 20 ENTER 709;A\$! fetch response 30 PRINT A\$			ns frequency	Progra
	40 END Response of th	he device:	50HZ Page	6 - 3 - 36	Techn. Specifica- tions & Appendix

Installation SENSe:RESistance:APERture Description: This command selects the measurement time base, i.e. the number of line periods over which the measurement is to be carried out. Operation Syntax: :SENSe:RESistance:APERture < parameter > 1..9 parameter Parameterization Depending on the desired number of line periods. Comments: **Ouery form:** On the entry of the query form ":SENSe: RESistance: APERture?", one obtains the Configuration current setting of the time base. Attention: At high resolution, the minimum value of the time base = 5. Reset value: at low resolution -> 1 at medium resolution -> 5 at high resolution -> 9 Calibration Example: 10 OUTPUT 709;":SENSE:RESISTANCE:APERTURE? 7" 20 ENTER 709;A\$ **30 PRINT A\$** 40 END Programming Response of the device: 7 Techn. Specifica-tions & Appendix

Page 6 - 3 - 37



	SENSe:I	RESistance:AVERage	nstallation		
Description:	This comman be determined	d selects the number of measured values whose average is to I.			
Syntax:	:SENSe:RESi	:SENSe:RESistance:AVERage < parameter >			
parameter	1255 depending on value.	the number of measured values required for forming a mean	trameterization		
Comments:	<i>Queryform:</i> Attention:	On the entry of the query form "SENSe:RESistance:AVERage?", one obtains the current number of measured values meant for forming a mean value. At high resolution, the minimum number of measured values for forming the mean value = 5	nfiguration Pa		
Dava and the	Reset value:	at low resolution -> 1 at medium resolution -> 1 at high resolution -> 5	alibration Co		
Example:	20 ENTER 70 30 PRINT A\$ 40 END Response of t	709;":SENSE:RESISTANCE:AVERAGE? 9" 09;A\$ he device: 9	idix Programming Ca		
		Page 6 - 3 - 38	Techn. Specifi tions & Appen		

nstallation	SENSe:RESistance:COMPlex:LIMit				
E	Description:	This command selects the release limit of the measured value during unipolar measurements involving mainly inductive test units.			
Operatic	Syntax:	:SENSe:RESistance:COMPlex:LIMit < parameter >			
Ę	parameter	0.05PCT20PCT			
terizatio		With the help of the parameter, the release limit is stated as a percentage.			
Parame		For example, a setting of "1PCT" means that a measured value can only be displayed if it differs from the previous one by less than 1PCT.			
Configuration	Comments:	<i>Query form:</i> On the entry of the query form ":SENSe:RESistance:COMPlex:LIMit?", one obtains the selected release limt as a percentage from the device.			
Calibration		Selection of the release limit is only of significance for unipolar measurements on inductive resistances. It serves to suppress the measured values during the transient phase, which occurs particularly in the case of large inductances.			
ŋg		Reset value: 20PCT			
I. Specifica- & Appendix	Example:	05 ! Setting the release limit to 2.34 % 10 OUTPUT 709;":SENS:RES:COMP:LIM? 2.34PCT" 20 ENTER 709;A\$ 30 PRINT A\$ 40 END Response of the device:2.34PCT			
Techr	Page 6 - 3 - 39				

	SENSe:RES	istance:LOAD	Installation
Description:	This command selects inductive resistance).	s the load to be measured (mainly ohmic or main	
Syntax:	:SENSe:RESistance:L	.OAD < parameter >	Operatio
parameter	The parameter specifi or an inductance.	es whether the test unit consists of a real resistance	e iion
	parameter	Remark	eteriza
	REAL	Test unit is mainly ohmic	arame
	COMPlex	Test unit is mainly inductive	u
Comments:	Query On the form: ":SENS selected	entry of the query form Se:RESistance:LOAD?", one obtains the currently d type of load.	Configurati
	When mainly inductiv (LOAD=COMPlex), range selection was p range selection when	ve test units are selected for resistance measuremen automatic range selection is not possible. If automat previously selected, the device switches to manu "COMplex" is activated.	ts ic alipration
	Reset value:	REAL	ming
Example:	05 ! measurement of a 10 OUTPUT 709;":SI 15 ENTER 709;A\$ 20 PRINT A\$	an ohmic resistance ENSE:RESISTANCE:LOAD? REAL"	ica- dix Program
	30 END Response of the devic	ce: REAL	nn. Specifi s & Appen
		Page 6 - 3 - 40	Tech

SENSe:RESistance:PAUSe

stallation	SENSe:RESistance:PAUSe				
<u></u>	Description:	This command selects the measurement pause.			
ration	Syntax:	:SENSe:RESistance:PAUSe < parameter >			
Ope	parameter	1255			
eterization	Comments:	depending on the required measurement pause. The measurement pause is a waiting period which allows the circuit to settle			
Parame		after switchover processes. It depends on the type of test unit and the selected operating mode. By means of the "measurement pause" factor, the internal presetting can be adapted to "problematic" test units.			
guration		As the measurement pause is entered in the charging time as a multiplicative factor, this parameter should be handled carefully.			
Confi		Query form: On the entry of the query form ":SENSe:RESistance: PAUSe?", one obtains the current number of line periods over which measurement is not carried out.			
Calibration		Reset value:at low resolution->1at medium resolution->1at high resolution->1			
	Example:	Setting the measurement pause to 9:			
Programming		10 OUTPUT 709;":SENSE:RESISTANCE:PAUSE? 9" 20 ENTER 709;A\$ 30 PRINT A\$ 40 END			
Specifica-		Response of the device: 9			
Techn. tions 8	$\mathbf{P}_{\mathbf{n},\mathbf{r}_{\mathbf{n}}} \in \mathcal{I}_{\mathbf{n}} = \mathcal{I}_{\mathbf{n}}$				

SE	NSe:RES	istance:RANGe:AUTO	Installation		
Description:	This command selection.	This command activates or deactivates automatic measurement range election.			
Syntax:	:SENSe:RESist	ance:RANGe:AUTO < <i>parameter</i> >	Opera		
parameter	parameter	Setting	tion		
	ON OFF	automatic measurement range selection manual measurement range selection	Parameteriza		
Comments:	Query form:	On the entry of the query form of the command, one obtains the following responses from the device: when STATE = ON $\rightarrow 1$ when STATE = OFF $\rightarrow 0$	Configuration		
	Reset value:	OFF			
	Automatic rang been selected as	e selection is not possible when inductive test units have s the load.	Calibration		
Example:	Setting the auto	matic measurement range selection:			
	OUTPUT 709;"	ESENSE:RESISTANCE:RANGE:AUTO ON"	Techn. Specifica- tions & Appendix		

allation	SENSe:RESistance:RANGe[:UPPer]		
Inst	Description:	This comman	d selects the desired measurement range.
beration	Syntax:	:SENSe:RESi	stance:RANGE[:UPPer] < <i>parameter</i> >
ð	parameter	0UOHM201	KOHM
zation		With the help is selected.	of the parameter, the desired measurement range
Parameteriz	Comments:	Queryform:	On the entry of the query form ":SENSe:RANGE[UPPer]?", one obtains the currently selected measurement range from the device.
tion		On recognizir selection.	ng the command, the device switches to manual range
nfigura		The paramete	r can be entered with the following units:
Co		UOHM MOHM	Microohms Milliohms
		OHM	Ohms Kiloshara
tion		МАОНМ	Megaohms
Calibrat		If the unit is c	mitted, the parameter is considered to be in ohms.
		The measurer can be measu	nent range in witch the resistance, input as a parameter, red is selected.
rogramming		-> The cor to the 2	nmand "SENS:RES:RANG: 2000HM" switches over kohm range.
ā		Reset value:	20KOHM
Specifica- Appendix	Example:	Selecting the	200 ohm measurement range: 700-"-SENSE-RESISTANCE-RANCE-LIPPER 1000LM"
chn. ns &		IUUUIPUI	109, JEINSEIKESISIAINUEIKAINUEIUPPEK 1000HM
ti e	Page 6 - 3 - 43		



	SENSe:RESista	ance:RESolution	Installation
Description:	This command selects t	he resolution of the measured value display.	uo
Syntax:	:SENSe:RESistance:RE	Solution < <i>parameter</i> >	Operat
purumeter	The desired resolution is	Setting	c
	MINimum DEFault MAXimum	low resolution medium resolution high resolution	Parameterizatic
Comments:	<i>Queryform:</i> On the RESolut from the Response	entry of the query form ":SENSe:RESistance: ion?", one obtains the currently selected resolution device. e: MIN or DEF or MAX	Configuration
	At the highest resolution a minimum value of 5. <i>Reset value:</i>	n setting, the "time base" and "average value" have DEFault	Calibration
Example:	Selecting the highest re 10 OUTPUT 709;":SEN 20 ENTER 709;A\$ 30 PRINT A\$ 40 END Response of the device	solution: ISE:RESISTANCE:RESOLUTION? MAXIMUM" : MAX	ifica- Programming
		Page 6 - 3 - 44	Techn. Spec tions & Appe

RESISTOMAT[®] burster

stallation	SORT:BINNing?				
<u>.</u>	Description:	The comparator setting can be requested with this command.			
Operatior	Syntax:	:SORT:BINNing?			
eterization	Comments:	 only query form no parameters 			
Param		0 -> when comparator type = comparator			
Configuration		 <i>I</i> -> when comparator type = classify function <i>Reset value:</i> 0 			
Calibration	Example:	10 OUTPUT 709;":SORT:BINNING?" 20 ENTER 709;A\$ 30 PRINT A\$ 40 END			
Techn. Specifica- tions & Appendix Programming	Page 6 - 3 - 45				



SORT:BINNing:ACKNowledge

	SORT:BINNing:ACKNowledge	Installation
Description:	With this command, all classification limits set via the interface are accepted, provided that they were valid.	e
Syntax:	:SORT:BINNing:ACKNowledge	Operatio
Comments:	- no query form - no parameters	ion
	If the classification limits entered previously with the command "SORT:BINNing:LIMit18" were invalid, the error message: -220."PARAMETER ERROR"	arameterizat
	is filed in the error buffer and the corresponding bits in the status register are set. (Bit 4 in the Standard Event Status Register : Execution Error Bit)If the display mode was changed, all limiting values and the specified value must be entered in the new display unit, otherwise an error is indicated again.	Infiguration Pa
	The discrepancy between the limiting values and the specified value should be less than 10000 %.	ő
Example:	see "SORT:BINNing:LIMit18" command	Calibration

nstallation		SORT:BINNing:DATA?		
	Description:	The classification statistics are requested with this command.		
Operation	Syntax:	:SORT:BINNing:DATA?		
arameterization	Comments:	 only query form no parameters Response of the device: <class 0="">,<class 1="">,<class2>,<class3>,,<class8>,<total></total></class8></class3></class2></class></class> 		
Configuration		<class0><class8> -> number of measured values within the individual classification limits.<total> -> total number of recorded measurements.</total></class8></class0>		
Calibration		The classification statistics are not active when the device is set to repetition measurement. If errors occur during the measurement, so that no measured values are available, the classification statistics are not changed.		
ica- Programming	Example:	see ":SORT:BINNing:LIMit1LIMit8" command		
Techn. Specifi tions & Appen	Page 6 - 3 - 47			



	SORT:BINNing:DATA:RESet	Installation
Description:	The classification statistics are deleted with this command.	
Syntax:	:SORT:BINNing:DATA:RESet	Operation
Comments:	- no query form - no paramteres	arameterization
Example:	see ":SORT:BINNing:LIMit1LIMit8" command	Configuration Pa

Techn. Specifications & Appendix Programming Calibration

Installation

Parameterization

SORT:BINNing:LIMit1...LIMit8 Description: This command selects the eight limiting values of the individual classes of the classify function. Operation Syntax: :SORT:BINNing:LIMitx < parameter > 1..8, depending on the desired limit. X The magnitude of the limit is entered with the parameter. parameter The paramter can be sent with or without a unit. The limiting value can also be entered as a percentage deviation (unit: PCT) from the specified value. e.g. "SORT:BINN:LIM1 -5PCT" Configuration Comments: Query form: On the entry of the query form "SORT: BINNing: LIMitx ?", one obtains the current value of the limit x. The percentage values cannot be requested directly. Valid units for the parameters are: Calibration UOHM, MOHM, OHM, KOHM, MAOHM, OHM/M, OHM/KM, OHM/10FT, OHM/KFT, M/(OHM*MM2), OHM*MM2/M or PCT. The limiting values must be entered in **increasing** order, i.e. limit 1< limit 2< limit 3< ... < limit 8 Programming After the "SORT:BINNing:ACKNowledge" command is sent, the limiting values are checked for validity and then accepted. If a limiting value was invalid, bit 4 (Execution Error Bit) in the standard event status register is set, and the error message: Techn. Specifica-tions & Appendix -220."PARAMETER ERROR" is written into the error buffer.

Page 6 - 3 - 49

	SORT:BINNing:LIMit1LIMit8	Installation
	If the display unit was changed, all limiting values and the specified value in the new display mode must be entered. Reset value: 960HM 970HM 980HM 00 0HM 1010000	ation
Example:	Measurement of resistances with a specified value of 100 ohms. The limits are:	Oper
	Limit 1 -> -4% of specified value Limit 2 -> -3% Limit 3 -> -2% Limit 4 -> -1% Limit 5 -> +1% Limit 6 -> +2%	Parameterizatior
	Limit 7 -> +3% Limit 7 -> +4% 5 n=0 ! auxiliary counter 10 OUTPUT 709;":SORT:STATE ON" ! activates sort function 20 OUTPUT 709;":SORT:BINNING:NOMINAL 100OHM" ! specified value 30 OUTPUT 700:":SORT:BINNING:NOMINAL 100OHM" ! specified value	Configuration
	40 OUTPUT 709;":SORT:BINNING:LIMIT1 -4PCT" 40 OUTPUT 709;":SORT:BINNING:LIMIT2 -3PCT" 50 OUTPUT 709;":SORT:BINNING:LIMIT3 -2PCT" 60 OUTPUT 709;":SORT:BINNING:LIMIT4 -1PCT" 70 OUTPUT 709;":SORT:BINNING:LIMIT5 +1PCT" 80 OUTPUT 709;":SORT:BINNING:LIMIT6 +2PCT" 90 OUTPUT 709;":SORT:BINNING:LIMIT7 +3PCT"	Calibration
	100 OUTPUT 709;":SORT:BINNING:LIMIT8 +4PCT" 105 ! accept values 110 OUTPUT 709;":SORT:BINNING:ACKNOWLEDGE" 120 END	Programming
	Page 6 - 3 - 50	tions & Appendix



lation	SORT:BINNing:NOMinal				
Instal	Description:	The specified value of the classify function is entered with this command.			
ition	Syntax:	:SORT:BINNing:N	OMinal < <i>parameter</i> >		
Opera	parameter	desired specified value with or without unit:			
		<specified value=""><u< th=""><th>unit></th><th></th></u<></specified>	unit>		
arameterization	Comments:	Query form: On the entry of the query form ":SORT:BINNing:NOMinal?", the device sends the currently selected specified value with the corresponding unit.			
å		The parameter can l	be sent with or without a u	mit.	
ation		The folowing units	are valid:		
Configura		in display mode	"Ohm"and "Delta%": "Ohm/Meter":	UOHM, МОНМ, ОНМ, КОНМ, МАОНМ ОНМ/М	
		with	"Ohm/Km":	OHM/KM	
		with	"Ohm/10ft":	OHM/10FT	
ion		with	"Ohm/kft":	OHM/KFT M/(OUN4*MM2)	
brat		with	"Rho":	OHM*MM2/M	
Cali		If the unit is not sent, the transmitted specified value is processed in the basic unit of each display mode.			
nming		The specified value is accepted after the ":SORT:BINNing:ACKNowledge" command is sent, when all limiting values are valid. The units of the specified value and the limiting values must be appropriate for the display. If the display mode was changed, all limiting values must be entered with the new unit.			
Progra					
÷ X		Reset value:	100OHM		
Specifi Appen	Example:	see ":SORT:BINNi	ng:LIMit1LIMit8" comn	nand	
Techn. tions &	Page 6 - 3 - 51				

Page 6 - 3 - 51



Installation

SORT:COMParator?

Description:	The setting of the comparator type can be requested with this command.
Syntax:	:SORT:COMParator?
Comments:	 only query form no parameters Response of the device: 0 -> when comparator = classify function 1 -> when comparator = comparator
	Reset value: 1
Example:	10 OUTPUT 709;":SORT:COMPARATOR?" 20 ENTER 709;A\$ 30 PRINT A\$ 40 END

Operation Parameterization Configuration Calibration Programming Techn. Specifica-tions & Appendix

Installation	SC	DRT:COMParator:ACKNowledge
u	Description:	With this command, all comparator limiting values set via the interface are accepted, if they were valid.
Operati	Syntax:	:SORT:COMParator:ACKNowledge
erization	Comments:	 no query form no parameters
Paramet		HLIMit" and "SORT:COMParator:LLIMit" commands were invalid, the error message:
Configuration		 -220,"PARAMETER ERROR" is filed in the error buffer, and the corresponding bits in the status register are set. (Bit 4 in the standard event status register : execution error bit) If the display mode was changed, both limiting values and the specified value must be entered in the new display unit, otherwise an error is indicated
bration		again. The discrepancy between the limiting values and the specified value must be smaller than 100 %.
Call	Example:	see "SORT:COMParator:LLIMit" command
pecifica- ppendix Programming		
Techn. S tions & A	Page 6 - 3 - 53	

Installation

SORT:COMParator:DATA?

Description: The comparator statistics are polled with this command.

Syntax: :SORT:COMParator:DATA?

Comments:

only query form no parameters

Response of the device:

- >, =, <,sum
- < -> number of measured values smaller than the lower limit.
 - -> number of measured values larger or equal than the lower limit and smaller or equal than the upper limit.
- > -> number of measured values larger than the upper limit.
- sum -> total number of recorded measurements

The comparator statistics are inactive when the device is switched to continuous measurement.

If errors occur during the measurements, so that no measured values are recorded, the statistics are not changed.

Example:

see ":SORT:COMParator:LLIMit" command



stallation	SORT:COMParator:DATA:RESet			
ů,	Description:	The comparator statistics are deleted with this command.		
Operation	Syntax:	:SORT:COMParator:DATA:RESet		
rization	Comments:	- no query form - no parameters		
Paramete	Example:	see ":SORT:COMParator:LLIMit" command		
Configuration				
Calibration				
:hn. Specifica- Is & Appendix Programming				
Tec	Page 6 - 3 - 55			

Installation SORT:COMParator:HLIMit Description: This command selects the upper limiting value for the comparator function. Operation Syntax: :SORT:COMParator:HLIMit < parameter > Desired upper limiting value with or without unit: parameter Parameterization <upper limit><unit> Comments: Query form: On the entry of the query form ":SORT:COMParator:HLIMit?", the device supplies the currently selected upper limit with the corresponding unit. Configuration Example: 1100HM Reset value: 1100HM The parameter can be sent with or without a unit. The following units are valid: Calibration UOHM, MOHM, OHM, KOHM, MAOHM, OHM/M, OHM/KM, OHM/10FT, OHM/KFT, M/(OHM*MM2), OHM*MM2/OHM. If no unit is sent, the transmitted upper limit is processed with the basic unit. After the":SORT:COMParator:ACKNowledge" command is sent, the upper Programming limit is checked for validity and accepted, if the specified value and the limiting values are valid. The upper limit must be larger than the lower limit. If the display unit was changed, the specified value and the limiting values Techn. Specifica-tions & Appendix must be entered again. Example: see ":SORT:COMParator:LLIMit" command

Installation		SORT:COMParator:LLIMit
ation	Description:	This command selects the lower limiting value for the comparator function.
Oper	Syntax:	:SORT:COMParator:LLIMit < <i>parameter</i> >
tion	parameter	Desired lower limiting value with or without unit.
arameteriza	Comments:	<lower limit=""><unit></unit></lower>
ь Б		Query form: On the entry of the query form ":SORT: COMParator: LLIMit?", the device supplies the
Configuratio		Example: 900HM
_		
ratior		The parameter can be sent with or without a unit.
Calib		The following units are valid:
		UOHM, MOHM, OHM, KOHM, MAOHM, OHM/M, OHM/KM, OHM/10FT, OHM/KFT, M/(OHM*MM2), OHM*MM2/M
ming		If no unit is sent, the transmitted lower limit is processed with the basic unit.
Program		The lower limit is accepted after the ":SORT:COMParator:ACKNowledge" command has been sent.
pecifica-		If the display unit was changed, the specified value and the limiting values must be entered with the new unit.
chn. S ns & A		
₽ë	Page 6 - 3 - 57	

Type 2304

Installation SORT:COMParator:HLIMit Operation Example: Setting the specified value, the lower limit and the upper limit of the comparator function (device switched to single measurement). 10 OUTPUT 709;":SORT:STATE"! sort function activated 20 OUTPUT 709;":SORT:COMP:LLIM 90OHM" 30 OUTPUT 709;":SORT:COMP:HLIM 1100HM" Parameterization 40 OUTPUT 709;":SORT:COMP:NOM 100OHM" 50 OUTPUT 709;":SORT:COMP:ACKN" 55 ! 5 single meaurements 60 OUTPUT 709;":INIT 65 ! ... switch the resistor connections when the meaurements is over 70 OUTPUT 709;":INIT 75 ! ... switch the resistor connections Configuration 80 OUTPUT 709;":INIT 55 ! ... switch the resistor connections 90 OUTPUT 709;":INIT 55 ! ... switch the resistor connections 100 OUTPUT 709;":INIT 105 wait until the measurement is over 110 OUTPUT 709;":SORT:COMP:DATA?" ! request statistics 120 ENTER 709;A\$ Calibration 130 PRINT A\$ 135 OUTPUT 709;":SORT:COMP:DATA:RES" ! delete statistics 140 END possible response oof teh device: 1.3.1.5 Programming Techn. Specifica-tions & Appendix Page 6 - 3 - 58

Installation

SORT:COMParator:NOMinal

tion	Description:	The specified value of the comparator function is entered with this command.
Opera	Syntax:	:SORT:COMParator:NOMinal < parameter >
	parameter	desired specified value with or without unit:
ization		<specified value=""><unit></unit></specified>
on Parameter	Comments:	Query form:On the entry of the query form ":SORT:COMParator:NOMinal?", the device supplies the currently selected specified value with the corresponding unit.
onfigurati		The parameter can be sent with or without a unit.
ပိ		The following units are valid:
u		UOHM, MOHM, OHM, KOHM, MAOHM, OHM/M, OHM/KM, OHM/10FT, OHM/KFT, M/(OHM*MM2), OHM*MM2/M
alibrati		If the unit is not sent, the transmitted specified value is processed with the basic unit.
D Bu		The specified value is accepted after the ":SORT:COMParator: ACKNowledge" command is sent, if all limiting values and the specified value are valid.
Programm		If the display unit was changed, the limiting values and the specified value must be entered in the new display unit.
Specifica- Appendix	Example:	see ":SORT:COMParator:LLIMit" command
Techn. Stions & J	Page 6 - 3 - 59	

		SORT:STATe	Installation
Description:	The sort func	tion is activated or deactivated with this command.	uo
Syntax:	:SORT:STAT	e < parameter >	Operati
parameter	parameter	Setting	uo
	ON OFF	Sort function on Sort function off	Parameterizat
Comments:	Query form:	On the entry of the query form ":SORT:STATe?", the device supplies: 0 -> when STATE = OFF 1 -> when STATE = ON	Configuration
Example:	<i>Reset value:</i> OUTPUT 709	0);":SORT:STATE ON"	Calibration
			Programming
		Page 6 - 3 - 60	Techn. Specifica- tions & Appendix

Installation	SOURce:CURRent[:LEVel:IMMediate:AMPLitude]			
	Description:	This command sets the measuring current.		
Operation	Syntax:	:SOURce:CURRent[:LEVel:IMMediate:AMPLitude] < parameter >		
Ŭ	parameter	parameter Setting		
Parameterization		MINimumsmall measuring currentDEFaultmedium measuring currentMAXimumlarge measuring current		
Configuration	Comments: Query form: On the entry of the query form "SOURce:CURRent?", one obtains the current setting of the measuring current. Response: MIN> - small measuring current			
Calibration		DEF -> medium measuring current MAX -> large measuring current IND -> individual measuring current		
Programming		Individual measuring currents are set with the "SOURce:CURRent: REFerence" command. The individual measuring current is selected with the "SOURce: CURRent:REFerence:STATe ON" command.		
Techn. Specifica- tions & Appendix	Example:	Selecting a large measuring current: OUTPUT 709;":SOURCE:CURRENT MAX"		



	SOURce:CURRent:REFerence	Installation
Description:	The individual measuring currents of each measurement range are selected with this command.	Operation
Syntax:	:SOURce:CURRent:REFerence < parameter >	
parameter	<range>,<current> <range> -> desired measurement range <current> -> desired individual measuring current</current></range></current></range>	Parameterization
Comments:	Queryform: On the entry of the query form "SOURce:CURRent:REFerence?", one obtains as a response the individual measuring currents of all ranges. The measuring currents are separated by commas.	Configuration
	Response:	"······
	10A,<2mohm range>,,<2kohm range>,100UA The individual measuring current is selected with the "SOURce: CURRent:REFerence:STATe ON" command.	Calibration
	<i>Reset valuee:</i> 10A, 10A, 1A, 100MA, 10MA, 1MA, 1MA, 1MA, 100UA	rogramming
Example:	Selecting a measuring curent of 1mA in the 20 ohm range	ā
	10 OUTPUT 709;":SOUR:CURR:REF 10OHM,1MA" 20 OUTPUT 709;":SOUR:CURR:REF:STAT ON"	Fechn. Specifica- ions & Appendix
	Page 6 - 3 - 62	1

Installation	SOL	JRce:CUR	Rent:REFerence:STATe	
tion	Description:	The individual r	neasuring current is selected with this command.	
Opera	Syntax:	:SOURce:CURRent:REFerence:STATe < parameter >		
u	parameter	narameter	Setting	
Parameterizatio	Georgeater	ON OFF	individual measuring current medium measuring current	
Configuration	Comments.	Query form: (On the entry of the query form ":SOUR:CURR:REF:STAT?", one obtains the status of the individual measuring current. Response of the device:) -> small, medium or large measuring current 1 -> individual measuring current	
Calibration		When the "SOU the device swite <i>Reset value:</i>	Rce:CURRent:REFerence:STATe OFF" command is sent, ches to the medium measuring current range.	
hn. Specifica- s & Appendix Programming	Example:	Selecting the in OUTPUT 709;	dividual measuring current: ":SOUR:CURR:REF:STAT ON"	
Tecl	Page 6 - 3 - 63			

burster RESISTOMAT®

	SOURce:FU	JNCtion[:SHAPe]	Installation
Description: Syntax:	This command swi measurements. :SOURce:FUNCtion	itches over between unipolar,bipolar and constant [:SHAPe] < <i>parameter</i> >	Operation
parameter	parameter	Setting	5
	PULS SQUare CONSTant	unipolar measurement bipolar measurement constant measurement	Parameterizati
Comments:	Query form: On ":SOU setting Respon	the entry of the query form lRce:FUNCtion[:SHAPe]?", one obtains the current of the measurement procedure.	Configuration
	PULS SQU CONS <i>Reset value:</i>	-> unipolar -> bipolar -> constant SQU	Calibration
Example:	1 1		
Linumpio.	bipolar measurement	RCE:FUNCTION:SHAPE SQUARE"	n. Specifica- & Appendix Programming
		Page 6 - 3 - 64	Techi tions

Installation

Operation

Parameterization

Configuration

Calibration

Programming

Techn. Specifications & Appendix

burster

SYSTem:BUZZer[:STATe]

Description:

This command controls the buzzer. When the buzzer is active, a warning tone occurs in the case of measurements on inductive loads; this tone persists from measurement interruption until the test unit has discharged.

Syntax:

:SYSTem:BUZZer[:STATe] < parameter >

parameter

parameter	Setting	corresponding num. value
ON	Buzzer on	1
OFF	Buzzer off	0

Comments:

Query form: On the entry of the query form ":SYSTem:BUZZer[:STATe]?", one obtains the current status of the buzzer from the device.

Response:

0	->	Buzzer off
1	->	Buzzer on

0

Reset value:

Example:

Activate buzzer:

OUTPUT 709;":SYSTEM:BUZZER ON"

Page 6 - 3 - 65

SYSTem:(COMMu	nicate:SERial:ADDRess:GROup	Installation
Description:	This comman	d selects the group address of the serial interface of the device.	ation
Syntax:	:SYSTem:CC	MMunicate:SERial:ADDRess:GROup < parameter >	Oper
parameter Comments:	015 The group address can be set within the range between 0 and 15.		
	Query form: Reset value:	On the entry of the query form "SYST:COMM:SER:ADDR:GRO?", one obtains the current group address from the device. Response of the device: 015	Configuration
Example:	The group ad Setting the gr	dress must be entered in decimal form. oup address to 12:	Calibration
	OUTPUT 70	9;":SYST:COMM:SER:ADDR:GRO 12" Page 6 - 3 - 66	Techn. Specifica- tions & Appendix Programming

stallation	SYSTem:	SYSTem:COMMunicate:SERial:ADDRess:USER				
<u> </u>	Description:	This command selects the user address of the serial interface of the device.				
Operation	Syntax:	:SYSTem:COMMunicate:SERial:ADDRess:USER < parameter >				
Ę	parameter	015				
Parameterizatio	Comments:	The user address can be set within the range between 0 and 15. Query form: On the entry of the query form "SVST:COMM:SEP: ADDP: USEP?" one obtains the				
Configuration		Response of the device: 015 Reset value: 0				
Calibration	Example:	The user address must be entered in decimal form. Setting the user address to 12: OUTPUT 709;":SYST:COMM:SER:ADDR:USER 12"				
Techn. Specifica- tions & Appendix Programming	Page 6 - 3 - 67					
SYSTen	n:COMM	unicate	:SER	al:BCCharac	ter	Installation
--------------	--	---	--	--	---------------------------------------	---------------------------------
Description:	This command transmission.	activates c	or deactive	ates the block check	during serial	
Syntax:	:SYSTem:COM	Municate:S	ERial:BC	Character < parameter	>	ratio
parameter	parameter	Sett	ing	corresponding num.	value	ope
	ON OFF	BC BC	CC on CC off	1 0		tion
Comments:	Query form:	On the entry one obtains from the de	of the quer the currer vice.	y form ":SYST:COMM It status of the block cf	ESER:BCC?", neck character	Parameteriza
	Attention:	Response: 0 -> 1 -> In the ca	BCC off BCC on se of the	block check character	, the MSB is	Configuration
	always to a is in Device has SLa When the block character durin	avoid mistak n the range t AVE status: check chara g serial trans	ting it for between 12 cter is activ smission.	ASCII control charact 28 and 255. ve, the device awaits it a	set ers. The BCC fter the "ETX"	Calibration
	Device has MA The BCC is set The BCC is fo bytes after "ST (see ANSI X3	ASTER statu nt by the dev ormed throug 'X" includin 3.28 1976 ch	s: vice after t gh Exclus g "ETX". apter 4.3	he "ETX" character. sive-OR operation on a page 28: "Block Checl	all transmitted	Programming
Example:	<i>Reset value:</i> Activate block OUTPUT 709	0 check chara ;":SYST:CO	icter: MM:SER	:BCC ON"		hn. Specifica- is & Appendix
				Ра	ge 6 - 3 - 68	tion

nstallation	SYST	em:COMM	unicate:SERial:CDELay
u	Description:	This command act 1.5 ms.	tivates a character transmission delay of approx. 1ms -
Operati	Syntax:	:SYSTem:COMM	unicate:SERial:CDELay < parameter >
Ę	parameter		
catio		<i>parameter</i>	Setting
Parameteriz		OFF	Delay off
Configuration	Comments:	Query form: On ":S sta	n the entry of the query form SYST:COMM:SER:CDEL?", one obtains the current atus of the character transmission delay from the device
		Kt	esponse.
Ę		0	-> Delay off
Calibratic		Reset value:	0 Delay on
- Programming	Example:	Activate character OUTPUT 709;":S	r transmission delay: YST:COMM:SER:CDEL ON"
Techn. Specifica tions & Appendio	Page 6 - 3 - 69		

SYSTem:C	COMMunicate:SERial:TRANsmit:BAUD	Installation
Description:	This command selects the baud rate of the serial interface.	
Syntax: parameter	:SYSTem:COMMunicate:SERial:TRANsmit:BAUD < parameter > 600, 1200, 4800, 9600, 19200	Operation
Comments:	depending on the desired baud rate Query form: On the entry of the query form ":SYST:COMM:SER:TRAN:BAUD?", one obtains the	Parameterization
	current setting of the baud rate from the device. Response: 60019200 Reset value: 9600	Configuration
Example:	Setting the baud rate to 9600 bits/sec: OUTPUT 709;":SYST:COMM:SER:TRAN:BAUD 9600"	Calibration
	Page 6 - 3 - 70	Techn. Specifica- tions & Appendix

stallation	SYSTem:	COMMunicate:SERial:TRANsmit:BITS
n n	Description:	This command selects the number of data bits per character during serial transmission.
Operatio	Syntax:	:SYSTem:COMMunicate:SERial:TRANsmit:BITS < parameter >
ç	parameter	7 or 8
Parameterizatio	Comments:	depending on the desired number of data bits Query On the entry of the query form form: ":SVST:COMM:SEB:TRAN:BITS?" one obtains the current
Configuration		number of data bits per character from the device. Response: 7 -> 7 data bits/character 8 -> 8 data bits/character
Calibration		Reset value:8During printer operation, the number of data bits should be set to 8, so that the ASCII special characters larger than the ASCII value of 127 are understood by the printer.
nn. Specifica- s & Appendix Programming	Example:	8 data bits/character: OUTPUT 709;":SYST:COMM:SER:TRAN:BITS 8"
Tecl	Page 6 - 3 - 71	

SYSTem:CO	MMunicate:S	ERial:TRANsmit:PARity[:TYPE	Installation
Description: Syntax: parameter	This command select	ets the type of parity bit in the case of serial transmission nicate:SERial:TRANsmit:PARity[:TYPE]< <i>paramete</i>	n. Operation
	parameter	Setting	Ę
	EVEN ODD NONE	even parity odd parity no parity	Parameterizatio
Comments:	<i>Query form:</i> On "SY sett tabl	the entry of the query for ST:COMM:SER:TRAN:PAR?", one obtains the curre ing of the parity type from the device (see paramet le)	m nt er Configuration
	Reset value:	NONE	
Example:	Selecting an even p OUTPUT 709;":SY	arity: /ST:COMM:SER:TRAN:PAR:TYPE EVEN"	Calibration
		Page 6 - 3 - 72	Techn. Specifica- tions & Appendix

Installation	SYSTem:	COMMunicate:SERial:TRANsmit:SBITs
uo	Description:	This command selects the number of stop bits per character in the case of serial transmission.
Operat	Syntax:	:SYSTem:COMMunicate:SERial:TRANsmit:SBITs < parameter >
Ę	parameter	1 or 2
Parameterizatio	Comments:	depending on the desired number of stop bits $Q \ u \ e \ r \ y$ On the entry of the query form
no		<i>form:</i> ":SYST:COMM:SER:TRAN:SBITs?", one obtains the current number of stop bits per character from the device.
Configurati		Response: 1 -> 1 stop bit/character 2 -> 2 stop bits/character
c		Reset value: 1
Calibratio	Example:	1 stop bit/character: OUTPUT 709;":SYST:COMM:SER:TRAN:SBIT 1"
Techn. Specifica- tions & Appendix	Page 6 - 3 - 73	

Tem:CO	MMunicate:SERial:TYPE	Installation
This comman or half duplex	d selects the type of connection for the RS485 interface (full	tion
:SYSTem:CC	MMunicate:SERial:TYPE < <i>parameter</i> >	Opera
FULL HALF	-> full duplex -> half duplex	rameterization
Query form: Reset value:	On the entry of the query form "SYST:COMM:SER:TYPE?", the device sends the current setting of the type of connection for the RS485 interface. Response: HALF or FULL FULL	Configuration Pa
Selecting the OUTPUT 70	full duplex connection for the RS485 : 9;":SYST:COMM:SER:TYPE FULL"	Calibration
	Tem:CO This comman or half duplex SYSTem:CO FULL HALF Query form: Reset value: Selecting the OUTPUT 709	Tem:COMMunicate:SERial:TYPE This command selects the type of connection for the RS485 interface (full or half duplex). :SYSTem:COMMunicate:SERial:TYPE < parameter > FULL -> full duplex HALF -> half duplex HALF -> half duplex

stallation	SYST	em:COMMunicate:GPIB:ADDRess
Ë	Description:	This command selects the address of the GPIB bus interface.
Operation	Syntax:	:SYSTem:COMMunicate:GPIB:ADDRess < parameter >
	parameter	030
ation		depending on the desired address of the GPIB interface
Parameteriz	Comments:	Query form: On the entry of the query form "SYST:COMM:GPIB:ADDR?", one obtains the current
tion		setting of the GPIB address from the device.
Configura		Response: 030 Reset value: 9
	Example:	Setting the address to 10:
Calibration		10 OUTPUT 709;":SYST:COMM:GPIB:ADDR? 10" 20 ENTER 710;A\$! new GPIB address 30 PRINT A\$ 40 END
echn. Specifica- ons & Appendix		

Page 6 - 3 - 75



	SY	STem	:DA	ATE
--	----	------	-----	-----

	SYSTem:DATE		Installation
Description:	This command selects the date on the device.		
Syntax:	:SYSTem:DATE < parameter >		Operation
parameter	<year>,<month>,<day></day></month></year>		
C	<year> -> year entry with century <month> -> month entry <day> -> day entry</day></month></year>	(e.g. 1991) (e.g. 9) (e.g.23)	Parameterization
Comments:	Q u e r y On the entry of the query for form: response obtained is the date cu	m":SYSTem:DATE?", the rrently set in the device.	ion
	Response of the device:		Jural
	<year>,<month>,<day> (e</day></month></year>	e.g. 91,09,23)	Config
	When the date is set, the year must be entered w	vith the appropriate century.	u
	In the response of the device, the year is stated	without century.	Calibrat
Example:	Setting and requesting the date:		ming
	10 OUTPUT 709;":SYSTEM:DATE? 1991,09 20 ENTER 709;A\$ 30 PRINT A\$	9,23"	Program
	40 END		di X
	Response of the device: 91,09,23		hn. Specifi is & Appen
		Page 6 - 3 - 76	Tec

RESISTOMAT®



SYSTem:ERRor? Installation Description: With this command, an error message is read out from the error buffer. Syntax: :SYSTem:ERRor? Operation Comments: only query form no parameters The error buffer has a size of 2: Parameterization One buffer for the first error message and one buffer for the "QUEUE OVERFLOW" message. The error buffer is a "first in first out" buffer. When an error is read out of the error buffer, it is deleted. When all error messages have been read out of the error buffer, or when no error has occurred, the device responds with "NO ERROR". Configuration The error message consists of: <error number>,"<error description>" Negative error messages are defined by the SCPI standard. Positive error messages indicate device-dependent errors. Calibration Error messages of the Resistomat 2304: 0,"NO ERROR" No error occurred -400,"QUERY ERROR" Programming Device was polled but no data was present -410,"QUERY INTERRUPTED" Device was interrupted without having sent a complete response -420,"QUERY UNTERMINATED" Techn. Specifica-tions & Appendix Device was polled without having received a complete command -200,"EXECUTION ERROR" Due to a certain state of the device, a command could not be executed (e.g. the device was performing a measurement).

Page 6 - 3 - 77

burster RESISTOMAT®

Type 2304

Installation

Operation

Parameterization

Configuration

SYSTem:ERRor?

-220,"PARAMETER ERROR" A command with an incorrect parameter was sent

-100,"COMMAND ERROR" An invalid command was sent

-105,"GET NOT ALLOWED" A GET command was sent within a command

-110,"COMMAND HEADER ERROR" Command with invalid command heading

10,"VCABLE" Cable rupture on measuring resistor

20,"VKOVER" Amplifier overdriven

30,"OVERRANGE" Range transgression

40,"TEMP OVER" Temperature of device too high (possible fan breakdown!)

50,"MEASURE ERROR" Error occurred during measurement

60,"CURRENT ERROR" Current cannot be controled (possible cable rupture)

Example:

Polling the error buffer:

10 OUTPUT 709;":SYSTEM:ERROR?" 20 ENTER 709;A\$ 30 PRINT A\$ 40 END

possible response of the device: 0,"NO ERROR"

Page 6 - 3 - 78

nstallation		SYSTem:KEYBoard:ACCess
	Description:	This command selects the access authorization for the keyboard on the front panel.
eration	Syntax:	:SYSTem:KEYBoard:ACCess < parameter >
Ope	parameter	FULL->full keyboard accessRANGe->measurement + range selectionMEASume>arkumanum
Parameterization	Comments:	Query form: On the entry of the query form "SYSTem:KEYBoard:ACCess?", the device supplies the currently selected access authorization for the keyboard on
Configuration		FULL -> full access RANG -> measurement + range selection MEAS -> only measure
ation		Reset value: FULL
Calibr	Example:	Keyboard access only for starting and stopping measurements: OUTPUT 709:":SYSTEM:KEYBOARD:ACCESS MEASURE"
Programming		
Techn. Specifica- tions & Appendix	Page 6 - 3 - 79	

burster RESISTOMAT®

edinganaa Statest San Afrikan ang ang Kita ang a	SYS	Tem:KLOCk	Installation
Description:	This command lo	cks the keyboard on the front panel of the device.	
Syntax:	:SYSTem:KLOC	< < parameter >	oeration
parameter	parameter	Einstellung	Ō
	ON OFF	Keyboard locked Keyboard released	tíon
Comments:	<i>Query form:</i> On Re loc	the entry of the query form ":SYSTem:KLOCk?", the s2304 responds with the current setting of the keyboard k.	Parameteriza
	Re Reset value:	sponse: Keyboard locked -> 1 Keyboard released -> 0 OFF	Configuration
	When the device also be locked wi	is controlled via the IEC bus interface, the keyboard can th the IEEE488.1 LOCAL LOCKOUT command.	Calibration
Example:	Lock keyboard:		
	OUTPUT 709;":	SYSTEM:KLOCK ON"	hn. Specifica- Is & Appendix
		Page 6 - 3 - 80	Tec

RESISTOMAT®



tallation		SYSTem:PRESet
	Description:	This command carries out a device reset with preset values.
Operation	Syntax:	:SYSTem:PRESet
Parameterization	Comments:	no query form no parameters After this reset, the device is set to front panel operation. PIf the device is to be controlled via serial interface, it must be set to the desired interface manually. If it is to be controlled by the GPIB no
Configuration		Conversion is necessary, as the device selects the IEEE488 interface control as a reset value.The values of the individual parameters after a SYSTEM:PRESET are stated as <i>reset values</i> under the respective commands in the command list.
Calibration		The values of the calibration data and the entries in the control are not lost.
Techn. Specifica- tions & Appendix	Page 6 - 3 - 81	



SYSTem:TIME

	SYSTem:TIME	Installation			
Description:	This command sets the time on the device.	and the second sec			
Syntax:	:SYSTem:TIME < parameter >	Operation			
parameter	<hours>,<minutes>,<seconds></seconds></minutes></hours>				
Commonto:	<hours> -> 023 <minutes> -> 059 <seconds> -> 059</seconds></minutes></hours>	arameterization			
Comments:	<i>Query form</i> On the entry of the query form "SYSTem:TIME?", the device supplies the time at which the command was received.				
	Response:	igura			
	<hours>,<minutes>,<seconds> (e.g. 12,30,45)</seconds></minutes></hours>	Conf			
Example:	Requesting the time 10 OUTPUT 709;":SYSTEM:TIME?" 20 ENTER 709;A\$	Calibration			
	30 PRINT A\$ 40 END	buju			
	Setting the time	Jramı			
	OUTPUT 709;":SYSTEM:TIME 12,30,45"	Proč			
	Page 6 - $3 - 82$	Techn. Specifica- tions & Appendix			

Installation



TRACe:DATA

Description: By m

By means of this command, the parameter values for each display mode are entered.

Syntax:

TRACe:DATA < parameter >

parameter

Display mode	parameter	Setting
Ohm/m and Ohm/km	LENGTH0,0.0019999999	Entry of the length in meters
Ohm/10 ft and Ohm/kft	LENGTH0,0.0019999999	Entry of the length in feet
Delta%	NOMINAL,1e ⁻⁷ 9999999e ³	Entry of the specified value in ohms
Rho1 and Gamma1	LENGTH1,0.0199.999 AREA,1e ⁻⁵ 99999999	Length in meters Cross-section in mm ²
Rho2 and Gamma2	MASS,1e ⁻⁵ 999999.9 LENGTH2,0.0199.999 DENSITY,0.0199.0 LENGTH3,0.0199.999	Mass in g Length in meters Density in g/cm ³ Measure length in meters

Operation Parameterization Configuration Calibration Programming Techn. Specifica-tions & Appendix



Installation

Operation

TRACe:DATA

Comments:

Example:

Query form: On the entry of the query form "TRACe:DATA?", the device supplies the parameter values of the current display mode accompanied with the corresponding unit.

Display mode	Response of the device	ç
Delta%	<specified value=""></specified>	rizatio
Ohm/m und Ohm/km	<length></length>	Parameter
Ohm/10ft und Ohm/kft	<length></length>	ration
Rho1 und Gamma1	<length>,<cross-section></cross-section></length>	Configu
Rho2 und Gamma2	<mass>,<length>,<density>,<measure-length></measure-length></density></length></mass>	ation
In the "Ohm" display mo command.	ode, no parameter is returned on the "TRACe:DATA?"	Calibr
Setting the display mo (100m).	de to "Ohm/m" and entering the "Length" parameter	Programming

10 OUTPUT 709;":CALC:MATH:EXPR R/LENGTH0[M]" 20 OUTPUT 709;":CALC:STAT ON" 30 OUTPUT 709;":TRAC:DATA LENGTH0,100" 40 END

Techn. Specifications & Appendix

RESISTOMAT[®] burster

Istallation	TRIGger:SOURce							
5	Description:	This command selec	ts the trigger source which is to be responded to.					
Operation	Syntax: parameter	:TRIGger:SOURce < <i>parameter</i> > <i>neter</i> The desired trigger source is selected with the parameter.						
ization		parameter	Description					
Parameter		IMMediate BUS	A measurement-start command is executed at once A measurement-start command is only executed after a group-execute-trigger is received					
Configuration	Comments:	Comments: Query form.On receiving the query form, the device sends the current trigger setting.						
ration		Trigg Trigg	er passive -> IMM er active -> BUS					
Calib		Reset value:	IMM					
Programming	Example:	10 OUTPUT 709;": 20 OUTPUT 709;": 30 : : ! set other device	TRIGGER:SOURCE BUS" !react to GET INITIATE" !measurement-start command					
Specifica- Appendix		: 80 90 SEND 7;CMD 8 100 END	!send GET -> start measurement					
Techn. tions &	Page 6 - 3 - 85							



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Installation	anna fa sua sua sua sua sua sua sua sua sua su	CCURve:ABORt
	Description:	This command stops measurement of the cooling curve.
Operatio	Syntax:	:CCURve:ABORt
erization	Comments:	no query form
aramete		no parameters If the command is not sent after the cooling-curve measurement has begun,
Configuration	Example:	the measurement ends after 256 measured values. On this command, the "cooling-curve menu" is shown on the display. At the same time, CCURve:STATe ON is switched, irrespective of its previous state.
Calibration		see "CCURve:STATe" command
Techn. Specifica- tions & Appendix	Page 6 - 3 - 87	



	escription: With this command, the ambient temperature of the test unit before the					
Description:	With this com measurement	mand, the ambient temperature of the test unit before the s entered manually.	eration			
Syntax:	CCURve:BTE	Mperatur < parameter >	ŏ O			
parameter	-99.9999.9	(in degrees Celsius)	Б			
Commonts	depending on	the ambient temperature	Parameterizati			
Comments.	Query form:	On the entry of the query form "CCURve:BTEMperature?", the device supplies the current setting of the ambient temperature before the measurement. Response: e.g. 23.4CEL	Configuration			
	For setting the The device ready With this com the same time state.	e temperature manually, the parameter is sent without a unit. sponds with a "CEL" unit. mand, the "cooling-curve menu" is shown on the display. At CCURve:STATe ON is switched, irrespective of its previous	Calibration			
Example:	see "CCURve	:STATe" command Page 6 - 3 - 88	Techn. Specifica- tions & Appendix			

RESISTOMAT® bur



Istallation		CCURve:CLEAr
	Description:	The cooling memory is cleared with this command.
Operation	Syntax:	CCURve:CLEAr
Parameterization	Comments:	no parameters
ation		no query form
Configur		With this command, the "cooling-curve menu" is shown on the display. At the same time, CCURve:STATe ON is switched, irrespective of its previous state.
Calibration		
Programming	Example:	OUTPUT 709;"CCURVE:CLEAR"
Techn. Specifica- tions & Appendix	Page 6 - 3 - 89	



Installation

CCURve:BTEMperatur:INITiate

Description:	With this	command,	the	ambient	temperature	of	the	test	unit	before
	measurem	ent is record	led a	utomatica	ally.					

Syntax: CCURve:BTEMperatur:INITiate

Comments:

no parameters

no query form

An external Pt 100 sensor must be connected to the device.

With this command, the "cooling-curve menu" is shown on the display. At the same time, CCURve:STATe ON is switched, irrespective of its previous state.

Example:

see "CCURve:STATe" command

Operation Parameterization Configuration Calibration Programming Techn. Specifica-tions & Appendix

RESISTOMAT[®] burster



Installation	CCURve:CHARge			
eration	Description:	With this command, the removal of the load on the test unit is signalled to the device.		
ð	Syntax:	:CCURve:CHARge < parameter >		
eterization	parameter	OFF		
Param	Comments:	no query form		
lion		Instead of "OFF", "0" can also be sent as a parameter.		
igurat		The command starts an internal stopwatch for the cooling-curve measurement.		
Conf		With this command, the "cooling-curve menu" is shown on the display. At the same time, CCURve:STATe ON is switched, irrespective of the previous state.		
Calibration	Example:	OUTPUT 709;":CCURVE:CHARGE OFF"		
chn. Specifica- ns & Appendix				
Tec	Page 6 - 3 - 91			



Installation

CCURve:CRESistance

Description: With this command, the cold resistance of the test unit is entered manually.

Syntax: CCURve:CRESistance < parameter >

parameter 0...9999999 KOHM

depending on the cold resistance value

Comments: *Query form:* On the entry of the query form "CCURve:CRESistance?", the device supplies the current setting of the cold resistance with the corresponding unit.

Response: e.g. 1000HM

If the parameter is sent without a unit, it is assumed to have a unit of "Ohms".

With this command, the "cooling-curve menu" is shown on the display. At the same time, CCURve:STATe ON is switched, irrespective of its previous state.

Example: OUTPUT 709;":CCURVE:CRESISTANCE 1000HM"

nstallation	CCURve:CRESistance:ABORt	
E	Description:	With this command, the measurement of the test unit's cold resistance is stopped.
Operatio	Syntax:	:CCURve:CRESistance:ABORt
erization	Comments:	no parameters
ramete		no query form
ъ В В		With this command, the "cooling-curve menu" is shown on the display. At the same time, CCURve:STATe ON is switched, irrespective of its previous state
Configuratio	Example:	state. see "CCURve:STATe" command
Calibration		
echn. Specifica- ons & Appendix		
tio Te	Page 6 - 3 - 93	



	CCURve:CRESistance:INITiate	Installation
Description:	With this command, the cold resistance of the test unit is measured.	ion
Syntax:	:CCURve:CRESistance:INITiate	Operat
Comments:	no parameters no query form If the device is set to repetition measurement, the cold resistance measurement must be stonged with the "CCUR verCRES istance: A BORt" command	Parameterization
	With this command, the "cooling-curve menu" is shown on the display. At the same time, CCURve:STATe ON is switched, irrespective of its previous	Configuration
Example:	see "CCURve:STATe" command	Calibration
	Page 6 - 3 -94	Techn. Specifica- tions & Appendix

RESISTOMAT® bursler



CCURve:DELay

CCURve:DELay		
Description:	With this command, the time interval between the cooling-curve	lnst
	measurements is set.	tion
Syntax:	:CCURve:DELay < parameter >	Opera
parameter	0999999.99S	
	depending on the desired delay time.	rization
Comments:	<i>Query form:</i> On the entry of the query form "CCURve:DELay?", the device supplies the current setting of the delay time.	Paramete
	Response: 099999.99s	Iration
	The parameter can be sent with a unit of seconds ("S"), milliseconds ("MS") or without a unit. If the unit is omitted, "S" is assumed.	Configu
	If 0S is sent as a parameter, as many measured values as possible are recorded.	Lo Lo
	With this command, the "cooling-curve menu" is shown on the display. At the same time, CCURve:STATe ON is switched, irrespective of its previous state.	Calibrati
Example:	see "CCURve:STATe" command	amming



CCURve:ETEMperatur

Installation Description: With this command, the ambient temperature of the test unit after the measurement is entered manually. Operation Syntax: CCURve:ETEMperatur < parameter > Parameterization -99.9...999.9 (in degrees Celsius) parameter depending on the ambient temperature Comments: Query form: On the entry of the query form "CCURve:ETEMperature?", Configuration the device supplies the current setting of the ambient temperature after the measurement. Response: e.g. 23.4CEL For setting the temperature manually, the parameter is sent without a unit. The device responds with a "CEL"unit. Calibration With this command, the "cooling-curve menu" is shown on the display. At the same time, CCURve:STATe ON is switched, irrespective of its previous state. Programming Example: see "CCURve:STATe" command Techn. Specifica-tions & Appendix



(CCURve:ETEMperatur:INITiate	Installation
Description:	With this command, the ambient temperature of the test unit after the measurement is registered automatically.	ation
Syntax:	CCURve:ETEMperatur:INITiate	n Opera
Comments:	no parameters no query form With this command, the "cooling-curve menu" is shown on the display. At the same time, CCURve:STATe ON is switched, irrespective of its previous state. An external Pt100 sensor must be connected to the device.	onfiguration Parameterization
Example:	see "CCURve:STATe" command	Calibration
	Page 6 - 3 - 98	Techn. Specifica- tions & Appendix

RESISTOMAT®



Installation	CCURve:PRINter				
tion	Description:	With this command, a printer is activated in order to output the cooling-cur measurement results.			
Opera	Syntax: :CCURve:PRINter < parameter >				
ation	parameter.	parameter	Setting		
eteriz		ON	measurement results are sent via serial interface.		
Param		OFF	measurement results are sent via GPIB.		
Configuration	Comments:	 Q u e r y On the entry of the query form "CCURve:PRINter?", the device supplies the current state of the serial printer. Response: 0 or 1 			
Calibration		The command is interface.	ineffective when the device is controlled via the serial t results are sent on the "CCURve:DATA?" command.		
ming		With this command, the "cooling-curve menu" is shown on the display. At the same time, CCURve:STATe ON is switched, irrespective of its previous state.			
Program		Reset value:	OFF		
Techn. Specifica- tions & Appendix	Example: Page 6 - 3 - 99	see "CCURve:ST	ATe" command		

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Type 2304

Installation

Operation

Parameterization

CCURve[:STATe]

Description: This command activates the "cooling-curve menu".

Syntax: :CCURve:STATe < parameter >

parameter:

parameter	Setting
ON	Cooling-curve menu on
OFF	Cooling-curve menu off

Comments:

Query On the entry of the query form "CCURve[:STATe]?", the device supplies the current setting of the measurement mode.

0 -> normal measurement 1 -> cooling-curve measurement

If the device is not in the cooling-curve mode when a cooling-curve command is sent, the device activates the cooling-curve mode.

When the device is in the cooling-curve mode, all "non-cooling-curve" commands are disabled. In order for such commands to be executed, the cooling-curve mode must first be deactivated with the "CCURve:STATe OFF" command.

Reset value: OFF



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nstallation	CCURve:INITiate			
Operation	Description:	With this command, the cooling-curve measurement will be activated.		
	Syntax:	CCURve:INITiate		
arameterization	Comments:	no parameters no query form		
Configuration		With this command, the "cooling-curve menu" will be displayed. Simultaneous the CCURve:STATe will be switched ON indepedence of the previous state.		
Calibration	Example:	see "CCURve:STATe" command		
Techn. Specifica- tions & Appendix	Page 6 - 3 - 101			



Installation

CCURve[:STATe]

			1
Example:	Example of setting the cooling-curve menu, with output of t results to a serial printer. 10 ! cooling-curve menu - on 20 OUTPUT 709:":CCUR:STAT ON"	he measurement	Operation
	30 ! enter cold resistance		
	40 OUTPUT 709;":CCUR:CRES 1000HM" 50 I set delay time (one measured value every minute)		Б
	60 OUTPUT 709;":CCUR:DEL 60S"		zati
	70 ! activate printer		teri
	90 ! measure initial temperature and request it		ame
	100 OUTPUT 709;":CCUR:BTEM:INIT"		Jara
	110 OUTPUT 709;":CCUR:BTEM?"		
	120 ENTER 709; btemps 130 ! removal of load		ion
	140 OUTPUT 709;":CCUR:CHAR OFF"		urat
	150 ! measure final temperature and request		nfigu
	170 OUTPUT 709;":CCUR:ETEM:INIT		Cor
	180 ENTER 709;etem\$		
	190 ! start cooling-curve measurement		6
	210 ! wait until 256 measured values have been recorded		tio
			ibra
	240 I measured results to serial printer		Cal
	250 OUTPUT 709;":CCUR:DATA?"		
	260 OUTPUT 709;":CCUR:STAT OFF"		o
			Programmin
			fica- ndix
			ppe
			& <u>^</u>
			sur
		Page 6 - 3 - 102	H E C E

Page 6 - 3 - 102


Status - Message Commands

Installation Operation Parameterization Configuration Calibration Programming Techn. Specifica-tions & Appendix

Page 6 - 3 - 103

Installation		STATus:OPERation:ENABle		
Operation	Description:	This command sets the enable mask for the "operation - event" register.		
	Syntax:	:STATus:OPERation:ENABle < parameter >		
Parameterization	Comments:	 parameter 065535 Query form: On the entry of the query form "STATus: OPERation:ENABle?", the device supplies the decimal value of the contents of the operation status register. 		
ď		Response: 065535		
Configuratio		The parameter is the decimal value of the mask for the operation status enable register.		
		register.		
alibration		Reset value: 0		
0	Example:	Desired enable mask: 0000 0000 0001 0000		
lix Programming		OUTPUT 709;":STAT:OPER:ENAB 16"		
Techn. Specific tions & Append	Page 6 - 3 -104			



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Mit Stady, Mit Stady, Mit Stady, J. Statement S. M. Mit Statement of P. Statement	STATus:OPERation:EVENt?	Installation
Description:	This command polls the contents of the operation status event register.	ation
Syntax:	:STATus:OPERation:EVENt?	Opera
Comments:	only query form; the event register is cleared after read-out.	leterization
Example:	10 OUTPUT 709;":STATUS:OPERATION:EVENT?" 20 ENTER 709;A\$	Param
	30 PRINT A\$ Response of the device: 065535	Configuration
		Calibration
		chn. Specifica- ns & Appendix
	Page 6 - 3 - 105	Tec

RESISTOMAT®



STATus:PRESet			
Description:	This command clears the masks of the enable register.		
Syntax:	:STATus:PRESet		
Comments:	no parameters		
Example	OUTPUT 700.".STATUS.DDESET"		
DAumpio.	OUTFUT 709, .STATUS:PRESET		
	·		
Page 6 - 3 - 106			
	Description: Syntax: Comments: Example:		

Г

	STATus:QUEStionable:ENABle	stallation
Description:	This command sets the enable mask for the "questionable event" regis	ter.
Syntax: parameter:	:STATus:QUEStionable:ENABle < parameter > 065535	Operation
Comments:	Query form: On the entry of the query form: STATus:QUEStionable:ENABle?", the device supplies decimal value of the contents of the questionable staregister. Response: 065535	the atus automatic
	The parameter is the decimal value of the mask for the questionable sta enable register. A bit set in the enable register releases the corresponding bit in the ever register.	rent Configuration
Example:	Reset value:0desired enable mask:0000 0000 0001 0000OUTPUT 709;":STATUS:QUESTIONABLE:ENABLE 16"	Calibration
	Page 6 - 3 - 107	Techn. Specifica- tions & Appendix

Installation	STATus:QUEStionable:EVENt?		
tion	Description:	This command polls the contents of the questionable status event register.	
Opera	Syntax:	:STATus:QUEStionable:EVENt?	
neterization	Comments:	only query form; the event register is cleared after read-out.	
Paran	Example:	10 OUTPUT 709;":STATUS:QUESTIONABLE:EVENT?"	
Configuration		20 ENTER 709;A\$ 30 PRINT A\$ Response of the device: 065535	
Calibration			
echn. Specifica- ons & Appendix			
투	Page 6 - 3 - 108		





allation			*CLS
Las Las	Description:	Clear Status command	
g		This command resets the IEEE488.2 status registers.	
Operatio	Syntax:	*CLS	
5		no parameters no query form	
rizati		Example: OUTPUT 709;"*CLS"	
mete			
Para			
ų			*ESE
Configurati	Description:	This command sets or polls the "STANDARD - EVEN ENABLE - REGISTER".	T - STATUS -
ation	Syntax:	*ESE < parameter >	
Calibra	parameter	0255 depending on the desired setting mask.	
D		Example: setting mask 0001 0000	
amming		OUTPUT 709;"*ESE 16"	
Progr	Query form:	*ESE?	
Specifica- Appendix		Response of the device: 0255 depending on the current set	tting mask.
Techn. S tions & /	Page 6 - 3 - 110		

burster RESISTOMAT®

	*ESR?	tailation
Description:	With this command, the "STANDARD - EVENT - STATUS - REGISTER"	s n s
Syntax:	*ESR? Example: 10 OUTPUT 709;"*ESR?" 20 ENTER 709;A\$ 30 PRINT A\$	Operation
Query form:	*ESR? only query form Response of the device: 0255	Parameterization
	*IDN?	Configuration
Description:	Identification Query This command interrogates the ID of the device. - Company name - Device name - Serial number - Device version	Calibration
Syntax:	*IDN? no parameters only query form Example: 10 OUTPUT 709;"*IDN?" 20 ENTER 709;A\$ 30 PRINT A\$ 40 END Response of the device: BURSTER,RESISTOMAT2304,SN123456,V1192	ons & Appendix Programming

Installation		*OPC
Operation	Description:	This command switches the device to the "operation complete active state" (OCAS). In the OCAS, the "operation complete bit" (bit 0) in the standard event status register is set when an operation has been completed.
Parameterization	Syntax:	*OPC no parameters Example: OUTPUT 709;"*OPC"
liguration		*OPC?
Conf	Description:	This commands switches the device to the "operation complete query active state" (OCQAS).
Calibration		In the OCQAS, the device writes "1 <cr><lf" a="" been="" buffer="" command="" executed.<="" has="" into="" output="" th="" the="" when=""></lf"></cr>
	Syntax:	*OPC?
Ding		only query form no parameters
Programn		Example: 10 OUTPUT 709;"*OPC?" 20 OUTPUT 709;":CAL:ZERO" 30 ENTER 709;A\$ 40 IF A\$ = "1 <cr><lf>" THEN GOTO CONTINUE ELSE</lf></cr>
Specifica- Appendix		GOTO 30 50 CONTINUE:! 60 . 70 .
Techn. tions &	Page 6 - 3 - 112	80 .

Page 6 - 3 - 112

burster RESISTOMAT®

			*RST	Installation
Description:	This command switches the	e device to a defined initial state	.	
C (The interface setting is not state, set to the interface vi	t changed, i.e. the device remain a which it was reset.	s in the remote	Operation
Syntax:	*RST			Ę
	no parameters no query form			leterizatio
	Example: OUTPUT	[709;"*RST"		Param
			*SRE	nfiguration
Description:	This command sets or pol REGISTER".	ls the "SERVICE - REQUEST	- ENABLE -	о С
Syntax:	*SRE < parameter >			Calibratio
parameter	0255 depending on the desired se	etting mask.		
	Example: setting mask	0001 0000		uming
	OUTPUT 709;'	'*SRE 16"		Progran
Query form:	*SRE?			<u>لا</u>
	Response of the device:	0255 depending on the current setting	ıg mask.	. Specific & Append
		Page	6 - 3 - 113	Techn tions (

Туре 2304

stallation		*STB?
	Description:	This command reads out the "STATUS - BYTE - REGISTER" with the master summary bit.
Operation	Syntax:	*STB?
ameterization	Query form:	Example: 10 OUTPUT 709;"*STB?" 20 ENTER 709;A\$ 30 PRINT A\$ 40 END *STB?
on Par		only query form
Configurati		depending on the current register content.
B		*TRG
Calibrati	Description:	Trigger command
nming	a .	This command is equivalent to the IEEE488.1 GET command for a particular device.
Prograr	Syntax:	*TRG no parameters no query form
Specifica- Appendix		Example: OUTPUT 709;"*TRG"
Techn. tions &	Page 6 - 3 - 114	

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Type 2304

*WAI

			*WAI	Installation
Description:	This command s The command d executes comm	ets a device so that all commands are exe oes not have any effect in the Res2304, as ands sequentially.	cuted sequentially.	Operation
Syntax:	*WAI no parameters no query form Example:	OUTPUT 709;"*WAI"		Parameterization

Configuration Calibration Programming

Techn. Specifica-tions & Appendix

. .



Installation

Operation

Table of contents, chapter 6-4

HP - IB commands

Introduction	6-4-2
ABORT (IFC)	6-4-4
CLEAR (DCL or SDC)	6-4-4
LOCAL (GTL)	6-4-5
LOCAL LOCKOUT (LLO)	6-4-6
REMOTE	6-4-7
SPOLL (Serial Poll)	6-4-8
TRIGGER (GET)	6-4-9





HP-IB commands

Introduction

The HP-IB BASIC COMMANDS in this chapter are meant especially for the HP series 200/300 computer. Every other IEEE488 controller can also send these commands. In terms of syntax, however, their commands could differ from the ones listed here. The IEEE488 command abbreviations are stated in parentheses after every HP-IB command.

All examples presuppose that the Interface Select Code of the HP-IB interface is set to 7 and the device address set to 9.



ANSI/IEEE488.1 - 1987 capabilities

IEEE488.1 function	Code	Description
Source Handshake	SH1	Enables the Res2304 to transfer multi-wire information.
Acceptor Handshake	AH1	Enables the Res2304 to receive multi-wire information.
Talker	Т6	Enables the Res2304 to transmit data via the GPIB. Enables the Res2304 to respond to the serial poll.
Listener	L4	Enables the Res2304 to receive data via the GPIB.
Service Request	SR1	Enables the Res2304 to send a service request to the controller.
Remote/Local	RL1	Enables control of the Res2304 via the front panel keyboard (local) or the GPIB(remote).
Parallel Poll	PP0	No capability.
Device Clear	DC1	Enables the Res2304 to be brought into a defined state by means of the Device Clear command.
Device Trigger	DT1	Enables the Res2304 to be triggered via the GPIB.
Controller Function	C0	No capability.
Driver Electronics	E1	Open - Collector GPIB driver.

Page 6 - 4 - 3



Installation

Operation

Parameterization

ABORT (IFC)

Description:	Interface clear command: Resets the GPIB interface of the Res2304.		
Syntax:	ABORT 7		
Example:	ABORT 7	! resets the interface.	

CLEAR (DCL oder SDC)

	CLEAR	(DCL oder SDC)	ation
Description:	Device clear o	r Selected device clear command:	Configur
	 clears the inp clears the out resets the cor brings the det brings the det 	but buffer iput buffer mmand interpreter. vice into the operation-complete-COMMAND-idle state. vice into the operation-complete-query-idle-state.	Calibration
Syntax:	CLEAR 7 CLEAR 709		gramming
Example:	CLEAR 7	! Device clear; resets all devices on the bus.	Pro
	CLEAR 709	! Selected device clear; resets the device with address 9.	chn. Specifica- ns & Appendix
		Page 6 - 4 - 4	Tec

RESISTOMAT®



stallation			DCAL (GTL)					
<u>ٿ</u>	Description:	Go to local con	umand:					
oeration		resets the Res2304 to front panel operation.						
lo u	Syntax:	LOCAL 7 LOCAL 709						
Parameterizatio	Comments:	If the LOCAL LOCKOUT, the	key of the Res2304 has been disabled through a LOCAL e Res2304 can be switched to front panel operation through AL 709 However, a subsequent remote command disables					
Configuration		front panel oper	ration again. In contrast, the LOCAL 7 command also enables ration after a subsequent remote command.					
tion	Example:	LOCAL 7	! Sets the FALSE IEEE488 bus line (all devices are switched to LOCAL operation). The command is cancelled with the REMOTE 7 command.					
Calibra		LOCAL 709	! Sets the device with address 9 to LOCAL operation by sending the GTL interface message.					
Techn. Specifica- tions & Appendix Programming	Page 6 - 4 - 5							



	LOCAL LOCKOUT (LLO)	Installation
Description:	Disables the local key of the Res2304.	
Syntax:	LOCAL LOCKOUT 7	Operation
Comments:	If the Res2304 is in the LOCAL operation mode when sending the LLO command, it remains in LOCAL. If the Res2304 is in the remote opertion mode, the local key is disabled at once.	ization
	If the keyboard has been disabled through a LOCAL LOCKOUT, it can be enabled a again though the LOCAL 7 command. The LOCALL 709 command also enables the keyboard; however, it is disabled again after a REMOTE command.	Parameter
Example:	LOCAL LOCKOUT 7 ! sends an LLO to all devices	Configuration
		Calibration
		In. Specifica- Rependix Programming
	Page 6 - 4 - 6	Tech tions

RESISTOMAT®



itallation		R	EMOTE
uns Ins	Description:	Sets the REN IE	EE488 bus line.
Operation	Syntax:	REMOTE 7 REMOTE 709	
erization	Comments:	The REMOTE 7 state. The REMO the REMOTE st assumes the RE	09 command switches the Res2304 into the REMOTE OTE 7 command alone does not switch the Res2304 into ate. After the REMOTE 7 command, the Res2304 only MOTE state upon receiving its listener address.
Paramet	Example:	REMOTE 7	! Sets the REN IEEE488 bus line This instruction does not switch the Res2304 into the REMOTE state
Configuration		REMOTE 709	! Sets the REN line and addresses device 9 This instruction switches the Res2304 into the REMOTE state.
Calibration			:
Techn. Specifica- tions & Appendix	Page 6 - 4 - 7		



	SPOLL (Serial Poll)	I Installation
Description:	The SPOLL command corresponds to the IEEE488.2 command *STB The number sent back is the weighted sum of the bits in the status by register.	?. beration
Syntax:	$\mathbf{P} = \mathbf{SPOLL}(709)$	ization
Comments:	The serial poll command differs from the *STB? command in that it do not load the microcontroller of the device. The status byte is returned to the GPIB chip of the Res2304.	Parameter
Example:	The meanings of the individual bits of the status byte are described in the chapter titled "STATUS MESSAGES." 10 P=SPOLL(709) !Serial poll 20 DISP P Display of the response	onfiguration
	30 END The meanings of the individual bits of the status byte are described in the chapter titled "STATUS MESSAGES."	Calibration
		D



RESISTOMAT[®]



Installation		TRIGGER (GET)
Operation	Description:	Group execute trigger: When the trigger setting of the Res2304 is on "active", the TRIGGER command starts a resistance measurement.
arameterization	Syntax:	TRIGGER 7 TRIGGER 709
Configuration P	Example:	The TRIGGER command only triggers the Res2304 when the trigger setting of the Res2304 is on "active". When the trigger setting is on "passive", the trigger command does not have any effect. TRIGGER 7 ! GET to all devices
Calibration		TRIGGER 709 ! GET to the device with address 9
Programming		
Techn. Specifica- tions & Appendix	Page $6 - 4 - 9$	



Table of contents, chapter 6-5

Sample program for controlling the RESISTOMAT 2304 via the RS232 interface with a PC-AT as system controller.

Introduction	
Sample program 1	
Explanation of sample program 1	6-5-5
Sample program 2	



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Installation

Operation

Introduction

Examples

The following examples illustrate the control of the Resistomat 2304 via the serial interface. The ANSI standard ANSI X3.28 Subcat.2.5, A3 serves as the communication protocol. The sample program is written in GW - Basic on a PC-AT with MS-DOS Version 3.3.

The display contrast is set to 70%, and this setting is then polled.

The Resistomat must be set to RS232 in the interface menu. Its hardware settings should be as follows: 9600 bauds, no parity, 8 data bits, 1 stop bit.

Techn. Specifications & Appendix

Page 6 - 5 - 2

Installation

RESISTOMAT[®] burste

Sample program 1

10 REM Sample program for controlling the Resistomat2304 via

20 REM theRS232 interface in accordance with ANSI X3.28 Subcat.2.5, A3

30 STX\$ = CHR\$(2)

- 40 ETX\$ = CHR\$(3)
- 50 EOT\$ = CHR\$(4)
- 60 ENQ\$ = CHR\$(5)
- 70 ACK\$ = CHR\$(6)
- 80 LF\$ = CHR\$(10)
- 90 NAK\$ = CHR\$(21)

100 OPEN "COM1:9600,N,8,1" AS #3

110 PRINT #3,EOT\$

115 CLS

120 INPUT "Enter the group address of the Resistomat2304 :(0..f) ";GRADR\$

130 INPUT "Enter the user address of the Resistomat2304 :(0..f) ";USADR\$

135 REM Formation of the selection supervisory sequence

140 SELSEQ\$ = EOT\$+GRADR\$+GRADR\$+USADR\$+USADR\$+"sr"+ENQ\$

150 REM Formation of the polling supervisory sequence

160 POLSEQ\$ = EOT\$+GRADR\$+GRADR\$+USADR\$+USADR\$+"po"+ENQ\$

170 REM

180 REM Set the Resistomat2304 as a slave

190 REM -> Selection supervisory sequence

200 REM

210 PRINT #3,SELSEQ\$

Page 6 - 5 - 3

Туре 2304

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	c
220 REM	atio
230 REM Fetch the response of the device (ACK or NAK)	talls
240 REM	lns
250 RES = INPUT(1,#3)	
260 IF RES\$<>ACK\$ THEN PRINT "Selection sequence not recognized":END	
270 REM	ion
280 REM 2304 is set as a slave	erat
290 REM SCPI Send command	ð
300 REM	
310 SCPI\$ = STX\$+":display:contrast? 0.7"+LF\$+ETX\$	uo
320 PRINT #3,SCPI\$	zati
330 REM	teri
340 REM Fetch the response of the device (ACK or NAK)	ame
350 REM	Para
360 RES = INPUT(1, #3)	
370 IF RES\$<>ACK\$ THEN PRINT "SCPI command not recognized":END	tior
380 REM	Jura
390 REM Fetch the response of the Resistomat 2304 to the SCPI query command	nfiç
400 REM -> Set the 2304 as master	ပိ
410 REM -> Send polling supervisory sequence	
420 REM	Ę
430 PRINT #3,POLSEQ\$	atic
440 REM	Idile
450 REM Response (display contrast"0.7")	Ŭ
460 REM	
470 CONT\$=INPUT\$(5,#3)	bu
480 REM	E
490 Terminate connection	grat
500 REMM	Proj
510 PRINT #3, EOT\$	
515 PRINT	fica
520 PRINT CONT\$:REM Indicate contrast	beci pel
530 END	Al Sp
	chn ns 8
Page 6 - 5 - 4	Te

Installation

Operation

Parameterization

Configuration

Calibration

Programming

Techn. Specifications & Appendix

Explanantion of sample program1 Lines 30 - 90 The ASCII characters required for communication are defined here (e.g. line feed = ASCII 10) Line 100 The serial interface of the PC is initialized here. The serial interface of the PC must be initialized in accordance with the setting on the Resistomat. The interface is assigned the input/output channel 3. Line 110 As system controller, the PC sends an EOT in order to deactivate any slaves present on the bus. Lines 120-130 Input of the group and user addresses. The addresses must be entered in 'hex' (0...f), and correspond with those set on the Resistomat. Line 140 The selection supervisory sequence is formed. Line 160 The polling supervisory sequence is formed. Line 210 The Resistomat2304 is initialized as a slave, in that the selection supervisory sequence is sent via the serial interface. Line 250 The response of the Resistomat2304 is read in via the serial interface. If ACK is received, the Resistomat is initialized as a slave and can receive SCPIs. Line 320 The SCPI "DISPLAY: CONTRAST? 0.7" is sent via the serial interface. Line 360 The response of the Resistomat2304 is read in via the serial interface. If ACK is received, the Resistomat has understood the command. Line 430 In order to fetch the requested setting of the display contrast, the Resistomat2304 is initialized as master. This is effected by sending the polling supervisory sequence. Line 470 The response of the Resistomat is fetched by the serial interface. Line 510 The connection is terminated. The master status is returned to the system controller (PC-AT).

Page 6 - 5 - 5

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Type 2304

Sample program 2

REM Sample program for controlling the Resistomat2304 via REM the RS232 interface in accordance with ANSI X3.28 Subcat.2.5, A3 REM (Start measurement and fetch measured value) REM REM language: QBASIC operating system: MS-DOS 5.0 REM baud rate: 9600 data bits: 8 stop bits: 1 parity : none

meas\$ = "" RES\$ = "" OPERSTAT\$ = "" a\$ = ""

REM Definition of the ASCII characters required for communication STX\$ = CHR\$(2) ETX\$ = CHR\$(3) EOT\$ = CHR\$(3) ENQ\$ = CHR\$(4) ENQ\$ = CHR\$(5) ACK\$ = CHR\$(5) ACK\$ = CHR\$(6) LF\$ = CHR\$(10) CRE\$ = CHR\$(13)NAK\$ = CHR\$(21)

REM Initializing the serial interface COM1 of the PC OPEN "COM1:9600,N,8,1" FOR RANDOM AS #3

REM As system controller, the PC sends an EOT in order to REM deactivate any slaves present on the bus PRINT #3, EOT\$

CLS

PRINT "Sample program for controlling the 2304 via the serial interface"

PRINT "9600 BAUD, 8 data bits, 1 stop bit, no parity"

PRINT "(Starting a measurement, polling the end-of-conversion bit",

PRINT "Fetching the measured value and stopping the measurement")

PRINT

REM Input of the group and user addresses. The addresses must be input in HEX format REM (0..f) and correspond with the addresses set on the 2304. INPUT "Input group address of the Resistomat2304 :(0..f) ";GRADR\$ INPUT "Input user address of the Resistomat2304:(0..f) "; USADR\$

REM Formation of the selection supervisory sequence SELSEQ\$ = EOT\$ + GRADR\$ + GRADR\$ + USADR\$ + "sr" + ENQ\$

REM Formation of the polling supervisory sequence POLSEQ\$ = EOT\$ + GRADR\$ + GRADR\$ + USADR\$ + "po" + ENQ\$

REM Set the Resistomat2304 as a slave REM -> Send the selection supervisory sequence PRINT #3, SELSEQ\$

REM Fetch the response 2304 (ACK or NAK) RES\$ = "" RES\$ = INPUT\$(1, #3) IF RES\$ <> ACK\$ THEN PRINT "Selection sequence not recognized!": END

REM A measurement currently in progress is stopped by sending the 2304 the SCPI REM "ABORT". PRINT #3, STX\$ + ":abort" + LF\$ + ETX\$

REM Fetch the response of the device (ACK or NAK) RES\$ = "" RES\$ = INPUT\$(1, #3) IF RES\$ <> ACK\$ THEN PRINT "ABORT Sequence not recognized!": END

REM The status registers of the 2304 are cleared by sending the IEEE488.2 REM command "*CLS". PRINT #3, STX\$ + "*CLS" + LF\$ + ETX\$

REM Fetch the response of the device (ACK or NAK) RES\$ = "" RES\$ = INPUT\$(1, #3) IF RES\$ <> ACK\$ THEN PRINT "*CLS sequence not recognized!": END

REM A measurement is started by sending the SCPI REM "INITIATE" SCPI\$ = STX\$ + ":initiate" + LF\$ + ETX\$ PRINT #3, SCPI\$

Programming

tions & Appendix

Specifica-

Techn.



Installation

Operation

Parameterization

Configuration

Calibration

Programming

Techn. Specifications & Appendix

REM Fetch the response of the device (ACK or NAK) RES\$ = "" RES\$ = INPUT\$(1, #3) IF RES\$ <> ACK\$ THEN PRINT "INITIATE Command not recognized!": END PRINT

PRINT "Measurement started!"

REM The measurement is started. Now the end-of-conversion bit REM (bit 9 of the operation status registers) is polled until a REM measured value is registered by the 2304.

Bit polling:

PRINT ".";

REM address the 2304 as a slave. PRINT #3, SELSEQ\$

REM Fetch the response of the device (ACK or NAK). RES\$ = "" RES\$ = INPUT\$(1, #3) IF RES\$ <> ACK\$ THEN PRINT "Selection sequence not recognized!": END

REM Poll the operation status register of the 2304. SCPI\$ = STX\$ + ":status:operation:event?" + LF\$ + ETX\$ PRINT #3, SCPI\$

REM Fetch the response of the device (ACK or NAK). RES\$ = "" RES\$ = INPUT\$(1, #3) IF RES\$ <> ACK\$ THEN PRINT "STATUS Command not recognized!": END

REM Fetch the contents of the operation status register of the 2304.
REM Initialize the 2304 as master.
REM -> Send polling supervisory sequence.
PRINT #3, POLSEQ\$

OPERSTAT\$ = "" a\$ = ""

REM Read in the response of the 2304. WHILE a\$ <> ETX\$ a\$ = "" a\$ = INPUT\$(1, #3) IF (a\$ <> STX\$) AND (a\$ <> ETX\$) AND (a\$ <> EOT\$) AND (a\$ <> LF\$) AND (a\$ <> CRE\$) THEN OPERSTAT\$ = OPERSTAT\$ + a\$ ELSE IF a\$ = EOT\$ THEN END WEND

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Installation REM Check end-of-conversion bit: REM When the EOC bit is set, a measured value is available, otherwise REM poll the bit again. IF ((VAL(OPERSTAT\$) AND 512) = 512) THEN GOTO Continue ELSE GOTO bit polling Continue: **REM** Fetch measured value Operation REM Initialize 2304 as slave PRINT PRINT #3, SELSEQ\$ REM Fetch the response of the device (ACK or NAK) Parameterization RES\$ = "" RES\$ = INPUT\$(1, #3) IF RES\$ <> ACK\$ THEN PRINT "Selection sequence not recognized": END REM Request measured value by sending the SCPI "FETCH?". SCPI\$ = STX\$ + ":fetch?" + LF\$ + ETX\$ PRINT #3, SCPI\$ Configuration REM Fetch the response of the device (ACK or NAK) RES\$ = "" RES\$ = INPUT\$(1, #3) IF RES\$ <> ACK\$ THEN PRINT "Fetch command not recognized": END REM Fetch the response of the Resistomat 2304 to the "FETCH?" command REM -> Set the 2304 as master Calibration REM -> Send the polling supervisory sequence REM PRINT #3, POLSEQ\$ REM REM Response (measured value) Programming REM meas\$ = "" a\$ = "" WHILE a\$ <> ETX\$ a\$ = "" echn. Specifica-ions & Appendix a = INPUT\$(1, #3) IF (a\$ <> STX\$) AND (a\$ <> ETX\$) AND (a\$ <> EOT\$) AND (a\$ <> LF\$) AND (a\$ <> CRE\$) THEN meas\$ = meas\$ + a\$ ELSE IF a\$ = EOT\$ THEN END **WEND**

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Туре 2304

REM The measurement is stopped in that the SCPI "ABORT" is sent. REM (Fast selection sequence) PRINT #3, EOT\$ + GRADR\$ + GRADR\$ + USADR\$ + USADR\$ + "sr" + ST ":abort" + LF\$ + ETX\$	'X\$ +	Installation
REM Fetch the response of the device (ACK or NAK) RES\$ = "" RES\$ = INPUT\$(1, #3) IF RES\$ <> ACK\$ THEN PRINT RES\$, "ABORT sequence not recognized": I	END	ration
PRINT "Measurement stopped!"		Ope
REM Terminate connection PRINT #3, EOT\$		ion
REM Display the measured value which has been read in PRINT PRINT "Measured value: "; PRINT meas\$	nd .	Parameterizati
CLOSE #3 END		Configuration
		Calibration
		Programming
Page 6 - 5	- 10	Techn. Specifica- tions & Appendix

-.
Table of contents, Chapters 7 - 1 to 7 - 6	Installation
Technical specifications and appendix	Operation
Technical specifications7-1-2	ation
Pin assignment 7-2-1	meteriz
IEC bus7-2-1	Para
Serial interfaces	guration
Digital inputs/outputs7-2-3	Confiç
Test unit connections 7-2-5	u
Error messages 7-3-1	Calibrati
Factory presettings ("Default-parameters")	
Printer character set 7-5-1	ramming
Function key overview	Prog



Technical specifications

Resolution and measuring current:

Resistance	range	Re	esolution*	Measuring current (bipolar)
			<u></u>	
200.00	μΩ	10	nΩ	10 A
2.0000	mΩ	100	nΩ	10 A, 1 A
20.000	mΩ	1	μΩ	10 A, 1 A, 100 mA
200.00	mΩ	10	μΩ	1 A, 100 mA, 10 mA
2.0000	Ω	100	μΩ	1 A, 100 mA, 10 mA, 1 mA
20.0000	Ω		mΩ	100 mA, 10 mA, 1 mA, 100 μA
200.00	Ω	10	mΩ	10 mA, 1 mA, 100 μA
2.0000	kΩ	100	mΩ	1 mA, 100 μA
20.000	kΩ	1	Ω	100 μA
		ŧ		

* on center setting

Measurement method:

Quotient process in 4-conductor Kelvin circuit

Techn, Specifications & Appendix

5	Maximum measurem	ent error f _{Lin, BIPOL} for BI	POLAR MEASUREN	IENT SEQUENCE:
Illatio	I	1/2 year	1 year	2 years
Insta	200 μ Ω range			
	10 A	$0.023\%\pm2$ Digits	$0.025\%\pm2$ Digit	$0.03\%\pm2$ Digits
c	2 m Ω range			
eratio	10 A 1 A	$0.015\%\pm2$ Digits $0.016\%\pm2$ Digits	$0.016\%\pm2$ Digits $0.018\%\pm2$ Digits	$\begin{array}{l} 0.018\% \pm 2 \text{ Digits} \\ 0.02\% \ \pm 2 \text{ Digits} \end{array}$
do	20 m Ω -Bereich			
ation	10 A 1 A 100 mA	0.012% ± 2 Digits 0.013% ± 2 Digits 0.015% ± 2 Digits	$0.013\% \pm 2$ Digits $0.014\% \pm 2$ Digits $0.016\% \pm 2$ Digits	0.015% ± 2 Digits 0.016% ± 2 Digits 0.018% ± 2 Digits
teriz	200 m Ω range			
Parame	1 A 100 mA 10 mA	0.011% ± 2 Digits 0.012% ± 2 Digits 0.014% ± 2 Digits	$0.012\% \pm 2$ Digits $0.013\% \pm 2$ Digits $0.015\% \pm 2$ Digits	0.014% ± 2 Digits 0.015% ± 2 Digits 0.017% ± 2 Digits
uo	2 Ω range			
onfigurati	1 A 100 mA 10 mA 1 mA	0.01% ± 2 Digits 0.01% ± 2 Digits 0.011% ± 2 Digits 0.013% ± 2 Digits	0.011% ± 2 Digits 0.011% ± 2 Digits 0.012% ± 2 Digits 0.014% ± 2 Digits	0.012% ± 2 Digits 0.012% ± 2 Digits 0.013% ± 2 Digits 0.015% ± 2 Digits
0	20 Ω range			
ibration	100 mA 10 mA 1 mA 100 μA	0.01% ± 2 Digits 0.01% ± 2 Digits 0.011% ± 2 Digits 0.013% ± 2 Digits	0.011% ± 2 Digits 0.011% ± 2 Digits 0.012% ± 2 Digits 0.014% ± 2 Digits	0.012% ± 2 Digits 0.012% ± 2 Digits 0.013% ± 2 Digits 0.015% ± 2 Digits
Cal	200 Ω range			
ing	10 mA 1 mA 100 μA	0.009% ± 2 Digits 0.009% ± 2 Digits 0.012% ± 2 Digits	0.01% ± 2 Digits 0.01% ± 2 Digits 0.013% ± 2 Digits	0.011% ± 2 Digits 0.011% ± 2 Digits 0.014% ± 2 Digits
amn	2 k Ω range			
Progr	1 mA 100 μA	$0.009\%\pm2$ Digits $0.012\%\pm2$ Digits	$\begin{array}{l} 0.01\% \ \pm 2 \ \text{Digits} \\ 0.013\% \pm 2 \ \text{Digits} \end{array}$	0.011% ± 2 Digits 0.014% ± 2 Digits
ģž	20 k Ω range			
ecifi	100 μA	0.012% ± 2 Digits	0.013% ± 2 Digits	0.014% 2 Digits
echn. Sp ions & Ap	A value of \leq 10 ppm/ye	ear can be entered as a	typical value for the le	ong-term stability.

Page 7 - 1 - 3

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Boundary c	onditio	ns for t	he mea	asurem	ent error tabl	e:				allation
Warm-up tin	ne for th	ne resol	ution hi	igh - 30	minutes, med	ium - 15	5 minut	es, low ·	- 5 minutes.	Inst
$Tu = 23^{\circ}C$ (1	aborato	ry conc	litions),	, careful	calibration in	accorda	ance wi	th chap.	5.3, VI,	
MEAS. TIM	E = 9, N	MEAS.	CURR	ENT =	LARGE/MED	IUM, N	IEAS. S	SEQUE	NCE = BIPOLAR,	
Display valu	$e \le 70$ §	% (1.40	0/14.00)0/140.(000 Digits)					eratio
Measureme	nt erro	rs unde	er boun	dary c	onditions devi	iating f	rom the	ese para	meters:	Ö
Display valu RESOLUTI	ie > ON =	70 % LOW	: Erro : Erro	r from t r from t	able above able above	+ ±	0.00 1 dig	5 %, git (inste	ead of 2 digits).	
The followir	ng appli	es to M	EASUI	REMEN	IT SEQUENC	E = UN	IPOLA	R		izatio
$f_{\text{LIN LINI}} = f_{\text{LIN}}$		0.04 %	+ U _{th} /]	[neter
whereby U ₄	implies	the the	rmoele	ctric e.r	n.f´s in the me	asurem	ent circ	uit and l	implies the	Parar
measuring c In practice 5	urrent th $0 \ \mu V \leq$	$rough U_{th} \le m$	the test V are to	unit. o be rec	koned with, d	ependin	g on the	e set-up	and the change in	
temperature.		• • • • • •								Iration
lemperatur	e coem	cient:			50 (11)					onfigu
10 ppm/K (o A value of \leq	10 ppm	μΩ me n/year c	an be e	ntered a	ge: 50 ppm/K) as a typical val). ue for tl	ne long-	-term sta	ability.	O
Error of the	e tempe	rature	measu	rement	channel (Pt1	00) with	iout a r	neasure	ment pick-up:	
	\leq	0.1	K	for	-30°C	\leq	Т	\leq	50°C,	ration
	< <	0.3 3	K K	for for	-50°C -200°C	< <	T T	< < <	100°C, 850°C,	Calibi
based on ITS	5 90 and	l DIN E	N 6075	51.						
Measureme	nt conn	ections								bu
4-wire techn	ology in	n Kelvi	n circui	t, floatii	ng circuit asse	mbly, po	otential	fixed w	ith respect to the	grammir
measuremen		or the	KE915	IOMAI						Pro
Max. compli	lance vo	litage:	at I _{meas} =	=	$\begin{array}{c} 100 \ \mu A \leq I_{m} \\ 10 \ A \end{array}$	$heas \leq 1 A$: 10 V, : 8 V,			
Max. voltage	e at the	open te	rminals	:<±	16 V.					aten lang
Max. permis	sible ov	vervolta	ge at m	easurer	nent input	: 100) V DC.			ch. Da d Anh
(voltage circ	uit)							Seite 7	- 1 - 4	Te

Туре 2304

Installation Operation Parameterization Configuration Calibration Programming Techn. Specifica-tions & Appendix

Measurement time:

Adjustable, Average value possible over \leq 255 values:

Display	Meaurement period for purely ohmic test unit with standard setting
3 1/2-digit	≤ 300 ms
4 1/2-digit	<u>≤</u> 600 ms
5 1/2-digit	≤ 5 s

Measurement type:

Repetition or single measurement, bipolar or unipolar.

Range selection:

Manual, automatic

Offset compensation:

per µP control upon request.

Display,:

240 x 64-dots, transflective graphic LCD with adjustable contrast and backglighting.

Overrange indication: >>>.

Indication of the measured value:

3 1/2, 4 1/2 and 5 1/2-digit, according to requirement; LCD 15 mm high; reading displayed: absolute, in %, or in other measurement units.

Voltage supply:

230 V + 6% - 10%; 115 V available as an option.

Line frequency: 45 - 65 Hz.

Power consumption: max. 260 VA.

Page 7 - 1 - 5

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Type 2304

Environ mental conditions:

Operation+5 <u>23</u> 40°C,	max. 90% relative humidity,
Storage 0 <u>23</u> 60°C.	non-condensing
Potential fixing:	measurement section internally grounded, switchable to external grounding. Digital section internally grounded.
Parameter entry:	Via keyboard or interface.
Weight:	28 kg.
Housing dimensions (HxLx	B): 255 x 520 x 480 (mm).
Device protection:	In accordance with VDE 0411.

Connections:

Test unit connection:

- At front, via 4 recessed safety laboratory sockets, 4 mm.
- At rear. via 5-pin LEMO socket EGG.2B.305.

Control signals:

The following signals are accessible via a 37-pin subminiature D socket on the rear panel:

-	Optocoupler output: ("Low-active", $\leq 27 \text{ V}, \leq 2 \text{ mA}$)	"Measurement in progress", "Measurement interrupted".
-	Optocoupler input: ("Low active", $\leq 40 \text{ V}$)	For printer "ON".
-	Foot switch input:	For Start/Stop (NO contact).
	9 relay changeover contacts for RGE0 RGE8:	r classify operations
	- max. voltage: - max. current:	42 V 0.5 A

Temperature compensation:

Measurement of the test unit's temperature via a Pt100 sensor which is connected via a 6-pin LEMO- socket EGG.1B.306.



Installation	Interfaces: - IEEE-488:
Operation	 - 24-pin, standard plug connection with open collector outputs: SH1, AH1, T6, TE0, L4, LE0, SR1, RL1, PP0, DC1, DT1, C0 - command language: SCPI, Version 1990.0. - RS232C:
Parameterization	 full duplex with RTS, CTS, 25-pin subminiature D-socket, baud rate 600 - 19 200, protocol ANSI X 3.28 subcategory 2.5, A3/A4, command language: SCPI, Version 1990.0. RS485: full duplex/half duplex without internal terminating resistances.
Configuration	 25-pin subminiature D-socket, baud rate 600-19200, protocol ANSI X 3.28 subcategory 2.5, A3/A4, command language: SCPI, Version 1990.0 Printer connection: Use of the RS232C output and the IBM character set in accordance with Appendix 7.5).
Calibration	
Programming	
Techn. Specifica- tions & Appendix	Page 7 - 1 -7



Installation

Operation

Parameterization

Configuration

Calibration

Programming

Specifica-Appendix

Techn tions {

Pin assignment

ATTENTION:

- Avoid the discharge of static electricity via the devices terminals.
 (particularly via the IEEE 488 connector!)
 It could destroy your measuring device.
- Observe the safety precautions: Before touching the devices' terminals and the leads connected to them, check whether any static charge needs to be removed.

Damage through electrostatic voltage is not covered by the guarantee!

In compliance with the relevant interference suppression regulations (VDE 0871B), all interface cables and plugs must be screened and grounded at both ends!

IEEE-488-Bus:

The 24-pin GPIB bus connector is standardized and has the pin assignment shown in Fig.7.1



Fig. 7.1: IEEE connector The connector has open collector outputs as shown in Fig. 7.2.



Installation



Serial interfaces

The RS232C/RS485 serial interfaces are accessible via a 25-pin subminiature D-connector, whose pin assignment is shown in Fig. 7.3.



High = A > B

Fig. 7.3: RS232C/RS485 connector

Terminating resistances are not present; they must be installed in the plug by the user, in accordance with the design (typical value: 150 Ω). Here, it should be ensured that the installation is performed on the transmission and reception sides:





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The inputs and outputs are optoelectronically decoupled. The electrical wiring of the outputs B) and C) is shown in Fig. 7.5, and that of the outputs E) and F) in Fig. 7.6.





Test unit connections

On the rear panel of the device, there is a second test-unit connection in parallel with the one on the front panel.

Its pin assignment is shown in Fig. 7.7



Fig.7.7: Test unit connections on rear panel (External view of socket)

Pt100 connections

The Pt100 connection is on the rear panel of the device. Its pin assignment is shown in Fig. 7.8.



Fig.7.8: Pt100 connections (External view of socket)





Type 2304

Error messages

	SMM25/Met-Smithenest	Error messages	Installation
ERR 0	:	Before measurement on load type Z is started, an overload or current error is already present.	Operation
ERR 1	-	Overload, range transgression, or U-cable rupture in the current path.	ation
I	:	Occurs superimposed with other messages: current error, current in transient phase, or I-cable rupture in the current path.	Parameteriza
MEAS	:	The measured value does not lie in the valid range; however, there is no overload.	Configuration
T>>	:	The temperature in the device is too high (the measurement is stopped, and the measuring current set to 0).	tion
VCOV	:	Overload of the amplifier channel C as shown in Fig. 1.5 (remedy: probably through zero compensation as described in Chap. 5.2.)	Calibra
When M an error	EAS.	MODE = CONT. and LOAD TYPE = R, the measurement continues if s (except for T>>).	Programming
When M stopped	EAS. when	MODE = CONT. and LOAD TYPE = Z, the measurement is normally ever an error occurs.	Specifica- k Appendix
		Page 7 - 3 -1	Techn tions &



Installation

Operation

5

Factory settings ("default parameters")

The following settings are valid for the cold start. After the *SEL* key is pressed (= access to the configuration and calibration menus) the settings listed below apply, with the exception of the calibration data and access monitoring entries which retain the current value. The device is calibrated and tested at the factory, i.e. it is delivered with calibration and control entries.

Measurement range: Range selection: Mesurement type: Measurement current: Load: Type of operation:	20 kΩ Manual Repetitior Large R Bipolar	1			Parameterizatio
Frequency: Resolution: Contrast: Beeper:	50 Hz Medium 54 Off With resol	lution: medium	high		Configuration
Average value: MEAS. TIME △ TIME BASE: Measurement pause: Display mode: Temperature compensation: Recording: Temperature: Co-efficient:	1 1 Ohm Off Manual 20 °C Nr. 5	1 5 1	5 9 1		Calibration
TC1: TC2: TC3: TC4: TC5: Individual measuring currents:	1600 (ppr 1700 2400 3100 3980 200 μΩ 10 A, 10 μ	n/K) A, 1 A, 100	TC6: TC7: TC8: TC9: TC10:) mA, 10 mA, 1 mA, 1	4030 4500 4800 6000 6500 20 kΩ mA, 100 uA	Programming
Comparator: Type: Bar display: Rel. limit: Abs.limit:	Off Comparation Off 100 $\Omega \pm 1$ correspond	tor I 0 % nds to rel. I	imit		m. Specifica- & Appendix



Installation

Printer character set

Operation	ion	izat	eter	ram	ц В	Ę	atic	igui	onf	<u> </u>	_	tion	ibra	Call		ರಾ
1 1 1 F	Ξ	±	≥	≤	ſ	J	÷	~	٥	•	•	1	η	2	8	SP
1 1 1 0 E	α	β	٦	п	Σ	σ	μ	τ	ф	Θ	Ω	δ	90	ÿ	3	n
1 1 0 1 D	II.	* *	T	L.	Ŀ	F	Æ	ŧ	÷	L	г		10	1	I	
1 1 0 0	L	Ŧ	т	ł		ł	F .	ŀ	5	ſ	Ŧ	T	ŀ	=	Å Å	7
1 0 1 1 8		XXXX	1988) 1999		4	*	ł	וו	7	-{	Ň	F.	Ţ.	Ľ.	اد ا	٦
1 0 1 0 A	á	i	6	ú	ñ	N	ġ	õ	ż	٣	- n	⅔	lý.	Ţ	«	»
1 0 1 9	Ê	æ	Æ	ô	ö	<u>ک</u>	û	ù	ÿ	Ö	Û	¢	£	¥	R	f
1 0 0 0	Ç	ü	é	â	ä	à	ક	¢	ê	ë	è	ï	î	i	Ä	A
0 1 1 1 7	р	q	r	S	t	u	v	¥	х	Y	z	J.				DEL
0 1 1 0 6		a	Ь	с	d	е	f	g	h	i	j	k	1	m	n	0
0 1 0 1 5	Р	Q	R	S	Т	U	v	W	X	Y	Z					
0 1 0 0		A	B	с	D	E	£	G	II	I	J	K	L	М	N	0
0 0 1 1 3	0	1	2	3	4	5	6	7	8	9	:	;	<	=	>	?
0 0 1 0 2	SP	!	11			%	&		()	*	÷	,		•	1
0 0 0 1		DC1	DC 2	DC 3	DC4	§			CAN			ESC	FS			
0 0 0 0	NUL			۷	*	•	*	BEL	BS	НТ	LF	۷T	FF	CR	so	SI
b0 b1 b2 b3 h1																
h2	0	1	2	3	4	5	6	7	8	9	A	В	С	D	E	F
b7	0	1	0	1	0	1	0	1	0	1	0	1	0	1	0	1
b6	0	0	1	1	0	0	1	1	0	0	1	1	0	0	1	1
b5	0	0	0	0	1	1	1	1	0	0	0	0	1	1	1	1
b4	0	0	0	0	0	0	0	0	1	1	1	1	1	1	1	1

national special character

Fig. 7.6: Character set2 (IBM)

R Programming



	Function keys - overview in alphabetical order	Installation
COMP F1	Selection of the menu for performing the scaling factor calibration (COMPensation).	Operation
COOL F2	Selection of the parameter assignment menu for recording a COOL ing curve.	erization
DISPMOD F3	Selection of the unit of measurement (DISP play MOD e)	Paramet
EVAL F5	Selection of the cooling curve protocol (EVALuation).	Configuration
• AUT	AUT omatic range selection, i.e. the device automatically selects the largest possible measurement range. (20 k Ω after power-on). When automatic range selection is active, the LED (light emitting diode) integrated in the button lights up.	Calibration
L-REM	Entry of the Load REM oval (= start of the internal stopwatch for the cooling curve); after this button is operated, the cooling curve F3 menu cannot be exited until the recording of the cooling curve is completed. With every access to the menu, the stopwatch is reset to zero.	Programming
PRINTER F4	Selection of the menu for parameterizing the PRINTER .	ın. Specifica- s & Appendix



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Type 2304

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HW-CONF F1	Selection of the menu for configurating the IEEE488 interface (HardWare CONF iguration) or the operating mode/format menu for serial interfaces. After this function key is operated, two different setting menus could appear, depending on the type of interface selected.	Installation
INDIV. F5	Selection of the menu for INDIV idual, range-dependent adjustment of the measuring current (0.1 mA 10 A), provided that the INDIV. option was also selected previously in the measuring current value list	Operation
kg F1	Unit key for completing the entry of a numerical value of mass in kg as the reference variable.	Parameterization
km F2 COEFF	Unit key for completing the entry of a numerical value of length in km as the reference variable. Selection of Table 3.17 with 10 preselectable temperature COEFF icients.	Configuration
F1 COMP F2	Selection of the menu for parameterizing the COMP arator functions (including the bar display switch).	Calibration
CONTROL F1	Selection of the table for access monitoring, i.e. CONTROL of the access to the configuration menu performed via. the ' SEL switch	Programming
F5	Reyboard operation. Page 7 - 6 -3	Techn. Specifica- tions & Appendix

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INTERF F3	Selection of the menu for parameterizing the INTERF ace.	Installation
STATCLA F4	Selection of the CLA ssification evaluation STAT istics (9 classifications and summations).	peration
STATCOM F3	Selection of the COM parator evaluation STAT istics (< = > and summations).	O uo
SW-CONF F2	Selection of the menu for setting the software parameters of the serial interfaces (S oft W are CONF iguration).	Parameterizati
TC F 1	Selection of the menu for parameterizing the T emperature C ompensation resp. for displaying the temperature of the test unit.	Configuration
	Cursor keys for selecting the parameter to be set, i.e. the line containing the parameter. The selected parameter is displayed in inverted form.	libration
	Cursor keys for scrolling through the value list belonging to the selected parameter. When the key is pressed, the next listed value appears; when the key is pressed, the preceding listed value appears.	ů D
μΩ kΩ	Unit keys for completing the entry of a numerical value of resistance in $\mu\Omega$ k Ω	Programminę
+ / - F2	Sign entry.	echn. Specifica- ons & Appendix
	Page 7-6-5	FF

Manual 2304/05

The manual for type 2304 you can also use for type 2305 The handling and the instruction codes via interface are the same.

The difference between 2304 and 2305 is as following:

	2304	2305
Range	200u Ω to 20k Ω	$2m\Omega$ to 20 k Ω
Resolution	up to $1n\Omega$	up to $0.1u\Omega$
Accuracy	0.01%	0.05%
Max. Current	10A	1A
Weight	28kg	24kg
Powerrequirement	260VA	60VA